Programming Languages and Compilers (CS 421)

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Based in part on slides by Mattox Beckman, as updated by Vikram Adve and Gul Agha

Data types play a key role in:

- Data abstraction in the design of programs
- Type checking in the analysis of programs
- Compile-time code generation in the translation and execution of programs
 - Data layout (how many words; which are data and which are pointers) dictated by type

Terminology

- Type: A type t defines a set of possible data values
 - E.g. short in C is $\{x \mid 2^{15} 1 \ge x \ge -2^{15}\}$
 - A value in this set is said to have type t
- Type system: rules of a language assigning types to expressions

Types as Specifications

- Types describe properties
- Different type systems describe different properties, eg
 - Data is read-write versus read-only
 - Operation has authority to access data
 - Data came from "right" source
 - Operation might or could not raise an exception
- Common type systems focus on types describing same data layout and access methods

Sound Type System

- If an expression is assigned type *t*, and it evaluates to a value *v*, then *v* is in the set of values defined by *t*
- SML, OCAML, Scheme and Ada have sound type systems
- Most implementations of C and C++ do not

Strongly Typed Language

When no application of an operator to arguments can lead to a run-time type error, language is *strongly typed*

Depends on definition of "type error"

Strongly Typed Language

C++ claimed to be "strongly typed", but

- Union types allow creating a value at one type and using it at another
- Type coercions may cause unexpected (undesirable) effects
- No array bounds check (in fact, no runtime checks at all)
- SML, OCAML "strongly typed" but still must do dynamic array bounds checks, runtime type case analysis, and other checks

Static vs Dynamic Types

- Static type: type assigned to an expression at compile time
- *Dynamic type*: type assigned to a storage location at run time
- Statically typed language: static type assigned to every expression at compile time
- *Dynamically typed language*: type of an expression determined at run time

Type Checking

When is op(arg1,...,argn) allowed?

- Type checking assures that operations are applied to the right number of arguments of the right types
 - Right type may mean same type as was specified, or may mean that there is a predefined implicit coercion that will be applied

Used to resolve overloaded operations

Type Checking

- Type checking may be done statically at compile time or dynamically at run time
- Dynamically typed (aka untyped) languages (eg LISP, Prolog) do only dynamic type checking
- Statically typed languages can do most type checking statically

Dynamic Type Checking

- Performed at run-time before each operation is applied
- Types of variables and operations left unspecified until run-time
 - Same variable may be used at different types

Dynamic Type Checking

- Data object must contain type information
- Errors aren't detected until violating application is executed (maybe years after the code was written)

Static Type Checking

- Performed after parsing, before code generation
- Type of every variable and signature of every operator must be known at compile time

Static Type Checking

- Can eliminate need to store type information in data object if no dynamic type checking is needed
- Catches many programming errors at earliest point
- Can't check types that depend on dynamically computed values
 - Eg: array bounds

Static Type Checking

- Typically places restrictions on languages
 - Garbage collection
 - References instead of pointers
 - All variables initialized when created
 - Variable only used at one type
 - Union types allow for work-arounds, but effectively introduce dynamic type checks

Type Inference

Type derivation : A formal proof that a term has a type,

- assuming types for variables
- using the rules of a type system

Type checking : A program to analyze code

- Confirms terms in the code have needed types according to the type system
- Assures type derivations exist

Type Declarations

- Type declarations: explicit assignment of types to variables (signatures to functions) in the code of a program
 - Must be checked in a strongly typed language
 - Often not necessary for strong typing or even static typing (depends on the type system)

Type Inference

- Type inference: A program analysis to assign a type to an expression from the program context of the expression
 - Fully static type inference first introduced by Robin Miller in ML
 - Haskle, OCAML, SML all use type inference
 Records are a problem for type inference

Format of Type Judgments

- A *type judgement* has the form
 Γ exp : τ
- Γ is a typing environment
 - Supplies the types of variables (and function names when function names are not variables)
 - Γ is a set of the form $\{x:\sigma,\ldots\}$
 - For any x at most one σ such that $(x : \sigma \in \Gamma)$
- exp is a program expression
- τ is a type to be assigned to exp
- pronounced "turnstyle", or "entails" (or "satisfies" or, informally, "shows")
 2/22/23



 $\Gamma \mid -n$: int (assuming *n* is an integer constant)

 Γ |- true : bool Γ |- false : bool

These rules are true with any typing environment

Γ, *n* are meta-variables

Axioms – Variables (Monomorphic Rule)

Notation: Let $\Gamma(x) = \sigma$ if $x : \sigma \in \Gamma$ Note: if such σ exits, its unique

Variable axiom:

$$\overline{\Gamma \mid -x:\sigma} \quad \text{if } \Gamma(x) = \sigma$$

Simple Rules – Arithmetic (Mono)

Primitive Binary operators $(\oplus \in \{+, -, *, ...\})$: $\Gamma \mid -\boldsymbol{e}_1:\boldsymbol{\tau}_1 \quad \Gamma \mid -\boldsymbol{e}_2:\boldsymbol{\tau}_2 \quad (\oplus):\boldsymbol{\tau}_1 \to \boldsymbol{\tau}_2 \to \boldsymbol{\tau}_3$ $\Gamma \mid - e_1 \oplus e_2 : \tau_3$ Special case: Relations ($\sim_{\in} \{ <, >, =, <=, >= \}$): $\Gamma \mid -e_1 : \tau \quad \Gamma \mid -e_2 : \tau \quad (\sim): \tau \to \tau \to bool$ $\Gamma \mid -e_1 \sim e_2$:bool

For the moment, think τ is int

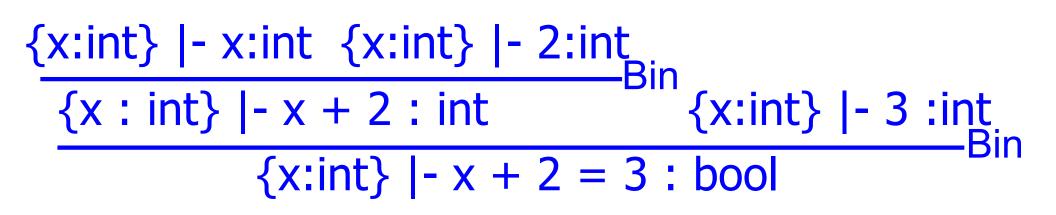
What do we need to show first?

$\{x:int\} | - x + 2 = 3 : bool$

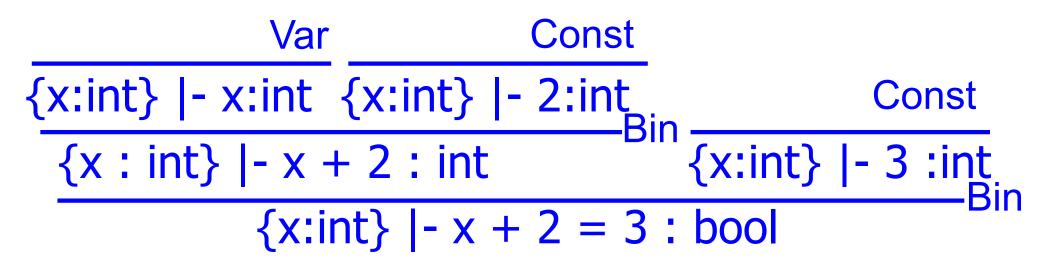
What do we need for the left side?

$\frac{\{x:int\} |-x+2:int \ \{x:int\} |-3:int \ \{x:int\} |-x+2 = 3:bool$

How to finish?



Complete Proof (type derivation)



Simple Rules - Booleans

Connectives

$$\frac{\Gamma \mid -e_1 : \text{bool} \quad \Gamma \mid -e_2 : \text{bool}}{\Gamma \mid -e_1 \&\& e_2 : \text{bool}}$$

$$\Gamma \mid -e_1 : \text{bool} \quad \Gamma \mid -e_2 : \text{bool}$$
$$\Gamma \mid -e_1 \mid \mid e_2 : \text{bool}$$

Type Variables in Rules

• If then else rule: $\Gamma \mid -e_1 : bool \quad \Gamma \mid -e_2 : \tau \quad \Gamma \mid -e_3 : \tau$ $\Gamma \mid -(if e_1 then e_2 else e_3) : \tau$

- τ is a type variable (meta-variable)
- Can take any type at all
- All instances in a rule application must get same type
- Then branch, else branch and if_then_else must all have same type

Example derivation: if-then-else-

Γ = {x:int, int_of_float:float -> int, y:float}

- - Γ |- if (fun y -> y > 3) x then x + 2 else int_of_float y : int

Function Application

Application rule:

$$\frac{\Gamma \mid - e_1 : \tau_1 \rightarrow \tau_2 \quad \Gamma \mid - e_2 : \tau_1}{\Gamma \mid - (e_1 \ e_2) : \tau_2}$$

• If you have a function expression e_1 of type $\tau_1 \rightarrow \tau_2$ applied to an argument e_2 of type τ_1 , the resulting expression e_1e_2 has type τ_2

Example: Application

Γ = {x:int, int_of_float:float -> int, y:float}

 $\Gamma \mid - (fun \ y \ -> \ y \ > 3)$: int -> bool $\Gamma \mid -x$: int

 Γ |- (fun y -> y > 3) x : bool

Fun Rule

- Rules describe types, but also how the environment
 may change
- Can only do what rule allows!
- fun rule:

$$\{x:\tau_1\} + \Gamma \mid e:\tau_2$$

$$\Gamma \mid fun \ x \rightarrow e:\tau_1 \rightarrow \tau_2$$

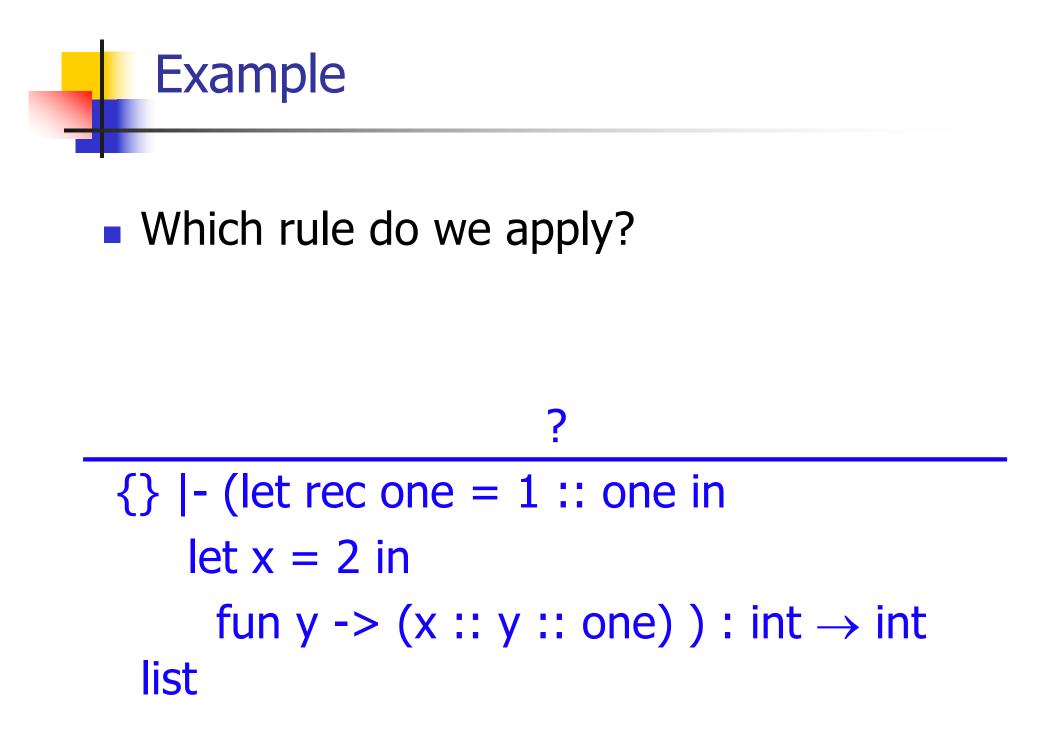


$\frac{\{y : int\} + \Gamma \mid -y + 3 : int}{\Gamma \mid -fun \mid y - y \mid + 3 : int \rightarrow int}$

$\begin{array}{l} \{f: \operatorname{int} \to \operatorname{bool}\} + \Gamma \mid -f \ 2 :: [true] : \operatorname{bool} \operatorname{list} \\ \Gamma \mid -(\operatorname{fun} f \ -> (f \ 2) :: [true]) \\ : (\operatorname{int} \to \operatorname{bool}) \to \operatorname{bool} \operatorname{list} \end{array}$

(Monomorphic) Let and Let Rec

- let rule: $\Gamma \mid -e_{1} : \tau_{1} \quad \{x : \tau_{1}\} + \Gamma \mid -e_{2} : \tau_{2}$ $\Gamma \mid -(\text{let } x = e_{1} \text{ in } e_{2}) : \tau_{2}$
- Iet rec rule:
 - $\{x: \tau_1\} + \Gamma \mid -e_1:\tau_1 \{x: \tau_1\} + \Gamma \mid -e_2:\tau_2$ $\Gamma \mid -(\text{let rec } x = e_1 \text{ in } e_2): \tau_2$



Example

(2) {one : int list} |-Let rec rule: (let x = 2 in)fun y -> (x :: y :: one)) {one : int list} |-(1 :: one) : int list : int \rightarrow int list $\{\} | - (\text{let rec one} = 1 :: \text{one in})$ let x = 2 in fun y -> (x :: y :: one)) : int \rightarrow int list



Which rule?

{one : int list} |- (1 :: one) : int list



Binary Operator

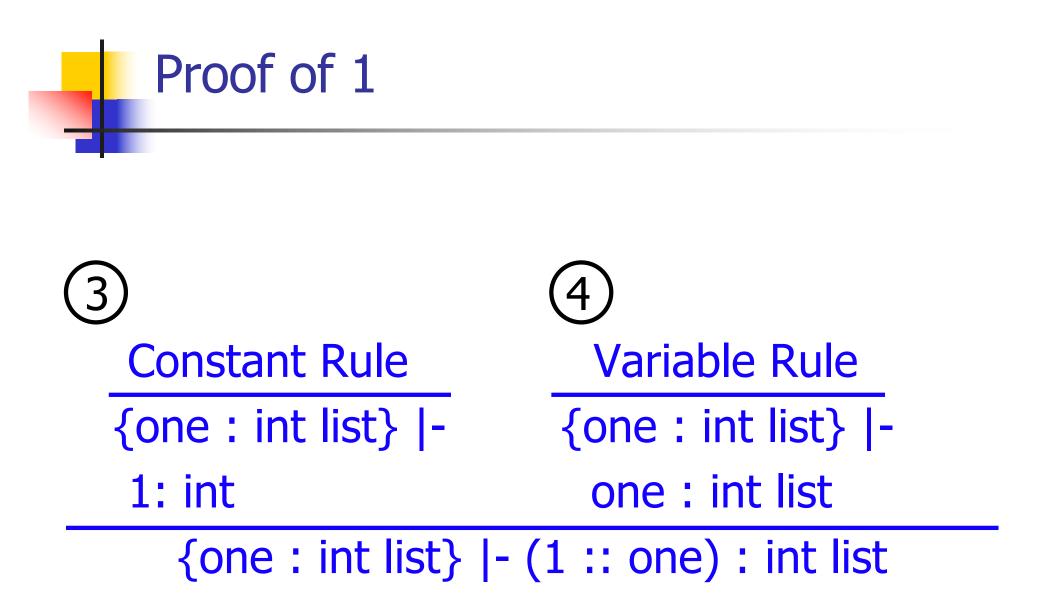
 3
 (4)

 {one : int list} | {one : int list} |

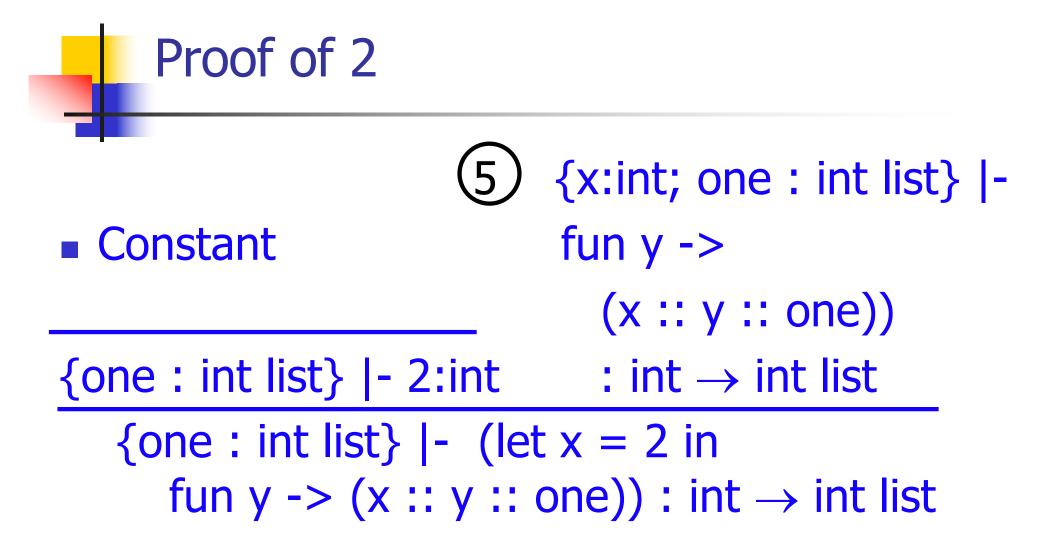
 1: int
 one : int list

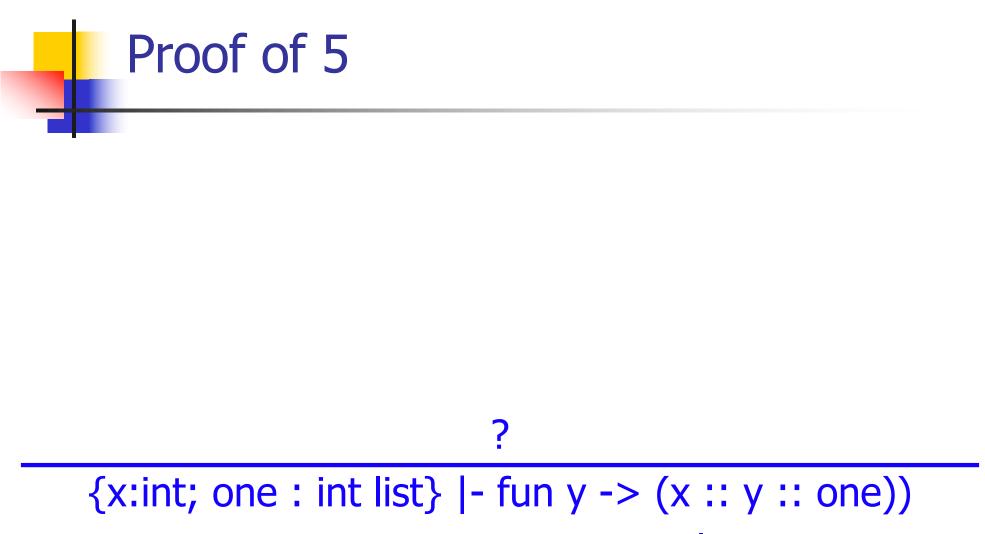
 {one : int list} |- (1 :: one) : int list

where (::) : int \rightarrow int list \rightarrow int list

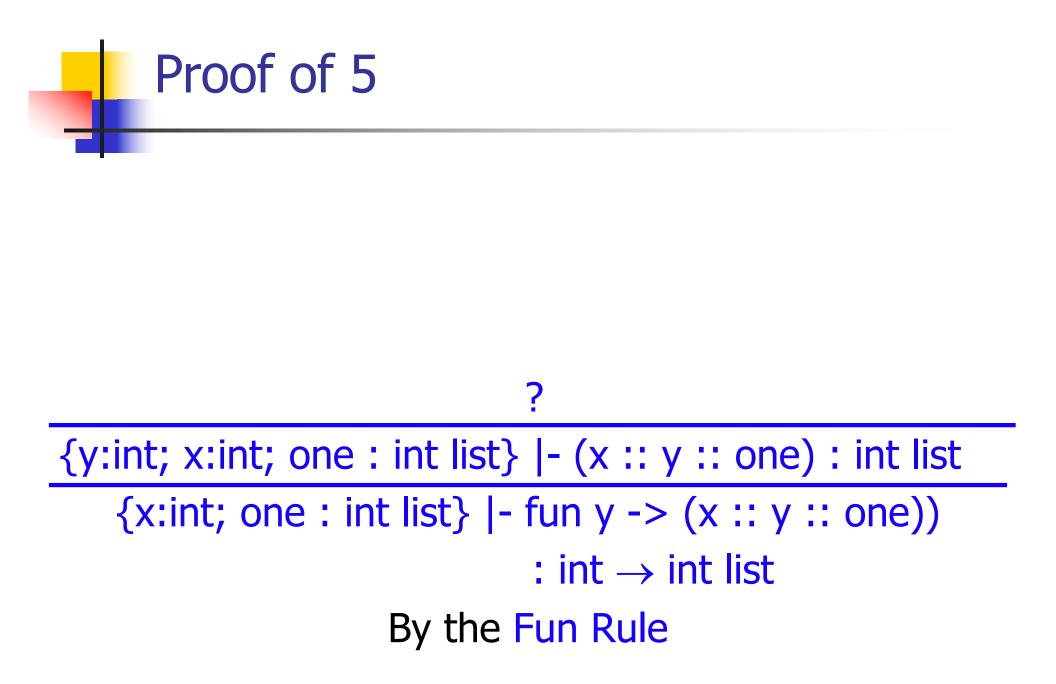


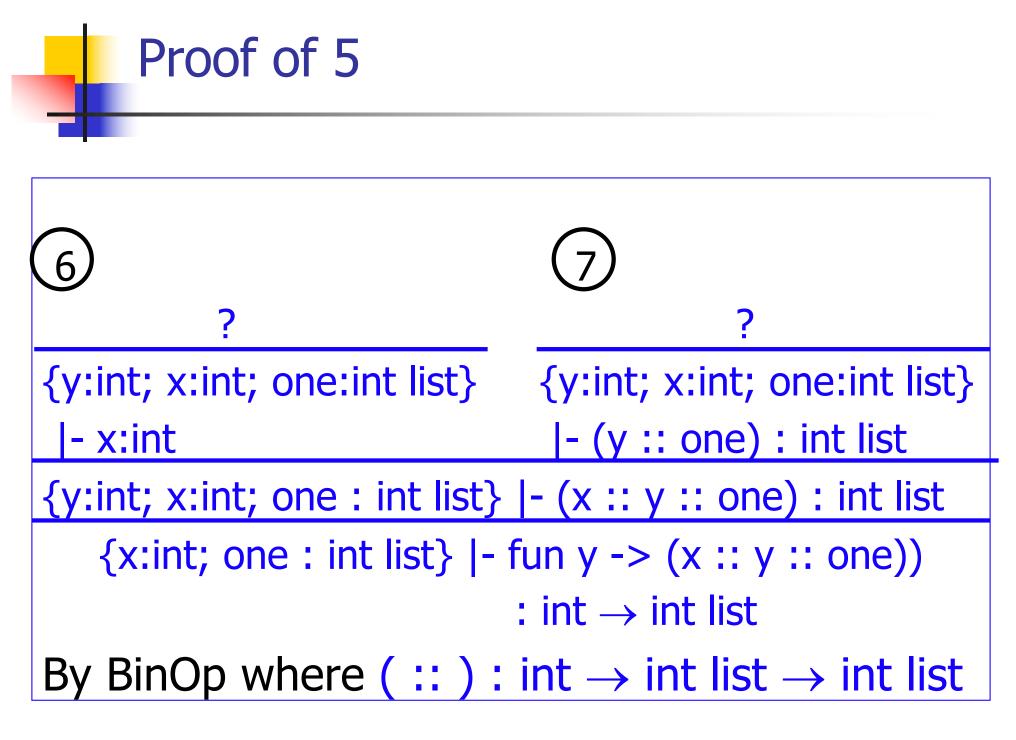
Proof of 2 Let Rule {x:int; one : int list} |fun y -> (x :: y :: one)) $\{\text{one : int list}\} \mid -2:\text{int} : \text{int} \rightarrow \text{int list} \}$ $\{\text{one}: \text{int list}\} \mid - (\text{let } x = 2 \text{ in})$ fun y -> (x :: y :: one)) : int \rightarrow int list

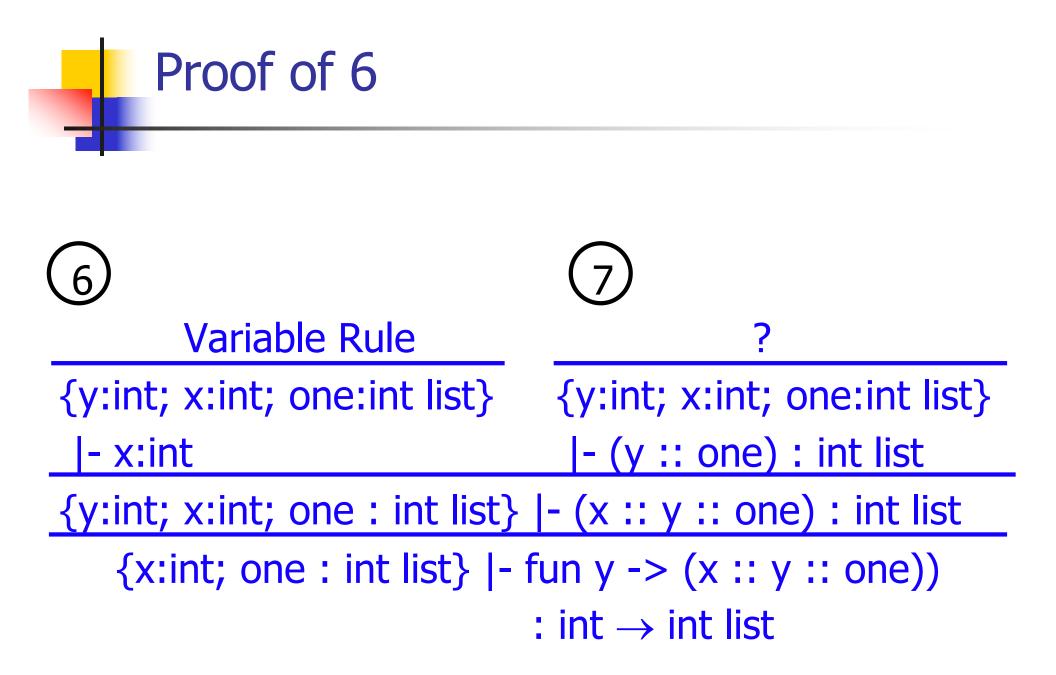


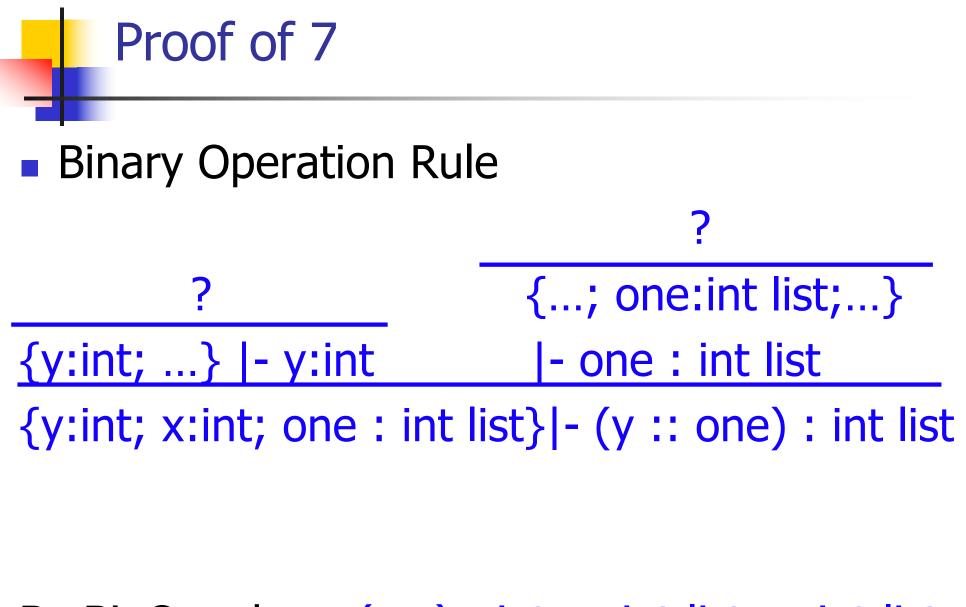


: int \rightarrow int list









By BinOp where (::) : int \rightarrow int list \rightarrow int list

Proof of 7	
	Variable Rule
Variable Rule	<pre>{; one:int list;}</pre>
{y:int;} - y:int	- one : int list
{y:int; x:int; one : int	: list} - (y :: one) : int list

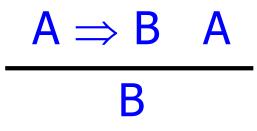
Curry - Howard Isomorphism

- Type Systems are logics; logics are type systems
- Types are propositions; propositions are types
- Terms are proofs; proofs are terms

 Function space arrow corresponds to implication; application corresponds to modus ponens



Modus Ponens



• Application $\Gamma \mid -e_1 : \alpha \to \beta \quad \Gamma \mid -e_2 : \alpha$ $\Gamma \mid -(e_1 e_2) : \beta$