CS/ECE 374: Algorithms \& Models of Computation

## Bellman-Ford and Dynamic Programming

Lecture 18

## Part I

## No negative edges: Dijkstra

## Dijkstra's Algorithm

$$
\begin{aligned}
& \text { Initialize for each node } v, \operatorname{dist}(s, v)=\infty \\
& \text { Initialize } X=\emptyset, \operatorname{dist}(s, s)=0 \\
& \text { for } \boldsymbol{i}=1 \text { to }|V| \text { do } \\
& \quad \text { Let } v \text { be such that } \operatorname{dist}(s, v)=\min _{u \in v-x} \operatorname{dist}(s, u) \\
& X=X \cup\{v\} \\
& \quad \text { for each } \boldsymbol{u} \text { in } \operatorname{Adj}(v) \text { do } \\
& \qquad \operatorname{dist}(s, u)=\min (\operatorname{dist}(s, u), \operatorname{dist}(s, v)+\ell(v, u))
\end{aligned}
$$

Priority Queues to maintain dist values for faster running time
(1) Using heaps and standard priority queues: $O((m+n) \log n)$
(2) Best-first-search

## Dijkstra's Algorithm using Priority Queues

```
\(Q \leftarrow\) makePQ()
insert ( \(Q,(s, 0)\) )
for each node \(u \neq s\) do
    insert \((Q,(u, \infty))\)
\(X \leftarrow \emptyset\)
for \(\boldsymbol{i}=1\) to \(|V|\) do
    \((v, \operatorname{dist}(s, v))=\operatorname{extractMin}(Q)\)
    \(X=X \cup\{v\}\)
    for each \(u\) in \(\operatorname{Adj}(v)\) do
        \(\operatorname{decreaseKey}(\boldsymbol{Q},(\boldsymbol{u}, \min (\operatorname{dist}(s, u), \operatorname{dist}(s, \boldsymbol{v})+\ell(\boldsymbol{v}, u))))\).
```

Priority Queue operations:
(1) $O(n)$ insert operations
(2) $O(n)$ extractMin operations
(3) $O(m)$ decreaseKey operations

## Implementing Priority Queues via Heaps

## Using Heaps

Store elements in a heap based on the key value
(1) All operations can be done in $O(\log n)$ time

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Dijkstra's algorithm can be implemented in $O((n+m) \log n)$ time.

## Priority Queues: Fibonacci Heaps/Relaxed Heaps

## Fibonacci Heaps

(1) extractMin, insert, delete, meld in $O(\log n)$ time
(2) decreaseKey in $O(1)$ amortized time:

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(1) Dijkstra's algorithm can be implemented in $O(n \log n+m)$ time.

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## Fibonacci Heaps

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(0) Relaxed Heaps: decreaseKey in $O(\mathbf{1})$ worst case time but at the expense of meld (not necessary for Dijkstra's algorithm)
(1) Dijkstra's algorithm can be implemented in $O(n \log n+m)$ time.
(2) Data structures are complicated to analyze/implement. Recent work has obtained data structures that are easier to analyze and implement, and perform well in practice. Rank-Pairing Heaps (European Symposium on Algorithms, September 2009!)

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(1) Non-negative edges: In order to get to $t$, only need nodes whose shortest distance is smaller than $t$.

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- Give us an evaluation order: $\boldsymbol{d}^{\prime}(\boldsymbol{s}, \boldsymbol{u})$ only updated when $\boldsymbol{v}$ is added to $\boldsymbol{X}$, and $\boldsymbol{u} \in \boldsymbol{\operatorname { A d j }}(\boldsymbol{v})$ and $\boldsymbol{u} \in \boldsymbol{V}-\boldsymbol{X}$


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- In particular, once a node is in $\boldsymbol{X}, \boldsymbol{d}^{\prime}(\boldsymbol{s}, \boldsymbol{u})$ no longer changes as $\boldsymbol{d}^{\prime}(\boldsymbol{s}, \boldsymbol{u})=\boldsymbol{d}(\boldsymbol{s}, \boldsymbol{u})$, and it is never updated again


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& d^{\prime}(s, u)=\min \left(d^{\prime}(s, u), \operatorname{dist}(s, v)+\ell(v, u)\right) \\
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& \text { - } d^{\prime}(s, u) \geq d(s, u) \\
& \text { - } d^{\prime}(s, v)=\min _{u \in v-x} d^{\prime}(s, u) \text { is the } i \text {-th closest node, and } \\
& d^{\prime}(s, v)=d(s, v)
\end{aligned}
$$

## Part II

## Negative Edges: Bellman-Ford

## What are the distances computed by Dijkstra's algorithm?

The distance as computed by Dijkstra algorithm starting from $s$ :
(A) $s=0, x=5, y=1$, $z=0$.
(B) $s=0, x=1, y=2$, $z=5$.
(c) $s=0, x=5, y=1$, $z=2$.
(D) IDK.

## Dijkstra's Algorithm and Negative Lengths

With negative length edges, Dijkstra's algorithm can fail


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$$
\begin{array}{ll}
x=\{s, y\} & \\
s \rightarrow y \rightarrow z & d^{\prime}(s, z)=2 \\
& <d^{\prime}(s, x)
\end{array}
$$

## Dijkstra's Algorithm and Negative Lengths

With negative length edges, Dijkstra's algorithm can fail


$$
\begin{array}{cc}
x=\{s, y, z\} & \\
x, w & d^{\prime}(s, w)=3 \\
& <d^{\prime}(s, x)
\end{array}
$$

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False assumption: Dijkstra's algorithm is based on the assumption that if $s=v_{0} \rightarrow v_{1} \rightarrow v_{2} \ldots \rightarrow v_{k}$ is a shortest path from $s$ to $v_{k}$ then $\operatorname{dist}\left(s, v_{i}\right) \leq \operatorname{dist}\left(s, v_{i+1}\right)$ for $\mathbf{0} \leq i<k$. Holds true only for non-negative edge lengths.

$$
d(s, x)>d(s, z)
$$

## Anything we can learn from Dijkstra?

$$
d^{\prime}(s, u)=\min \left(d^{\prime}(s, u), \operatorname{dist}(s, v)+\ell(v, u)\right)
$$

- $d^{\prime}(s, u) \geq d(s, u)$ still true.


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if $s=v_{0} \rightarrow v_{1} \rightarrow v_{2} \ldots \rightarrow v_{k}$ is a shortest path from $s$ to $v_{k}$

- for $\mathbf{1} \leq i<k: s=v_{0} \rightarrow v_{1} \rightarrow v_{2} \rightarrow \ldots \rightarrow v_{i}$ is a shortest path from $s$ to $v_{i}$, i.e. subpath of a shortest path is still a shortest path.
- Not true: $\operatorname{dist}\left(s, v_{i}\right) \leq \operatorname{dist}\left(s, v_{i+1}\right)$, the intermediate set is no longer $\boldsymbol{X}$; in fact, it can be anything


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$d^{\prime}(s, u)=\min \left(d^{\prime}(s, u), \operatorname{dist}(s, v)+\ell(v, u)\right)$

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if $s=v_{0} \rightarrow v_{1} \rightarrow v_{2} \ldots \rightarrow v_{k}$ is a shortest path from $s$ to $v_{k}$
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Solution: Update all edges $|\boldsymbol{V}|-\mathbf{1}$ times!

## Bellman-Ford Algorithm

$$
\begin{aligned}
& \text { for each } u \in V \text { do } \\
& \quad d(u) \leftarrow \infty \\
& d(s) \leftarrow 0 \\
& \text { for } k=1 \text { to } n-1 \text { do } \\
& \quad \text { for each } v \in V \text { do } \\
& \quad \text { for each edge }(u, v) \in \ln (v) \text { do } \\
& \quad d(v)=\min \{d(v), d(u)+\ell(u, v)\} \\
& \text { for each } v \in V \text { do } \\
& \quad \operatorname{dist}(s, v) \leftarrow d(v)
\end{aligned}
$$

Running time: $O(\mathbf{m n})$

## Part III

## Bellman-Ford and DP

## Shortest Paths and Recursion

(1) Compute the shortest path distance from $s$ to $t$ recursively?
(2) What are the smaller sub-problems?

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## Lemma

Let $G$ be a directed graph with arbitrary edge lengths. If $s=v_{0} \rightarrow v_{1} \rightarrow v_{2} \rightarrow \ldots \rightarrow v_{k}$ is a shortest path from $s$ to $v_{k}$ then for $\mathbf{1} \leq i<k$ :
(1) $s=v_{0} \rightarrow v_{1} \rightarrow v_{2} \rightarrow \ldots \rightarrow v_{i}$ is a shortest path from $s$ to $v_{i}$

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Sub-problem idea: paths of fewer hops/edges

## Hop-based Recursion: Bellman-Ford Algorithm

Single-source problem: fix source $s$.
$d(v, k)$ : shortest path length from $s$ to $v$ using at most $k$ edges.

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Note: $\operatorname{dist}(s, v)=d(v, n-1)$.
Recursion for $d(v, k)$ :

$$
d(v, k)=\min \left\{\begin{array}{l}
\min _{u \in \ln (v)}(d(u, k-1)+\ell(u, v)) . \\
d(v, k-1) \text { at most } k-1 \text { edges }
\end{array}\right.
$$

Base case: $d(s, 0)=0$ and $d(v, 0)=\infty$ for all $v \neq s$.

Example



## Bellman-Ford Algorithm

for each $\boldsymbol{u} \in \boldsymbol{V}$ do $d(u, 0) \leftarrow \infty$
$d(s, 0) \leftarrow 0$
for $k=1$ to $n-1$ do
for each $v \in V$ do
$d(v, k) \leftarrow d(v, k-1)$
for each edge $(u, v) \in \operatorname{In}(v)$ do $d(v, k)=\min \{d(v, k), d(u, k-1)+\ell(u, v)\}$
for each $\boldsymbol{v} \in \boldsymbol{V}$ do

$$
\operatorname{dist}(s, v) \leftarrow d(v, n-1)
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& \text { for each } v \in V \text { do } \\
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\end{array}
\end{aligned}
$$

for each $\boldsymbol{v} \in \mathbf{V}$ do

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Running time:

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Running time: $O(m n)$

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Running time: $O(\boldsymbol{m n})$ Space:

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Running time: $O(m n)$ Space: $O\left(n^{2}\right)$

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for each $\boldsymbol{v} \in \boldsymbol{V}$ do

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Running time: $O(m n)$ Space: $O\left(n^{2}\right)$
Space can be reduced to $O(n)$.

## Bellman-Ford Algorithm

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## Negative Length Cycles

## Definition

A cycle $C$ is a negative length cycle if the sum of the edge lengths of $C$ is negative.


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## Shortest Paths and Negative Cycles

Given $G=(V, E)$ with edge lengths and $s, t$. Suppose
(1) $G$ has a negative length cycle $C$, and
(2) $s$ can reach $C$ and $C$ can reach $t$.

Question: What is the shortest distance from $s$ to $t$ ?

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Question: What is the shortest distance from $s$ to $t$ ?
$-\infty$

## Bellman-Ford: Negative Cycle Detection

Check if distances change in iteration $\boldsymbol{n}$.

```
for each \(\boldsymbol{u} \in \boldsymbol{V}\) do
    \(d(u) \leftarrow \infty\)
\(d(s) \leftarrow 0\)
for \(k=1\) to \(n-\mathbf{1}\) do
    for each \(v \in V\) do
        for each edge \((u, v) \in \operatorname{In}(v)\) do
                        \(d(v)=\min \{d(v), d(u)+\ell(u, v)\}\)
(* One more iteration to check if distances change *)
for each \(\boldsymbol{v} \in \boldsymbol{V}\) do
    for each edge \((u, v) \in \operatorname{In}(v)\) do
    if \((d(v)>d(u)+\ell(u, v))\)
Output ''Negative Cycle'’
for each \(\boldsymbol{v} \in \boldsymbol{V}\) do
\[
\operatorname{dist}(s, v) \leftarrow d(v)
\]
```


## Negative Cycle Detection

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Given directed graph $G$ with arbitrary edge lengths, does it have a negative length cycle?

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Given directed graph $G$ with arbitrary edge lengths, does it have a negative length cycle?
(1) Bellman-Ford checks whether there is a negative cycle $C$ that is reachable from a specific vertex $\boldsymbol{s}$. There may negative cycles not reachable from $s$.
(2) Run Bellman-Ford $|\boldsymbol{V}|$ times, once from each node $\boldsymbol{u}$ ?

## Negative Cycle Detection

(1) Add a new node $s^{\prime}$ and connect it to all nodes of $G$ with zero length edges. Bellman-Ford from $s^{\prime}$ will find a negative length cycle if there is one. Exercise: why does this work?
(2) Negative cycle detection can be done with one Bellman-Ford invocation.

