CS/ECE 374 A: Algorithms & Models of Computation

Bellman-Ford and All-Pairs Shortest Paths

Lecture 19 April 3, 2025

Part I

SSSP with Negative Weights

Want to solve the single-source shortest-path problem: given a vertex s, what is dist(s, t) for each vertex t?

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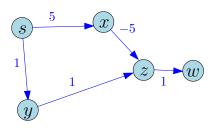
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Dijkstra's algorithm makes "guesses" based on shortest path seen so far, and at each step "confirms" the smallest guess.

- Correct as long as the edge weights are all non-negative.
- May give the wrong answer if there are negative edge weights!



DP: Attempt 1

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Subproblem definition:

Recurrence:

Evaluation Order:

DP: Attempt 2

How do we avoid circular dependencies? (Hint: add a subproblem parameter.)

Subproblem definition:

Recurrence:

Evaluation Order:

DP Pseudocode

Let LSP(v, ℓ) be the length of the shortest path from s to v that uses at most ℓ edges.

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\begin{aligned} & \text{SSSP-DP}(G,\ s): \\ & \text{Initialize LSP as a } V \times V \text{ matrix} \\ & \text{Set LSP}[s,0] = 0 \text{ and LSP}[v,0] = \infty \text{ for all } v \neq s \\ & \text{for } \ell \text{ from 1 to } V - 1: \\ & \text{for all vertices } v: \\ & \text{LSP}[v,\ell] = \text{LSP}[v,\ell-1] \\ & \text{for all edges } (u,v): \\ & \text{LSP}[v,\ell] = \min(\text{LSP}[v,\ell], \text{LSP}[u,\ell-1] + w(u,v)) \\ & \text{return LSP}[u,V-1] \text{ for all } u \in V \end{aligned}
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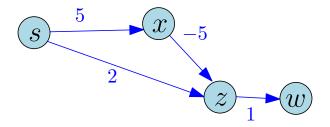
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Efficiency?

DP Example



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BellmanFord(G, s):

Set s.dist = 0 and v.dist = \infty for all v \neq s

for \ell from 1 to V-1:

for all edges (u,v):

v.dist = \min(v.dist, u.dist + w(u,v))

return u.dist for all u \in V
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Correctness?

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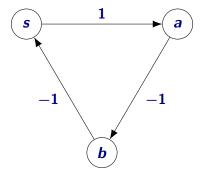
return v.\text{dist} = 0
```

Correctness?

Proof by induction: after iteration i, v.dist $\leq LSP(v, i)$ for all v.

Just One Catch

What happens to Bellman-Ford on the following graph?



Negative Cycles

If our graph has a cycle with negative *total* length, our argument that the shortest path must use at most V-1 edges breaks down.

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(Technically, it's actually the concept of a shortest walk that breaks down. But note that all our algorithms implicitly are computing the shortest walk and using the fact that the shortest walk must be a path as long as there are no negative cycles. In fact, if we really want to find the shortest path with no restrictions on the weights at all, this turns out to be one of the canonically hard problems we study in the last part of the course!)

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for \ell from 1 to \ell - 1:

for all edges (u, v):

v.dist = \min(v.dist, u.dist + u(u, v))

for all edges (u, v):

if v.dist > u.dist + u(u, v): return ''Negative cycle!'' return u.dist for all u \in \ell
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Exercise: modify the pseudocode to output a negative cycle.

Negative Weights Takeaways

If G has no negative cycles, we can use BellmanFord to solve the SSSP problem in O(VE) time.

• Can also check if **G** has a negative cycle!

If G may have negative cycles, the SSSP problem is (depending on your definitions) either (1) not well-defined, or (2) one of the canonical hard problems we'll consider in the last part of the class.

Part II

All-Pairs Shortest Paths

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More general question: output dist(s, t) for all pairs of s and t. (Similar to SSSP, we will need to assume no negative cycles.)

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Naïve approach: run SSSP from each vertex.

- Non-negative weights (Dijkstra): $O(V(V + E) \log V)$ time
- Negative weights (Bellman-Ford): $O(V^2E)$ time

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Can we do better?

When In Doubt, Try Using DP

How would we write a DP algorithm for this?

Subproblem definition:

Recurrence:

Evaluation Order:

DP Pseudocode

Let LSP (u, v, ℓ) be the length of the shortest path from u to v that uses at most ℓ edges.

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APSP-DP(G):
     Initialize LSP as a \mathbf{V} \times \mathbf{V} \times \mathbf{V} matrix
     Set LSP[u, u, 0] = 0 for all u
     Set LSP[u, v, 0] = \infty for all u \neq v
     for \ell from 1 to V-1:
           for all vertices u:
                 for all vertices v:
                      LSP[u, v, \ell] = LSP[u, v, \ell - 1]
                      for all edges (x, v):
                            LSP[u, v, \ell] = min \begin{pmatrix} LSP[u, v, \ell], \\ LSP[u, x, \ell - 1] + w(x, v) \end{pmatrix}
     return LSP[u, v, V - 1] for all u, v \in V
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DP Pseudocode

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     return LSP[u, v, V - 1] for all u, v \in V
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Efficiency?

Improving Our Approach

Can we come up with a more efficient recurrence?

Subproblem definition: Let LSP(u, v, ℓ) be the length of the shortest path from u to v that uses at most ℓ edges.

Recurrence:

Evaluation Order:

Fischer-Meyer Pseudocode

Let LSP (u, v, ℓ) be the length of the shortest path from u to v that uses at most 2^{ℓ} edges.

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FischerMeyer(G):

Initialize LSP as a V \times V \times (\lceil \log_2(V) \rceil + 1) matrix

Set LSP[u, v, 0] = w(u, v) for all u, v \in V

# Let w(u, u) := 0, and for all (u, v) \notin E let w(u, v) := \infty

for \ell from 1 to \lceil \log_2(V) \rceil:

for all vertices u:

LSP[u, v, \ell] = \min_x (\text{LSP}[u, x, \ell - 1] + \text{LSP}[x, v, \ell - 1])

return LSP[u, v, \lceil \log_2(V) \rceil] for all u, v \in V
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LSP[u, v, \ell] = \min_x (\text{LSP}[u, x, \ell - 1] + \text{LSP}[x, v, \ell - 1]) return LSP[u, v, \lceil \log_2(V) \rceil] for all u, v \in V
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Efficiency?

A Clever Subproblem

Subproblem definition:

Recurrence:

Evaluation Order:

Clever DP Pseudocode

Let LSP(u, v, r) be the length of the shortest path from u to v that only uses intermediate vertices from $\{1, 2, \ldots r\}$.

```
APSP-CleverDP(G):

Initialize LSP as a V \times V \times (V+1) matrix

Set LSP[u, v, 0] = w(u, v) for all u, v \in V

# Let w(u, u) := 0, and for all (u, v) \notin E let w(u, v) := \infty

for r from 1 to V:

for all vertices u:

LSP[u, v, r] = min \begin{pmatrix} \text{LSP}[u, v, r-1], \\ \text{LSP}[u, v, r-1] \end{pmatrix}

return LSP[u, v, V] for all u, v \in V
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\begin{aligned} &\mathsf{APSP\text{-}CleverDP}(G)\colon\\ &\mathsf{Initialize}\ \mathsf{LSP}\ \mathsf{as}\ \mathsf{a}\ V\times V\times (V+1)\ \mathsf{matrix}\\ &\mathsf{Set}\ \mathsf{LSP}[u,v,0]=w(u,v)\ \mathsf{for}\ \mathsf{all}\ u,v\in V\\ &\#\ \mathsf{Let}\ w(u,u):=0,\ \mathsf{and}\ \mathsf{for}\ \mathsf{all}\ (u,v)\not\in E\ \mathsf{let}\ w(u,v):=\infty\\ &\mathsf{for}\ \mathsf{r}\ \mathsf{from}\ 1\ \mathsf{to}\ V\colon\\ &\mathsf{for}\ \mathsf{all}\ \mathsf{vertices}\ u\colon\\ &\mathsf{for}\ \mathsf{all}\ \mathsf{vertices}\ v\colon\\ &\mathsf{LSP}[u,v,r]=\min\left(\begin{smallmatrix} \mathsf{LSP}[u,v,r-1],\\ \mathsf{LSP}[u,v,r-1] + \mathsf{LSP}[r,v,r-1] \end{smallmatrix}\right)\\ &\mathsf{return}\ \mathsf{LSP}[u,v,V]\ \mathsf{for}\ \mathsf{all}\ u,v\in V\end{aligned}
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for all vertices r:
    for all vertices v:
        dist[u,v] = \min \begin{pmatrix} \operatorname{dist}[u,v], \\ \operatorname{dist}[u,v] + \operatorname{dist}[r,v] \end{pmatrix}

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return \operatorname{dist}[u,v] for all u,v \in V
```

Correctness? Proof by induction: after iteration i of outermost loop, dist[u, v] < LSP(u, v, i) for all $u, v \in V$.

Problems and Algorithms From Today

- Shortest paths from s with no negative cycles
 - Bellman-Ford, O(VE)
 - Can also check for negative cycles
- All-pairs shortest paths with no negative cycles
 - Negative weights: Floyd-Warshall, $O(V^3)$
 - Non-negative weights: Djikstra from each vertex,