

CS447: Natural Language Processing

<http://courses.engr.illinois.edu/cs447>

Lecture 5: Introduction to Classification for NLP

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Lecture 5, Part 1:
Review and
Overview

Review: Lecture 4

Language models define a probability distribution over all strings $\mathbf{w}=w^{(1)}\dots w^{(K)}$ in a language:

$$\sum_{\mathbf{w} \in L} P(\mathbf{w}) = 1$$

N-gram language models define the probability of a string $\mathbf{w}=w^{(1)}\dots w^{(K)}$ as the product of the probabilities of each word $w^{(i)}$, conditioned on the $n-1$ preceding words:

$$P_{n\text{-gram}}(w^{(1)} \dots w^{(K)}) = \prod_{i=1..K} P(w^{(i)} | w^{(i-1)}, \dots, w^{(i-n+1)})$$

$$\text{Unigram: } P_{\text{unigram}}(w^{(1)} \dots w^{(K)}) = \prod_{i=1..K} P(w^{(i)})$$

$$\text{Bigram: } P_{\text{bigram}}(w^{(1)} \dots w^{(K)}) = \prod_{i=1..K} P(w^{(i)} | w^{(i-1)})$$

$$\text{Trigram: } P_{\text{trigram}}(w^{(1)} \dots w^{(K)}) = \prod_{i=1..K} P(w^{(i)} | w^{(i-1)}, w^{(i-2)})$$

Lecture 4, Part 5:
Evaluating
Language Models

Intrinsic vs Extrinsic Evaluation

How do we know whether one language model is better than another?

There are two ways to evaluate models:

- **intrinsic evaluation** measures how well the model captures what it is supposed to capture (e.g. probabilities)
- **extrinsic (task-based) evaluation** measures how useful the model is in a particular task.

Both cases require an **evaluation metric** that allows us to measure and compare the performance of different models.



Intrinsic Evaluation of Language Models: Perplexity

Intrinsic evaluation

Define an **evaluation metric (scoring function)**.

We will want to measure how similar the predictions of the model are to real text.

Train the model on a **'seen' training set**

Perhaps: tune some parameters based on **held-out data** (disjoint from the training data, meant to emulate unseen data)

Test the model on an **unseen test set**

(usually from the same source (e.g. WSJ) as the training data)

Test data must be disjoint from training and held-out data

Compare models by their scores (more on this in the next lecture).

Perplexity

The perplexity of a language models is defined as the **inverse** ($\frac{1}{P(\dots)}$) of the **probability of the test set**, **normalized** ($\sqrt[N]{\dots}$) by the **# of tokens** (N) in the test set.

If a LM assigns probability $P(w_1, \dots, w_N)$ to a test corpus $w_1 \dots w_N$, the LM's perplexity, $PP(w_1 \dots w_N)$, is

$$PP(w_1 \dots w_N) = \sqrt[N]{\frac{1}{P(w_1 \dots w_N)}}$$

A LM with **lower perplexity is better** because it **assigns a higher probability to the unseen test corpus**.

LM₁ and LM₂'s perplexity can only be compared if they use the same vocabulary

- Trigram models have lower perplexity than bigram models;
- Bigram models have lower perplexity than unigram models, etc.

Practical issues: Use logarithms!

Since language model probabilities are very small, multiplying them together often yields to underflow.

It is often better to use **logarithms** instead, so replace

$$PP(w_1 \dots w_N) =_{def} \sqrt[N]{\prod_{i=1}^N \frac{1}{P(w_i | w_{i-1}, \dots, w_{i-n+1})}}$$

with

$$PP(w_1 \dots w_N) =_{def} \exp \left(-\frac{1}{N} \sum_{i=1}^N \log P(w_i | w_{i-1}, \dots, w_{i-n+1}) \right)$$

Extrinsic (Task-Based) Evaluation of LMs: Word Error Rate

Intrinsic vs. Extrinsic Evaluation

Perplexity tells us which LM assigns a higher probability to unseen text

This doesn't necessarily tell us which LM is better for our task (i.e. is better at scoring candidate sentences)

Task-based evaluation:

- Train model A, plug it into your system for performing task T
- Evaluate performance of system A *on task T*.
- Train model B, plug it in, evaluate system B on same task T.
- Compare scores of system A and system B on task T.

Word Error Rate (WER)

Originally developed for speech recognition.

How much does the *predicted* sequence of words differ from the *actual* sequence of words in the correct transcript?

$$\text{WER} = \frac{\text{Insertions} + \text{Deletions} + \text{Substitutions}}{\text{Actual words in transcript}}$$

Insertions: “eat lunch” → “eat **a** lunch”

Deletions: “see **a** movie” → “see movie”

Substitutions: “drink **ice** tea” → “drink **nice** tea”

Review: Lecture 4

How do we...

...**estimate the parameters** of a language model?

Relative frequency estimation (aka Maximum Likelihood estimation)

... **compute the probability of the first $n-1$ words?**

By padding the start of the sentence with $n-1$ BOS tokens

... **obtain *one* distribution over strings of *any* length?**

By adding an EOS token to the end of each sentence.

... **handle unknown words?**

By replacing rare words in training and unknown words with an UNK tokens

... **evaluate** language models?

Intrinsically with perplexity of test data, extrinsically e.g. with word error rate

Overview: Lecture 5

Part 1: Review and Overview

Part 2: What is classification?

Part 3: The Naive Bayes classifier

Part 4: Running&evaluating classification experiments

Reading:

Chapter 4, 3rd edition of Jurafsky and Martin

Today's questions

What is classification?

What is binary/multiclass/multilabel classification?

What is supervised learning?

And why do we want to learn classifiers
(instead of writing down some rules, say)?

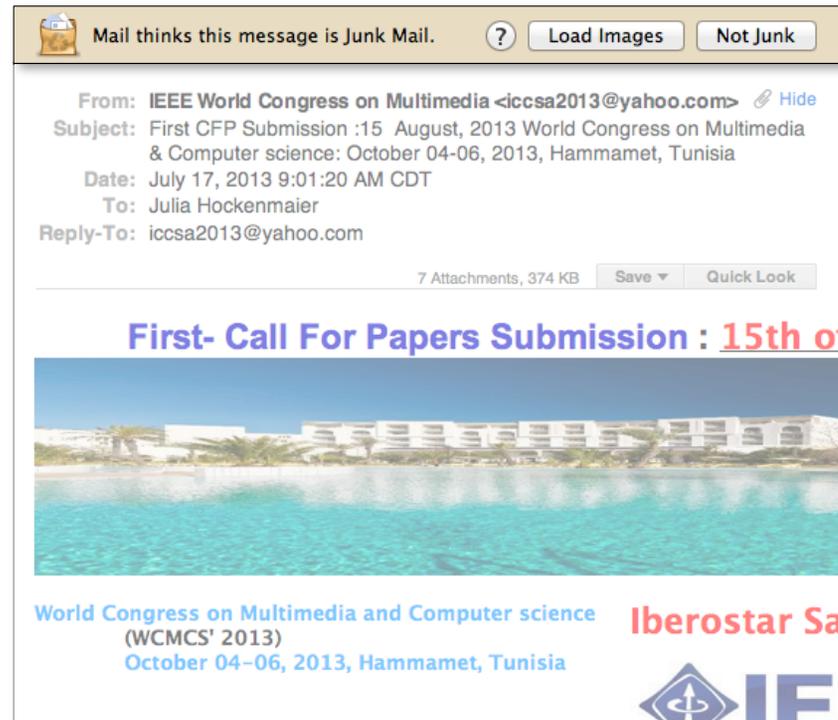
Feature engineering: from data to vectors

How is the Naive Bayes Classifier defined?

How do you evaluate a classifier?

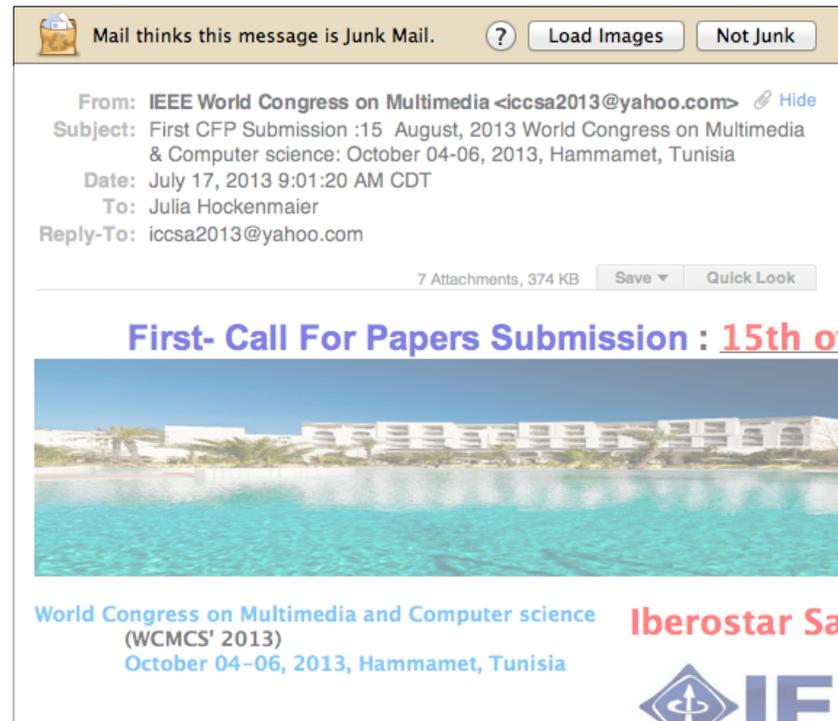
Lecture 5, Part 2:
What is
Classification?

Spam Detection



Spam detection is a **binary classification task**:
Assign **one of two labels** (e.g. {SPAM, NO SPAM})
to the input (here, an email message)

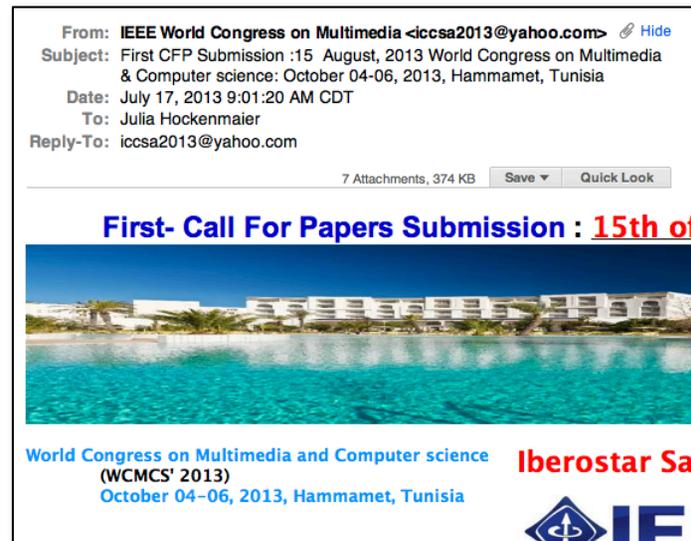
Spam Detection



A **classifier** is a **function** that maps inputs to a predefined (**finite**) set of class **labels**:

Spam Detector: Email \mapsto {SPAM, NOSPAM}

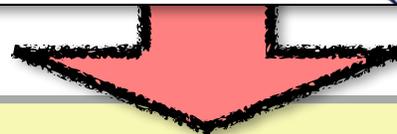
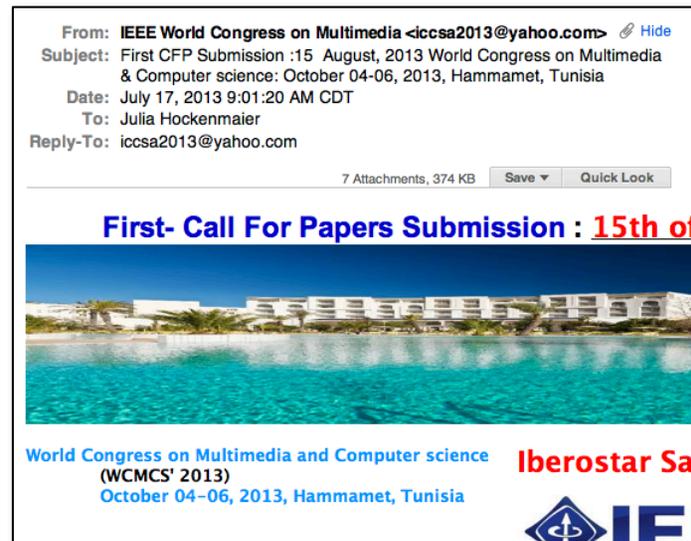
The importance of generalization



Mail thinks this message is junk mail.

We need to be able to **classify items**
our classifier **has never seen before.**

The importance of adaptation

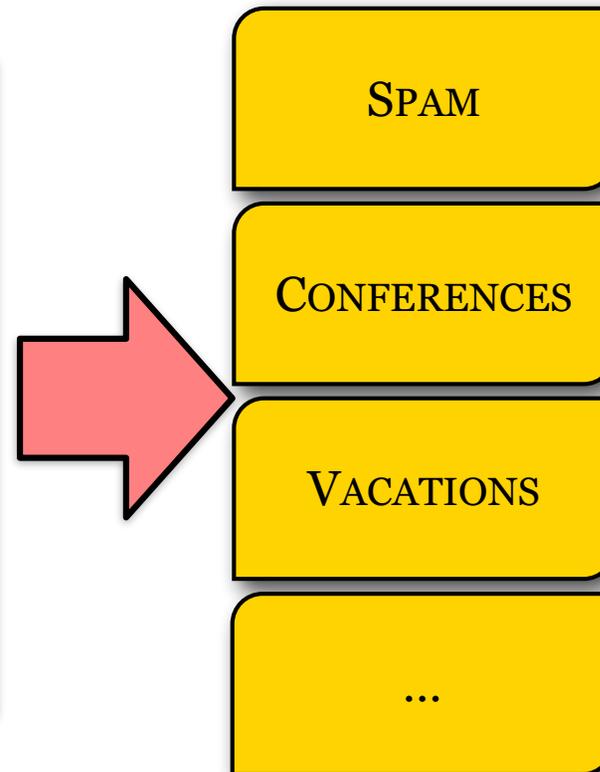


Mail thinks this message is junk mail.

Not junk

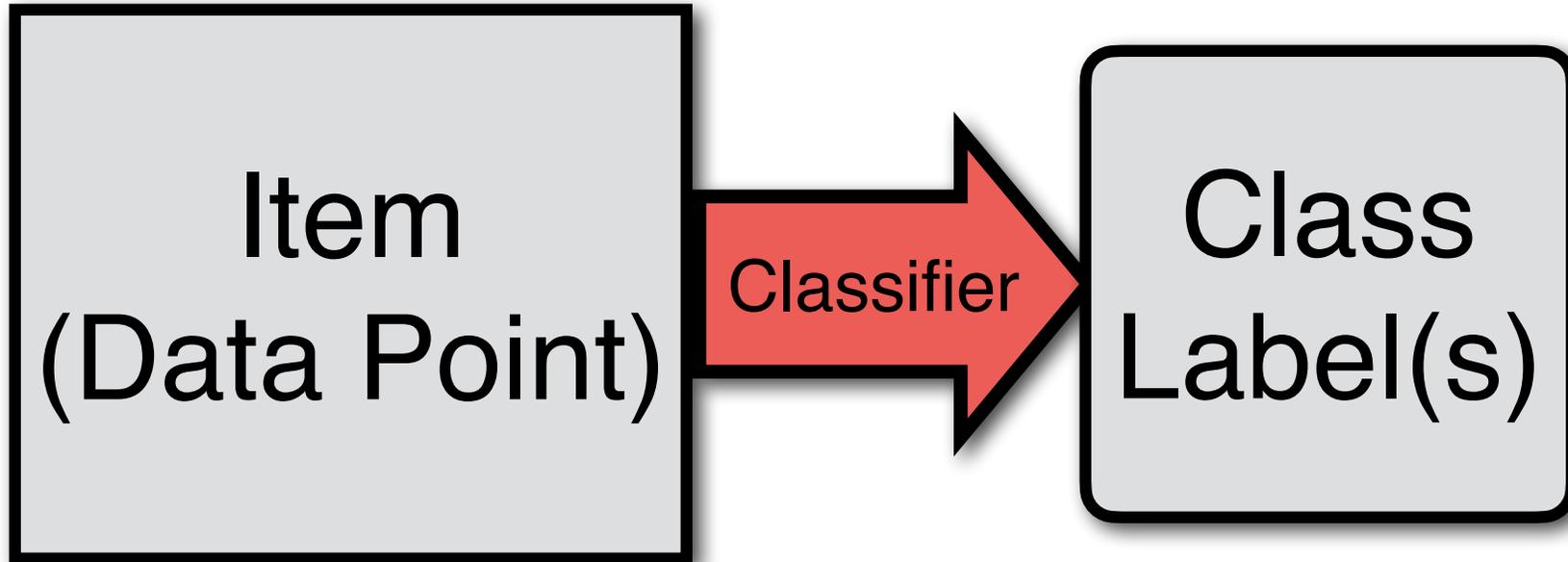
The classifier needs to **adapt/change** based on the **feedback (supervision)** it receives

Text classification more generally



This is a **multiclass** classification task:
Assign **one of K** labels to the input
{SPAM, CONFERENCES, VACATIONS,...}

Classification more generally

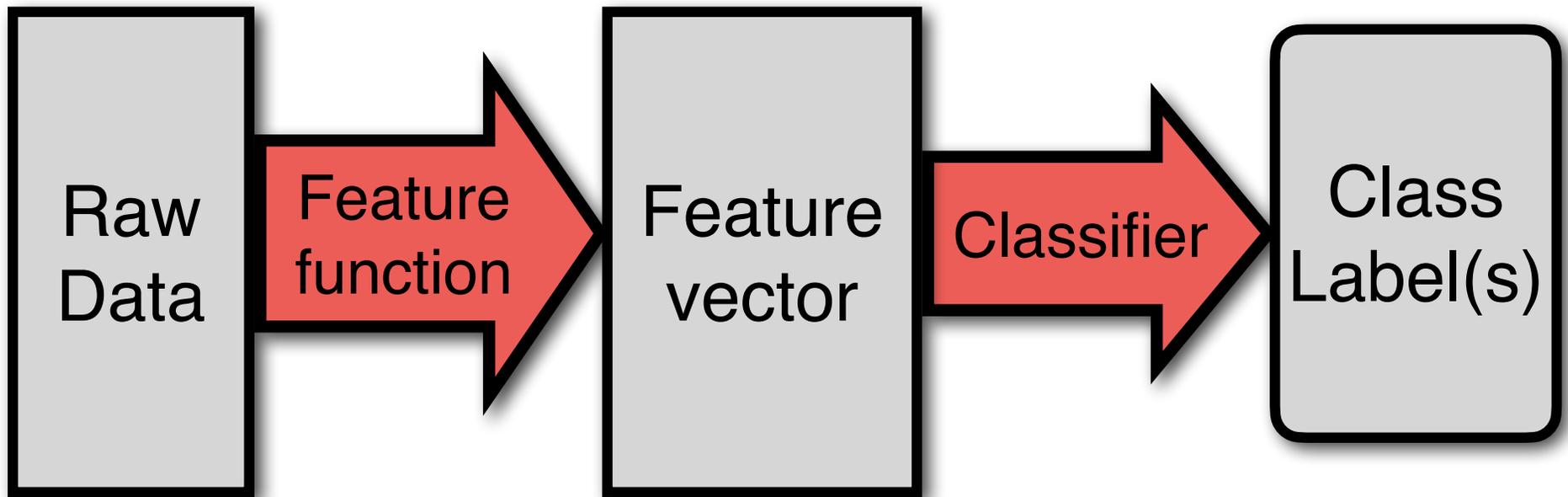


But: The data we want to classify could be *anything*:

Emails, words, sentences, images, image regions, sounds, database entries, sets of measurements,

We assume that *any* data point can be represented as a **vector**

Classification more generally



Before we can use a classifier on our data, we have to map the data to **“feature” vectors**

Feature engineering as a prerequisite for classification

To talk about classification mathematically, we assume each input item is represented as a **'feature' vector** $\mathbf{x} = (x_1 \dots x_N)$

- Each element in \mathbf{x} is one **feature**.
- The **number of elements/features N is fixed**, and may be very large.
- \mathbf{x} has to capture **all the information** about the item that the classifier needs.

But the raw data points (e.g. documents to classify) are typically not in vector form.

Before we can train a classifier, we therefore have to first define a suitable **feature function** that maps raw data points to vectors.

In practice, **feature engineering** (designing suitable feature functions) is very important for accurate classification.



From texts to vectors

In NLP, input items are documents, sentences, words,
⇒ How do we represent these items as vectors?

Bag-of-Words representation: (this ignores word order)

Assume that each element x_i in $(x_1 \dots x_N)$ corresponds to one word type (v_i) in the vocabulary $V = \{v_1, \dots, v_N\}$

There are many different ways to represent a piece of text as a vector over the vocabulary, e.g.:

- If $x_i \in \{0,1\}$: Does word v_i occur (yes: $x_i = 1$, no: $x_i = 0$) in the input document?
- If $x_i \in \{0, 1, 2, \dots\}$: How often does word v_i occur in the input document?

Now, back to classification....:

A **classifier** is a function $f(\mathbf{x})$ that maps input items $\mathbf{x} \in X$ to class labels $y \in Y$
(X is a vector space, Y is a finite set)

Binary classification:

Each input item is mapped to exactly one of 2 classes

Multi-class classification:

Each input item is mapped to exactly one of K classes ($K > 2$)

Multi-label classification:

Each input item is mapped to N of K classes

($N \geq 1$, varies per input item)

Classification as supervised machine learning

Classification tasks: Map inputs to a fixed set of class labels

Underlying assumption: Each input *really* has one (or N) correct labels

Corollary: The **correct mapping** is a function (aka the ‘**target function**’)

How do we **obtain a classifier (model)** for a given task?

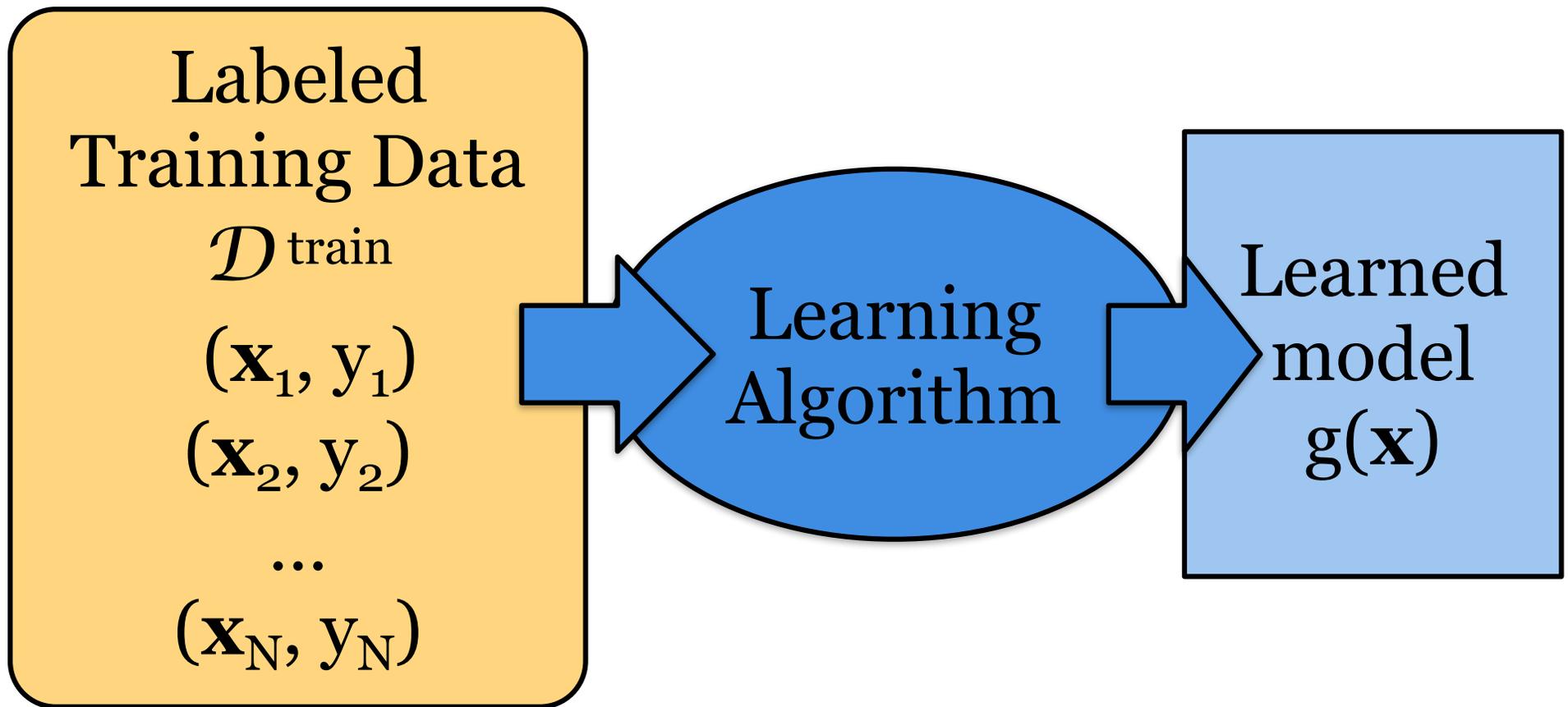
- If the target function is very simple (and known), implement it directly
- Otherwise, if we have enough **correctly labeled data**,
estimate (aka. **learn/train**) a classifier based on that labeled data.

Supervised machine learning:

Given (correctly) **labeled training data**, obtain a classifier that predicts these labels as accurately as possible.

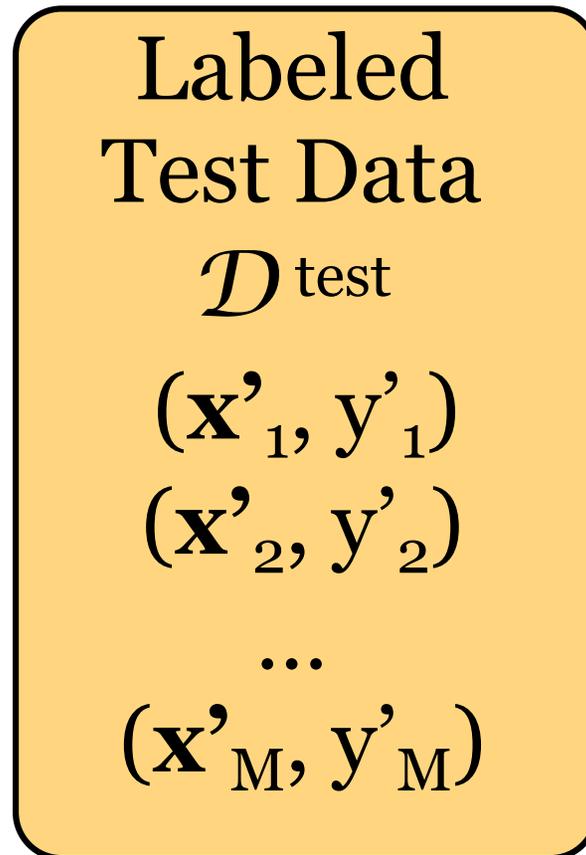
Learning is supervised because the learning algorithm can get **feedback** about how accurate its predictions are **from the labels in the training data**.

Supervised learning: Training



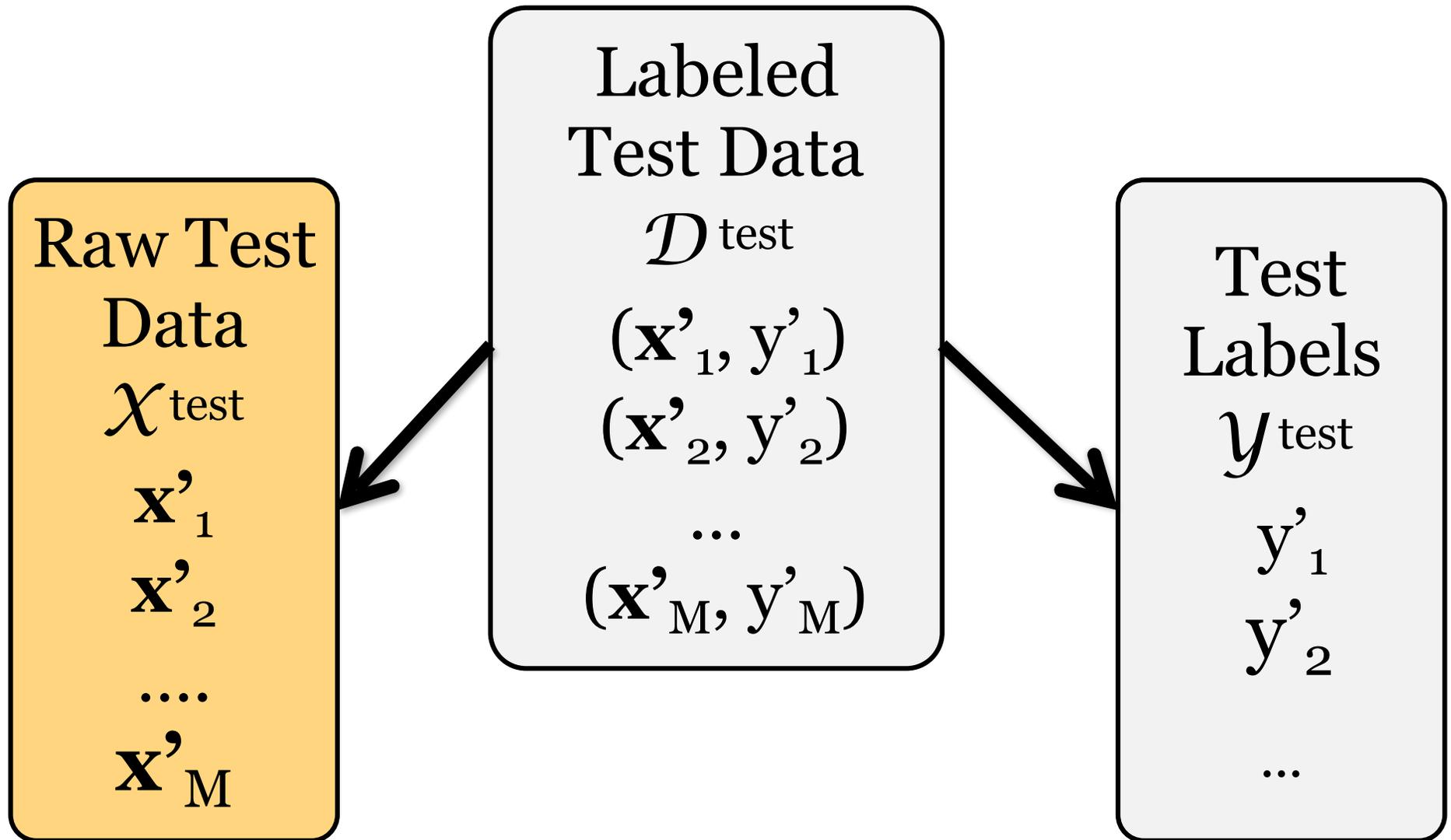
Give the learning algorithm examples in $\mathcal{D}^{\text{train}}$
The learning algorithm returns a model $g(\mathbf{x})$

Supervised learning: **Testing**



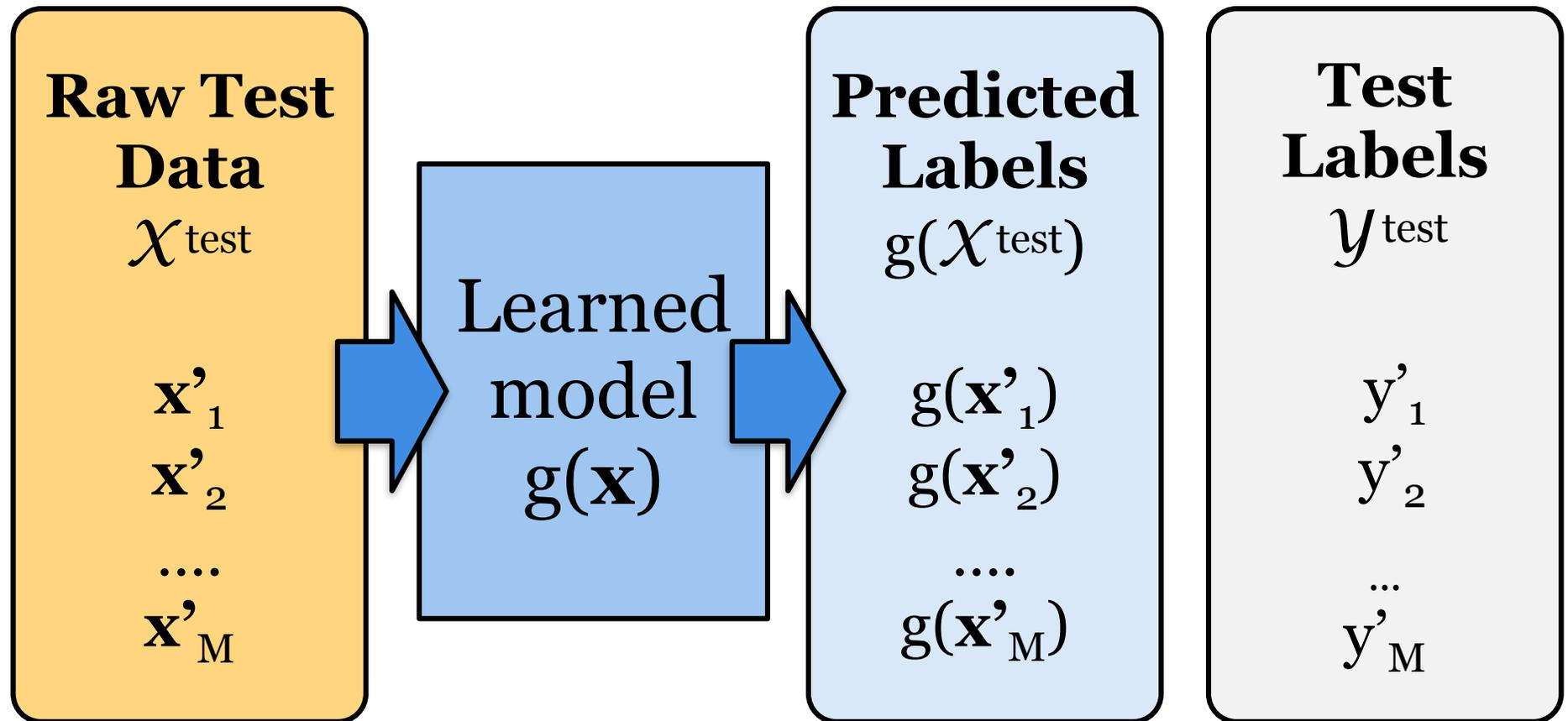
Reserve some labeled data for testing

Supervised learning: **Testing**



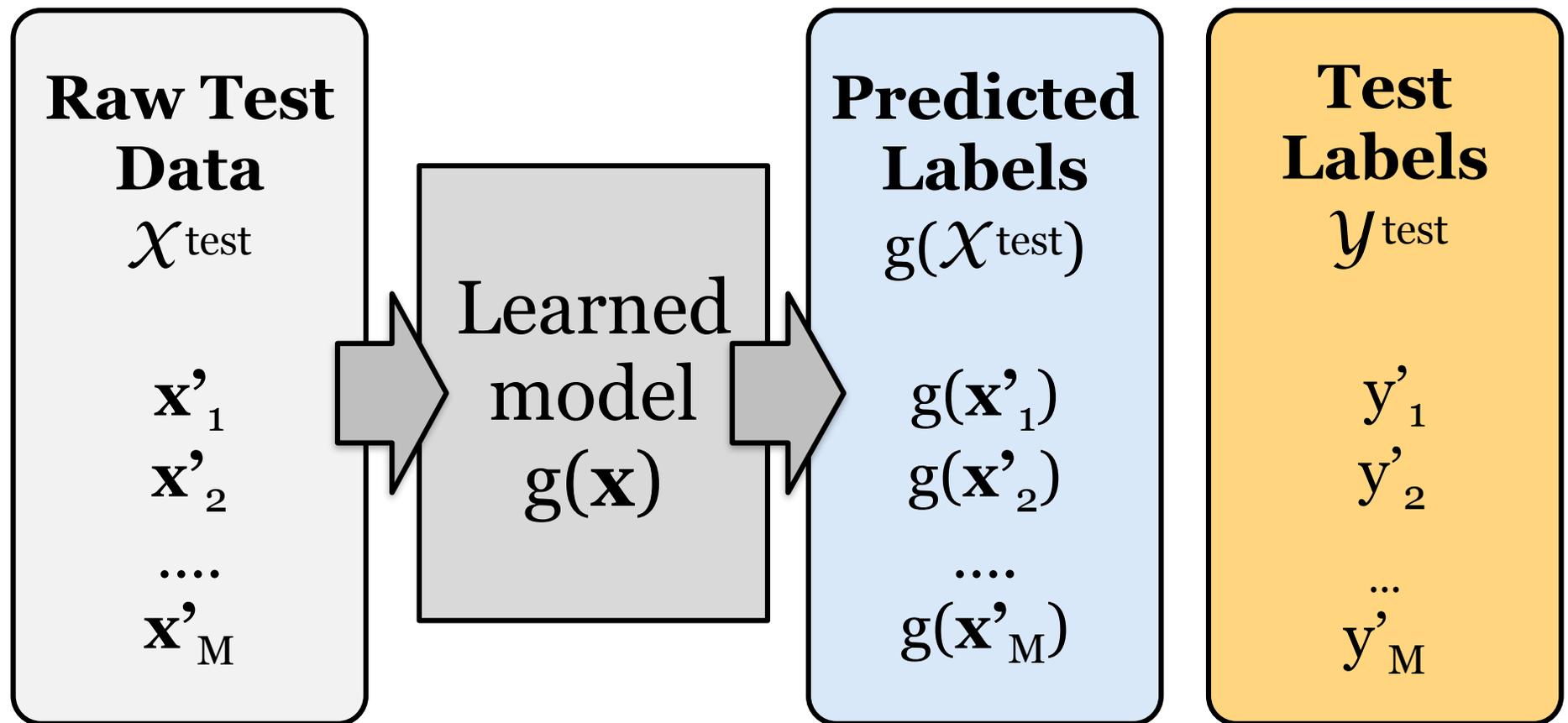
Supervised learning: **Testing**

Apply the learned model to the raw test data to obtain **predicted labels** for the test data



Supervised learning: **Testing**

Evaluate the learned model by comparing the predicted labels against the (correct) test labels



Supervised machine learning

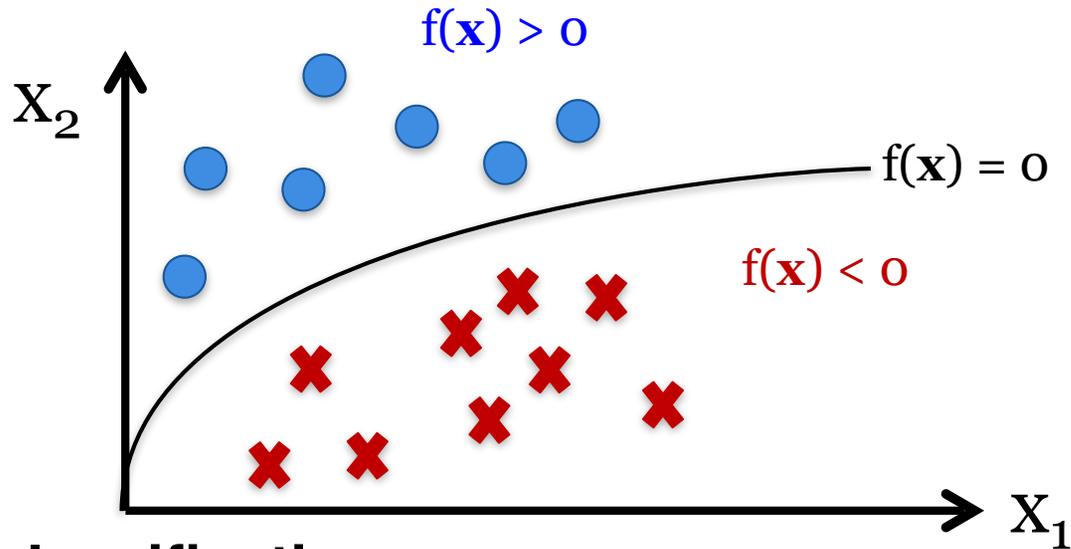
The supervised learning task (for classification):

Given (correctly) labeled data $D = \{(\mathbf{x}_i, y_i)\}$,
where each item \mathbf{x}_i is a vector $(x_1 \dots x_N)$ with label y_i
(which we assume is given by the target function $f(\mathbf{x}_i) = y_i$),
return a classifier $g(\mathbf{x}_i)$ that predicts these labels as accurately
as possible (i.e. such that $g(\mathbf{x}_i) = y_i = f(\mathbf{x}_i)$)

To make this more concrete, we need to specify:

- what *class of functions* $g(\mathbf{x}_i)$ to consider
(many classifiers assume $g(\mathbf{x}_i)$ is a *linear function*)
- what *learning algorithm* we will use to learn $g(\mathbf{x}_i)$
(many learning algorithms assume a particular class of functions)

Classifiers in vector spaces



Binary classification:

Learn a function f that best *separates* the positive and negative examples:

- Assign $y = 1$ to all \mathbf{x} where $f(\mathbf{x}) > 0$
- Assign $y = 0$ to all \mathbf{x} where $f(\mathbf{x}) < 0$

Linear classifier: $f(\mathbf{x}) = \mathbf{w}\mathbf{x} + b$ is a **linear** function of \mathbf{x}

Lecture 05, Part 3:
The Naive Bayes
Classifier

Probabilistic classifiers

We want to find the *most likely class* y for the input \mathbf{x} :

$$y^* = \operatorname{argmax}_y P(Y = y | \mathbf{X} = \mathbf{x})$$

$P(Y = y | \mathbf{X} = \mathbf{x})$:

The probability that the class label is y when the input feature vector is \mathbf{x}

$$y^* = \operatorname{argmax}_y f(y)$$

Let y^* be the y that maximizes $f(y)$

Modeling $P(Y | X)$ with Bayes Rule

Bayes Rule relates $P(Y | X)$ to $P(X | Y)$ and $P(Y)$:

$$\begin{aligned} P(Y | X) &= \frac{P(Y, X)}{P(X)} \\ &= \frac{P(X | Y)P(Y)}{P(X)} \\ &\propto \overset{\text{Likelihood}}{P(X | Y)} \overset{\text{Prior}}{P(Y)} \end{aligned}$$

Posterior

Bayes rule: The **posterior** $P(Y | X)$ is proportional to the **prior** $P(Y)$ times the **likelihood** $P(X | Y)$

Using Bayes Rule for our classifier

$$y^* = \operatorname{argmax}_y P(Y | \mathbf{X})$$

$$= \operatorname{argmax}_y \frac{P(\mathbf{X} | Y)P(Y)}{P(\mathbf{X})}$$

$$= \operatorname{argmax}_y P(\mathbf{X} | Y)P(Y)$$

[Bayes Rule]

[$P(\mathbf{X})$ doesn't
change argmax_y]

Modeling $P(Y = y)$

$P(Y = y)$ is the “prior” class probability

We can estimate this as the **fraction of documents** in the training data **that have class y** :

$$\hat{P}(Y = y) = \frac{\text{\#documents } \langle \mathbf{x}_i, y_i \rangle \in D_{train} \text{ with } y_i = y}{\text{\#documents } \langle \mathbf{x}_i, y_i \rangle \in D_{train}}$$

Modeling $P(\mathbf{X} = \mathbf{x} \mid Y = y)$

$P(\mathbf{X} = \mathbf{x} \mid Y = y)$ is the “likelihood” of the input \mathbf{x}

$\mathbf{x} = \langle x_1, \dots, x_n \rangle$ is a vector

Each x_i represents a word (type) in our vocabulary

Let’s make a (naive) **independence assumption**:

$$P(\mathbf{X} = \langle x_1, \dots, x_n \rangle \mid Y = y) := \prod_{i=1..n} P(X_i = x_i \mid Y = y)$$

With this independence assumption, we now need to define (and multiply together) all $P(X_i = x_i \mid Y = y)$

The Naive Bayes Classifier

Assign class y^* to input $\mathbf{x} = (x_1 \dots x_n)$ if

$$y^* = \operatorname{argmax}_y P(Y = y) \prod_{i=1..n} P(X_i = x_i | Y = y)$$

$P(Y = y)$ is the **prior class probability**
(estimated as the fraction of items in the training data
with class y)

$P(X_i = x_i | Y = y)$ is the (class-conditional)
likelihood of the feature x_i conditioned on the class y .
There are different ways to model this probability.

$P(X_i = x_i | Y = y)$ as Bernoulli

Capture **whether a word occurs** in a document or not:

$P(X_i = x_i | Y = y)$ is a **Bernoulli** distribution ($x_i \in \{0,1\}$)

$P(X_i = 1 | Y = y)$: probability that **word v_i occurs**
in a document of class y .

$P(X_i = 0 | Y = y)$: probability that **word v_i does not occur**
in a document of class y

Estimation:

Compute the fraction of documents of class y with/without x_i :

$$\hat{P}(X_i = 1 | Y = y) = \frac{\#\text{docs } \langle \mathbf{x}_i, y_i \rangle \in D_{train} \text{ with } y_i = y \text{ in which } x_i \text{ occurs}}{\#\text{docs } \langle \mathbf{x}_i, y_i \rangle \in D_{train} \text{ with } y_i = y}$$

$$\hat{P}(X_i = 0 | Y = y) = \frac{\#\text{docs } \langle \mathbf{x}_i, y_i \rangle \in D_{train} \text{ with } y_i = y \text{ in which } x_i \text{ does not occur}}{\#\text{docs } \langle \mathbf{x}_i, y_i \rangle \in D_{train} \text{ with } y_i = y}$$

$P(\mathbf{X} | Y = y)$ as a Multinomial

What if we want to capture **how often** a word appears in a document?

Let's represent each document as a vector of **word frequencies** $x_i = C(v_i)$:

Vocabulary $V = \{ \text{apple, banana, coffee, drink, eat, fish} \}$

A document: *“fish fish eat eat fish”*

Vector representation of this document: $\mathbf{x} = \langle 0, 0, 0, 0, 2, 3 \rangle$

$P(X_i = x_i | Y = y)$: probability that word v_i occurs with frequency $x_i = C(v_i)$ in a document of class y .

We can model this by treating $P(\mathbf{X} | Y)$ as a **Multinomial distribution**

Multinomial Distribution: Rolling Dice

Before we look at language, let's assume we're **rolling dice**, where the **probability of getting any one side** (e.g. a 4) when rolling the die once is **equal** to that of any other side (e.g. a 6).

A **multinomial** computes the probability of, say, getting two 5s and three 6s if you roll a die five times:

$$P(\langle 0,0,0,0,2,3 \rangle) = \frac{5!}{0!0!0!0!2!3!} (1/6)^2 (1/6)^3$$

#of sequences of three 6s and two 5s: $5!/(0!0!0!0!2!3!)$

Prob. of getting a 5 (or a 6) when you roll a die once = $1/6$

#Occurrences of 5 and 3: 2 and 3

Prob. of any one sequence of three 6s and two 5s: $(1/6)^2(1/6)^3$

NB: Note that we can ignore the probabilities of any sides (i.e. 1, 2, 3, 4) that didn't come up in our trial (unlike in the Bernoulli model)

$P(\mathbf{X}_i = \mathbf{x}_i | Y = y)$ as Multinomial

We want to know $P(\mathbf{X} = \langle 0,0,0,0,2,3 \rangle | Y = y)$
where $\langle 0,0,0,0,2,3 \rangle = \langle C(\text{apple}), \dots, C(\text{eat}), C(\text{fish}) \rangle$

Unlike the sides of a dice, words **don't have uniform probability**
(cf. Zipf's Law)

So we need to **estimate the class-conditional unigram probability** $P(\text{apple} | Y = y)$ **of each word** $v_i \{\text{apple}, \dots, \text{fish}\}$
in documents of class y ...

... **and multiply that probability** x_i **times**

(x_i = frequency of v_i in our document):

$$P(\langle 0,0,0,0,2,3 \rangle | Y = y) = P(\text{eat} | Y = y)^2 P(\text{fish} | Y = y)^3$$

Or more generally: $P(\mathbf{X} = \mathbf{x} | Y = y) = \prod P(v_i | Y = y)^{x_i}$

Unigram probabilities $P(v_i | Y = y)$

We can estimate the **unigram probability** $P(v_i | Y = y)$ of word v_i in all documents of class y as

$$\hat{P}(v_i | Y = y) = \frac{\#v_i \text{ in all docs } \in D_{\text{train}} \text{ of class } y}{\#\text{words in all docs } \in D_{\text{train}} \text{ of class } y}$$

or **with add-one smoothing**
(with N words in vocab V):

$$\hat{P}(v_i | Y = y) = \frac{(\#v_i \text{ in all docs } \in D_{\text{train}} \text{ of class } y) + 1}{(\#\text{words in all docs } \in D_{\text{train}} \text{ of class } y) + N}$$

Lecture 04, Part 4:
Running and Evaluating
Classification
Experiments

Evaluating Classifiers

Evaluation setup:

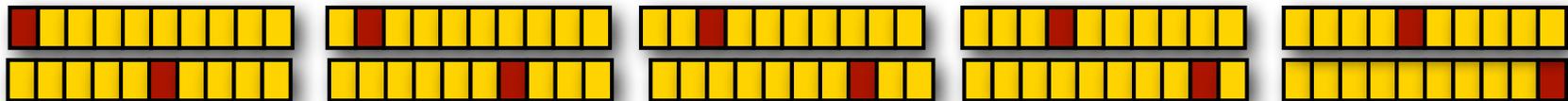
Split data into separate **training**, (**development**) and **test** sets.



Better setup: **n-fold cross validation**:

Split data into n sets of equal size

Run n experiments, using set i to test and remainder to train



This gives average, maximal and minimal accuracies

When **comparing two classifiers**:

Use the **same** test and training data with the same classes

Evaluation Metrics

Accuracy: What fraction of items in the test data were classified correctly?

It's easy to get high accuracy if one class is very common (just label everything as that class)

But that would be a pretty useless classifier

Precision and recall

Precision and recall were originally developed as evaluation metrics for information retrieval:

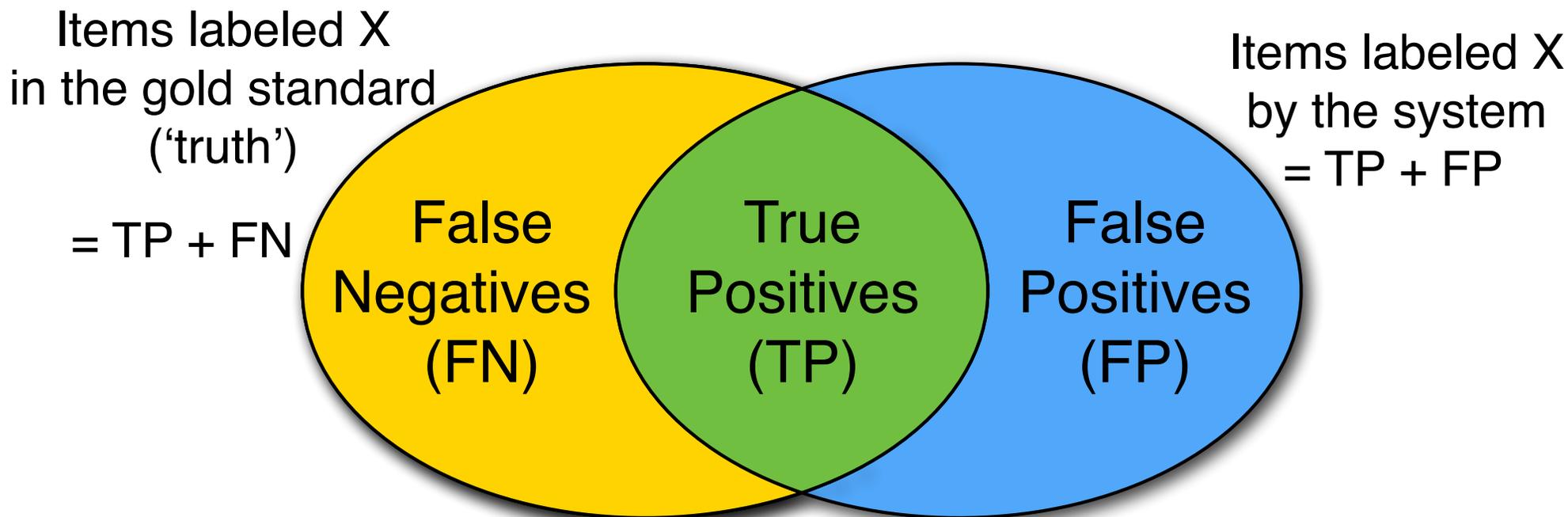
- **Precision**: What percentage of retrieved documents are relevant to the query?
- **Recall**: What percentage of relevant documents were retrieved?

In NLP, they are often used in addition to accuracy:

- **Precision**: What percentage of items that were assigned label X do actually have label X in the test data?
- **Recall**: What percentage of items that have label X in the test data were assigned label X by the system?

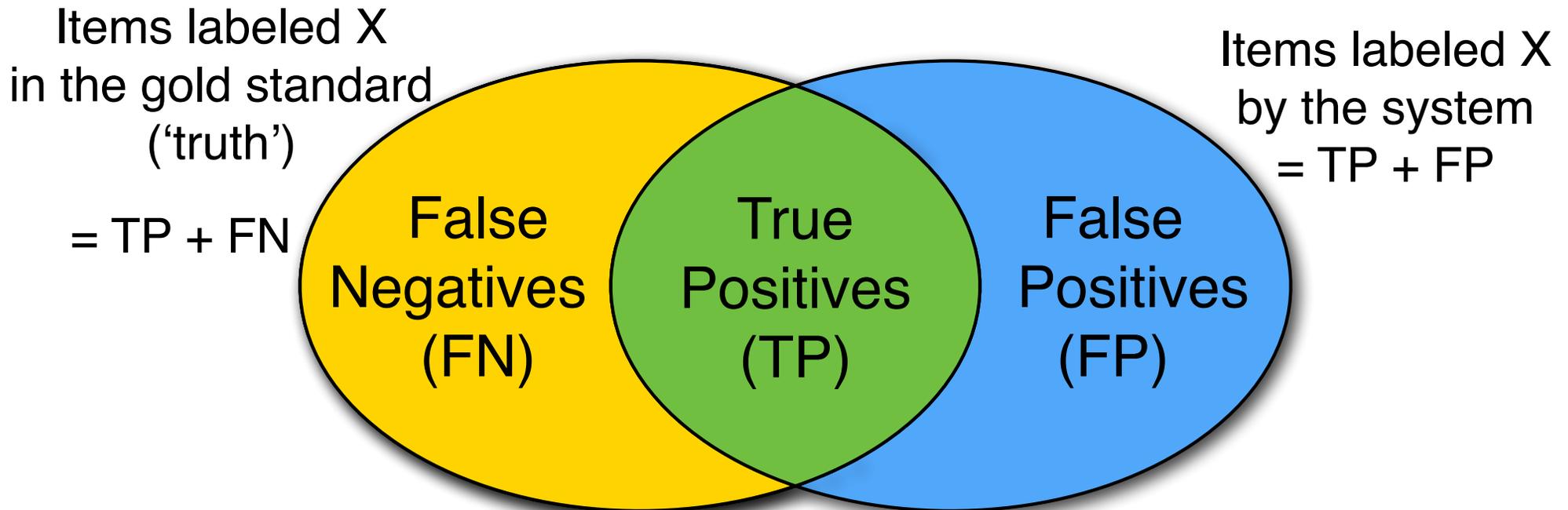
Precision and Recall are particularly useful when there are more than two labels.

True vs. false positives, false negatives



- **True positives:** Items that were labeled X by the system, and should be labeled X.
- **False positives:** Items that were labeled X by the system, but should *not* be labeled X.
- **False negatives:** Items that were *not* labeled X by the system, but should be labeled X,

Precision, Recall, F-Measure



Precision: $P = \frac{TP}{TP + FP}$

Recall: $R = \frac{TP}{TP + FN}$

F-measure: harmonic mean of precision and recall

$$F = \frac{2 \cdot P \cdot R}{P + R}$$

Confusion Matrices

A confusion matrix tabulates how many items that are labeled with class y in the gold data are labeled with class y' by the classifier.

		<i>gold labels</i>		
		urgent	normal	spam
<i>system output</i>	urgent	8	10	1
	normal	5	60	50
	spam	3	30	200

Confusion Matrices

This can be useful for understanding what kinds of mistakes a (multi-class) classifier makes

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Only 8/16 'urgent' messages are classified correctly.

Confusion Matrices

This can be useful for understanding what kinds of mistakes a (multi-class) classifier makes

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Only 8/16 'urgent' messages are classified correctly.

But 200/251 'spam' messages are classified correctly.

Confusion Matrices

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	normal	5	60	50
	spam	3	30	200

Only 8/16 'urgent' messages are classified correctly.

But 200/251 'spam' messages are classified correctly.

And only 8/19 messages labeled 'urgent' are actually urgent

Reading off Precision and Recall

		<i>gold labels</i>			
		urgent	normal	spam	
<i>system output</i>	urgent	8	10	1	precision_u = $\frac{8}{8+10+1}$
	normal	5	60	50	precision_n = $\frac{60}{5+60+50}$
	spam	3	30	200	precision_s = $\frac{200}{3+30+200}$
		recall_u = $\frac{8}{8+5+3}$	recall_n = $\frac{60}{10+60+30}$	recall_s = $\frac{200}{1+50+200}$	

Reading off Precision and Recall

Class 1: Urgent

	true urgent	true not
system urgent	8	11
system not	8	340

$$\text{precision} = \frac{8}{8+11} = .42$$

Class 2: Normal

	true normal	true not
system normal	60	55
system not	40	212

$$\text{precision} = \frac{60}{60+55} = .52$$

Class 3: Spam

	true spam	true not
system spam	200	33
system not	51	83

$$\text{precision} = \frac{200}{200+33} = .86$$

Macro-average vs Micro-average

How do we aggregate precision and recall across classes?

Class 1: Urgent

	true urgent	true not
system urgent	8	11
system not	8	340

$$\text{precision} = \frac{8}{8+11} = .42$$

Class 2: Normal

	true normal	true not
system normal	60	55
system not	40	212

$$\text{precision} = \frac{60}{60+55} = .52$$

Class 3: Spam

	true spam	true not
system spam	200	33
system not	51	83

$$\text{precision} = \frac{200}{200+33} = .86$$

$$\text{macroaverage precision} = \frac{.42+.52+.86}{3} = .60$$

Macro-average: average the precision over all K classes (regardless of how common each class is)

Macro-average vs Micro-average

How do we aggregate precision and recall across classes?

	Class 1: Urgent		Class 2: Normal		Class 3: Spam	
	true urgent	true not	true normal	true not	true spam	true not
system urgent	8	11	60	55	200	33
system not	8	340	40	212	51	83

	Pooled	
	true yes	true no
system yes	268	99
system no	99	635

microaverage precision = $\frac{268}{268+99} = .73$

Micro-average: average the precision **over all N items**
(regardless of what class they have)

Macro-average vs. Micro-average

Which average should you report?

Macro-average (average P/R of all classes):

Useful if performance on all *classes* is equally important.

Micro-average (average P/R of all items):

Useful if performance on all *items* is equally important.

THE END