CS/ECE 374: Algorithms & Models of Computation

# Bellman-Ford and Dynamic Programming

Lecture 18



# Part I

# No negative edges: Dijkstra



# Dijkstra's Algorithm

Initialize for each node v, 
$$\operatorname{dist}(s, v) = \infty$$
  
Initialize  $X = \emptyset$ ,  $\operatorname{dist}(s, s) = 0$   
for  $i = 1$  to  $|V|$  do  
Let v be such that  $\operatorname{dist}(s, v) = \min_{u \in V-X} \operatorname{dist}(s, u)$   
 $X = X \cup \{v\}$   
for each u in  $\operatorname{Adj}(v)$  do  
 $\operatorname{dist}(s, u) = \min(\operatorname{dist}(s, u), \operatorname{dist}(s, v) + \ell(v, u))$ 

Priority Queues to maintain *dist* values for faster running time

- **1** Using heaps and standard priority queues:  $O((m + n) \log n)$
- Best-first-search

# Dijkstra's Algorithm using Priority Queues

```
Q \leftarrow \mathsf{makePQ}()
insert(Q, (s,0))
for each node u \neq s do
insert(Q, (u,\infty))
X \leftarrow \emptyset
for i = 1 to |V| do
(v, \operatorname{dist}(s, v)) = extractMin(Q)
X = X \cup \{v\}
for each u in Adj(v) do
decreaseKey(Q, (u, \min(\operatorname{dist}(s, u), \operatorname{dist}(s, v) + \ell(v, u)))).
```

Priority Queue operations:

- O(n) insert operations
- O(n) extractMin operations
- O(m) decreaseKey operations

# Implementing Priority Queues via Heaps

## Using Heaps

Store elements in a heap based on the key value

• All operations can be done in  $O(\log n)$  time



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## Fibonacci Heaps

- extractMin, insert, delete, meld in O(log n) time
- **Olymotry** decreaseKey in **O(1)** *amortized* time:



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- ③ Relaxed Heaps: decreaseKey in O(1) worst case time but at the expense of meld (not necessary for Dijkstra's algorithm)
- Dijkstra's algorithm can be implemented in  $O(n \log n + m)$  time.
- Data structures are complicated to analyze/implement. Recent work has obtained data structures that are easier to analyze and implement, and perform well in practice. Rank-Pairing Heaps (European Symposium on Algorithms, September 2009!)

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- We have to recognize the *i*-th closest node?  $d'(s, u) = \min(d'(s, u), \operatorname{dist}(s, v) + \ell(v, u))$

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- 2 How to recognize the *i*-th closest node?
   d'(s, u) = min(d'(s, u), dist(s, v) + ℓ(v, u))
   o'(s, u) ≥ d(s, u)

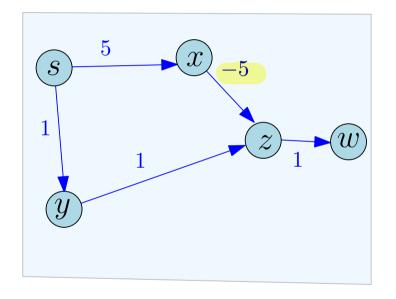
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- Wow to recognize the *i*-th closest node?
  d'(s, u) = min(d'(s, u), dist(s, v) + ℓ(v, u))
  d'(s, u) ≥ d(s, u)
  d'(s, v) = min<sub>u∈V-X</sub> d'(s, u) is the *i*-th closest node, and d'(s, v) = d(s, v)

# Part II

# Negative Edges: Bellman-Ford



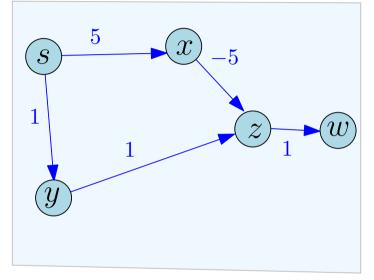
# What are the distances computed by Dijkstra's algorithm?



The distance as computed by Dijkstra algorithm starting from *s*:

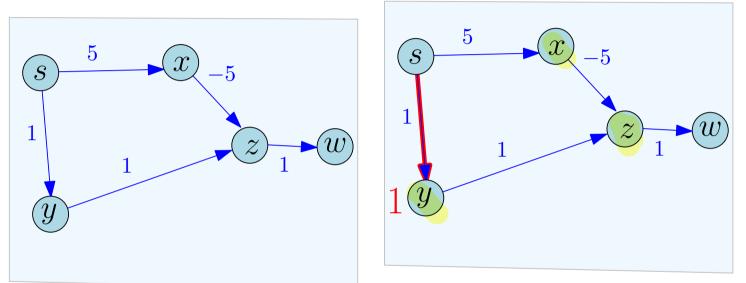
- (a) s = 0, x = 5, y = 1, z = 0.
- (b) s = 0, x = 1, y = 2, z = 5.
- (a) s = 0, x = 5, y = 1, z = 2.

IDK.





With negative length edges, Dijkstra's algorithm can fail

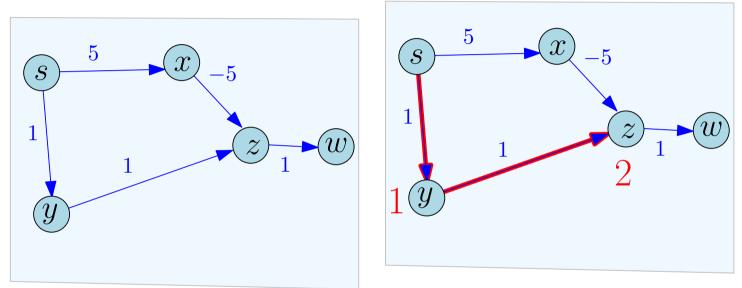


$$X = \{ s, y \}$$
  

$$S \rightarrow y \rightarrow Z \qquad d'(s, Z) = 2$$
  

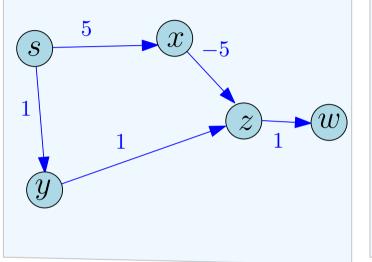
$$< d'(s, X)$$

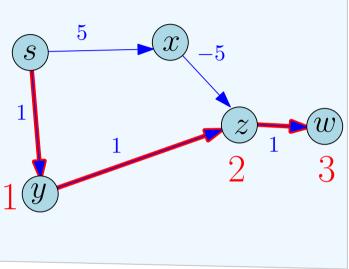
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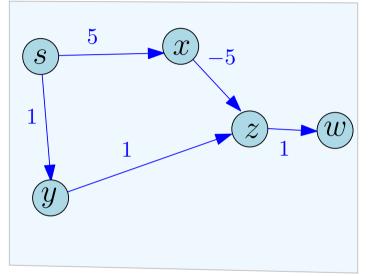
$$\begin{array}{c} X = \left\{ S, Y, Z \right\} \\ X, W \\ X, W \\ \zeta d'(S, W) = 3 \\ \zeta d'(S, X) \end{array}$$

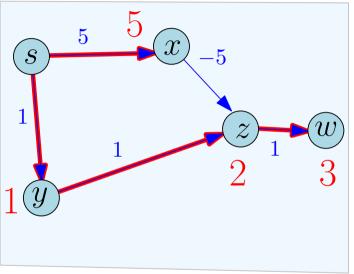
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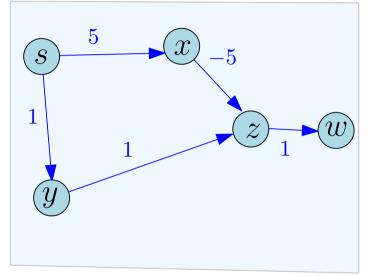


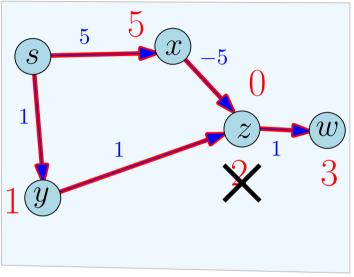




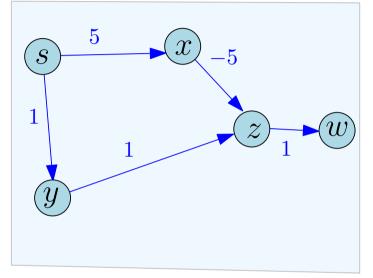


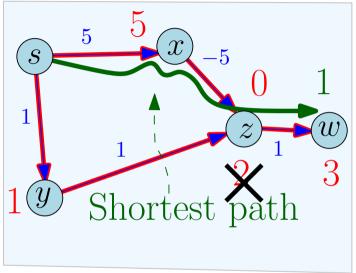






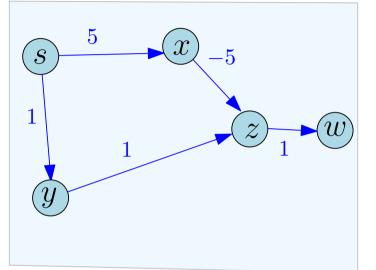


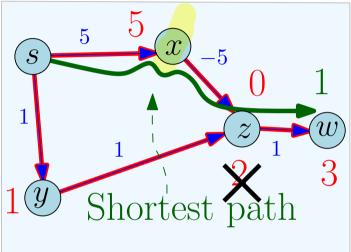






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False assumption: Dijkstra's algorithm is based on the assumption that if  $s = v_0 \rightarrow v_1 \rightarrow v_2 \dots \rightarrow v_k$  is a shortest path from s to  $v_k$ then  $dist(s, v_i) \leq dist(s, v_{i+1})$  for  $0 \leq i < k$ . Holds true only for non-negative edge lengths.

# Anything we can learn from Dijkstra?

 $d'(s, u) = \min(d'(s, u), \operatorname{dist}(s, v) + \ell(v, u))$ •  $d'(s, u) \ge d(s, u)$  still true.



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 $d'(s, u) = \min(d'(s, u), \operatorname{dist}(s, v) + \ell(v, u))$ •  $d'(s, u) \ge d(s, u) \text{ still true.}$ 

- if  $s = v_0 \rightarrow v_1 \rightarrow v_2 \dots \rightarrow v_k$  is a shortest path from s to  $v_k$ • for  $1 \leq i < k$ :  $s = v_0 \rightarrow v_1 \rightarrow v_2 \rightarrow \dots \rightarrow v_i$  is a shortest path from s to  $v_i$ , i.e. subpath of a shortest path is still a shortest path.
  - Not true: dist(s, v<sub>i</sub>) ≤ dist(s, v<sub>i+1</sub>), the intermediate set is no longer X; in fact, it can be anything

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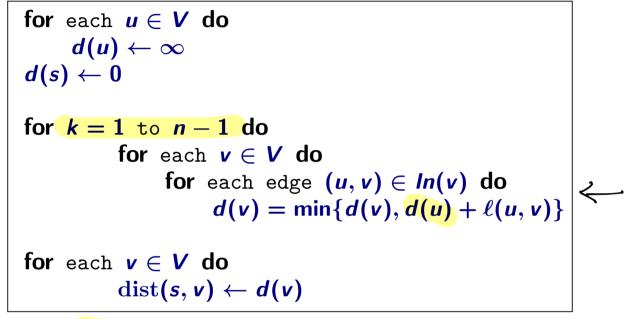
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- if  $s = v_0 \rightarrow v_1 \rightarrow v_2 \ldots \rightarrow v_k$  is a shortest path from s to  $v_k$ 
  - for 1 ≤ i < k: s = v<sub>0</sub> → v<sub>1</sub> → v<sub>2</sub> → ... → v<sub>i</sub> is a shortest path from s to v<sub>i</sub>, i.e. subpath of a shortest path is still a shortest path.
  - Not true: dist(s, v<sub>i</sub>) ≤ dist(s, v<sub>i+1</sub>), the intermediate set is no longer X; in fact, it can be anything

Solution: Update all edges |V| - 1 times!

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# Bellman-Ford Algorithm



Running time: **O(mn)** 

# Part III

# Bellman-Ford and DP



## Shortest Paths and Recursion

- Compute the shortest path distance from s to t recursively?
- What are the smaller sub-problems?



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- Compute the shortest path distance from s to t recursively?
- What are the smaller sub-problems?

#### Lemma

Let G be a directed graph with arbitrary edge lengths. If

 $s = v_0 \rightarrow v_1 \rightarrow v_2 \rightarrow \ldots \rightarrow v_k$  is a shortest path from s to  $v_k$  then for  $1 \leq i < k$ :

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Sub-problem idea: paths of fewer hops/edges



Single-source problem: fix source *s*.

d(v, k): shortest path length from s to v using at most k edges.



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Recursion for d(v, k):



Single-source problem: fix source s.

d(v, k): shortest path length from s to v using at most k edges. Note: dist(s, v) = d(v, n - 1).

Recursion for d(v, k):

$$d(v, k) = \min \begin{cases} \min_{u \in In(v)} (d(u, k-1) + \ell(u, v)), \\ d(v, k-1) \\ \mathbb{R} + mo \text{ St } | < -| \quad edges \\ \text{case: } d(s, 0) = 0 \text{ and } d(v, 0) = \infty \text{ for all } v \neq s. \end{cases}$$

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Base

# Example

-3

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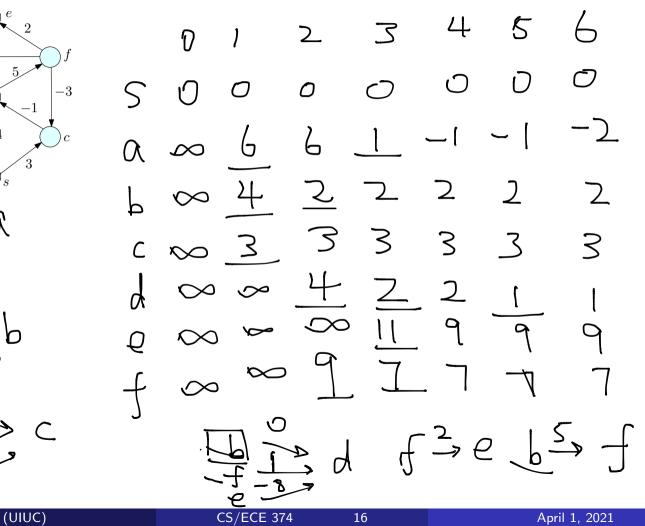
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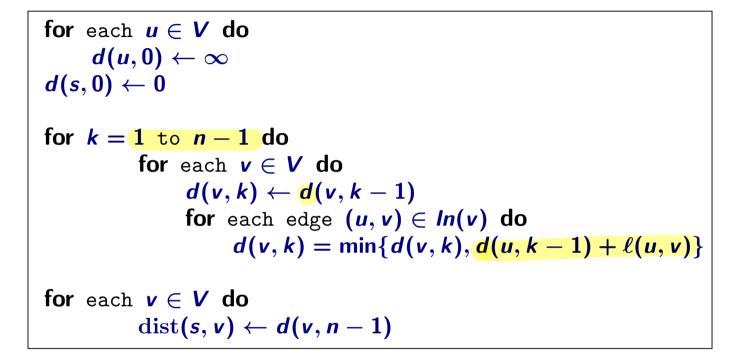
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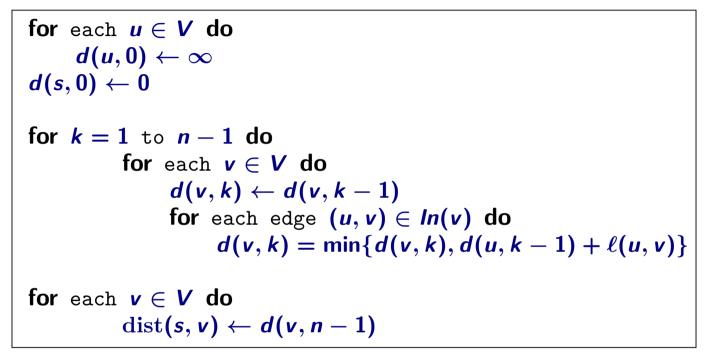
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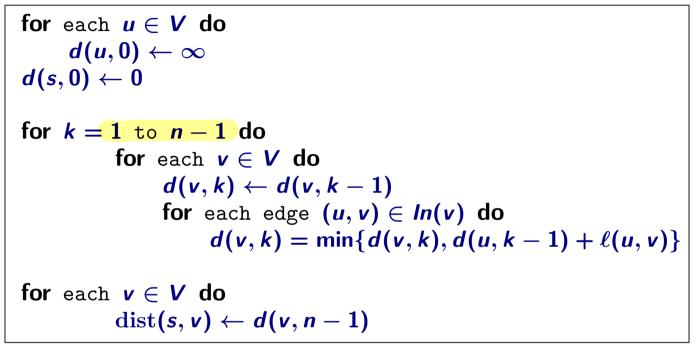






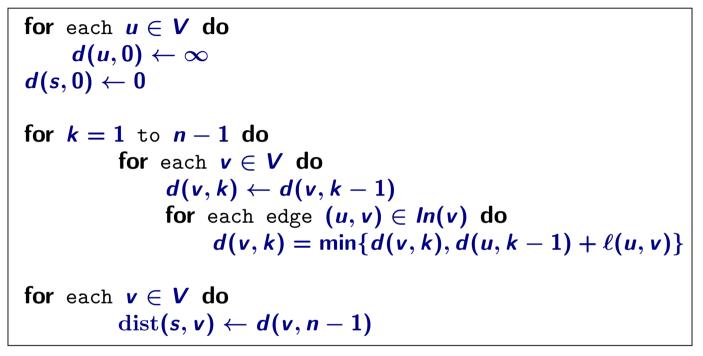


Running time:

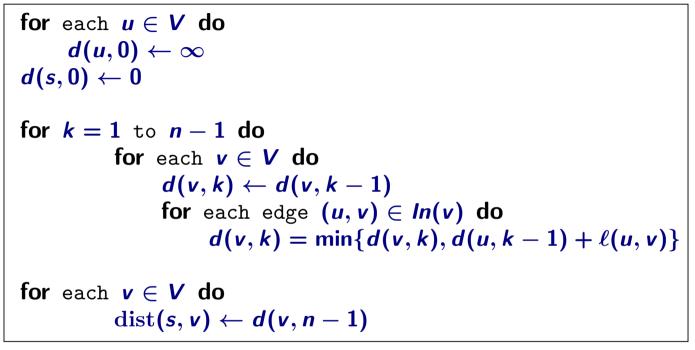


Running time: O(mn)

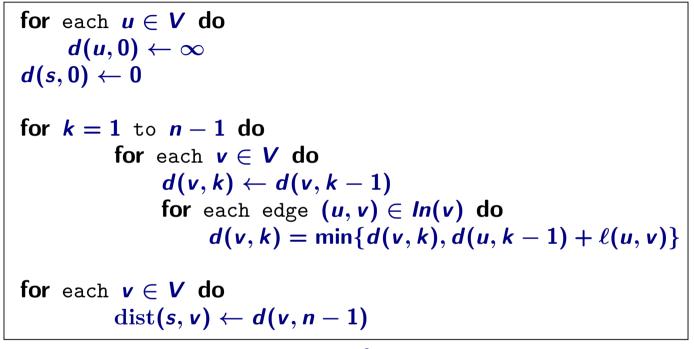
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Running time: O(mn) Space:



Running time: O(mn) Space:  $O(n^2)$ 



Running time: O(mn) Space:  $O(n^2)$ Space can be reduced to O(n).

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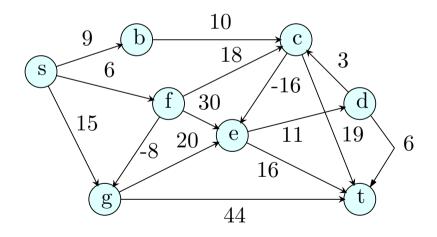
```
for each \boldsymbol{u} \in \boldsymbol{V} do
    d(u) \leftarrow \infty
d(s) \leftarrow 0
for k = 1 to n - 1 do
            for each \mathbf{v} \in \mathbf{V} do
                   for each edge (u, v) \in In(v) do
                          d(v) = \min\{d(v), \frac{d(u)}{d(u)} + \ell(u, v)\}
for each v \in V do
             dist(s, v) \leftarrow d(v)
```

Running time: O(mn) Space: O(n)

# Negative Length Cycles

#### Definition

A cycle C is a negative length cycle if the sum of the edge lengths of C is negative.

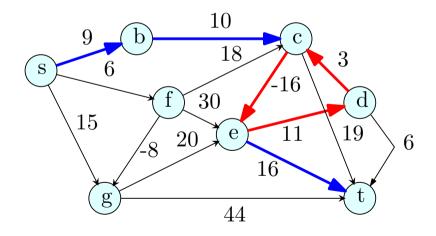




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## Shortest Paths and Negative Cycles

Given G = (V, E) with edge lengths and s, t. Suppose

- G has a negative length cycle C, and
- **2** s can reach C and C can reach t.

**Question:** What is the shortest **distance** from *s* to *t*?



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Given G = (V, E) with edge lengths and s, t. Suppose

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 $-\infty$ 



# Bellman-Ford: Negative Cycle Detection

Check if distances change in iteration *n*.

```
for each \mu \in V do
    d(u) \leftarrow \infty
d(s) \leftarrow 0
for k = 1 to n - 1 do
           for each \mathbf{v} \in \mathbf{V} do
                for each edge (u, v) \in In(v) do
                      d(v) = \min\{d(v), d(u) + \ell(u, v)\}
(* One more iteration to check if distances change *)
for each \mathbf{v} \in \mathbf{V} do
     for each edge (u, v) \in In(v) do
           if (d(v) > d(u) + \ell(u, v))
                Output ''Negative Cycle''
for each \mathbf{v} \in \mathbf{V} do
           dist(s, v) \leftarrow d(v)
```

# Negative Cycle Detection

#### Negative Cycle Detection

Given directed graph G with arbitrary edge lengths, does it have a negative length cycle?





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#### Negative Cycle Detection

Given directed graph G with arbitrary edge lengths, does it have a negative length cycle?

- Bellman-Ford checks whether there is a negative cycle C that is reachable from a specific vertex s. There may negative cycles not reachable from s.
- 2 Run Bellman-Ford |V| times, once from each node u?



# Negative Cycle Detection

- Add a new node s' and connect it to all nodes of G with zero length edges. Bellman-Ford from s' will find a negative length cycle if there is one. Exercise: why does this work?
- Negative cycle detection can be done with one Bellman-Ford invocation.

