CS/ECE 374: Algorithms & Models of Computation

Bellman-Ford and Dynamic Programming

Lecture 18

Part I

No negative edges: Dijkstra

Dijkstra's Algorithm

Initialize for each node v,
$$\operatorname{dist}(s, v) = \infty$$

Initialize $X = \emptyset$, $\operatorname{dist}(s, s) = 0$
for $i = 1$ to $|V|$ do
Let v be such that $\operatorname{dist}(s, v) = \min_{u \in V-X} \operatorname{dist}(s, u)$
 $X = X \cup \{v\}$
for each u in $\operatorname{Adj}(v)$ do
 $\operatorname{dist}(s, u) = \min(\operatorname{dist}(s, u), \operatorname{dist}(s, v) + \ell(v, u))$

Priority Queues to maintain *dist* values for faster running time

- **1** Using heaps and standard priority queues: $O((m + n) \log n)$
- Best-first-search

Dijkstra's Algorithm using Priority Queues

```
\begin{aligned} Q \leftarrow \mathsf{makePQ}() \\ \mathsf{insert}(Q, (s, 0)) \\ \mathsf{for each node } u \neq s \ \mathsf{do} \\ & \mathsf{insert}(Q, (u, \infty)) \\ X \leftarrow \emptyset \\ \mathsf{for } i = 1 \ \mathsf{to} \ |V| \ \mathsf{do} \\ & (v, \mathrm{dist}(s, v)) = extractMin(Q) \\ & X = X \cup \{v\} \\ & \mathsf{for each } u \ \mathsf{in } \mathrm{Adj}(v) \ \mathsf{do} \\ & \mathsf{decreaseKey}\Big(Q, (u, \min(\mathrm{dist}(s, u), \ \mathrm{dist}(s, v) + \ell(v, u)))\Big). \end{aligned}
```

Priority Queue operations:

- O(n) insert operations
- O(n) extractMin operations
- O(m) decreaseKey operations

Implementing Priority Queues via Heaps

Using Heaps

Store elements in a heap based on the key value

All operations can be done in O(log n) time



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Dijkstra's algorithm can be implemented in $O((n + m) \log n)$ time.



Fibonacci Heaps

- extractMin, insert, delete, meld in O(log n) time
- **decreaseKey** in *O*(1) *amortized* time:

Fibonacci Heaps

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- **2** decreaseKey in O(1) amortized time: ℓ decreaseKey operations for $\ell \ge n$ take together $O(\ell)$ time

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- Relaxed Heaps: decreaseKey in O(1) worst case time but at the expense of meld (not necessary for Dijkstra's algorithm)
- Dijkstra's algorithm can be implemented in O(n log n + m) time.
- Data structures are complicated to analyze/implement. Recent work has obtained data structures that are easier to analyze and implement, and perform well in practice. Rank-Pairing Heaps (European Symposium on Algorithms, September 2009!)

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- Output to recognize the *i*-th closest node? $d'(s, u) = \min(d'(s, u), \operatorname{dist}(s, v) + \ell(v, u))$

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- When to recognize the *i*-th closest node?
 d'(s, u) = min(d'(s, u), dist(s, v) + ℓ(v, u))
 d'(s, u) ≥ d(s, u)

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 - Give us an evaluation order: d'(s, u) only updated when v is added to X, and $u \in Adj(v)$ and $u \in V X$
 - In particular, once a node is in X, d'(s, u) no longer changes as d'(s, u) = d(s, u), and it is never updated again
- **a** How to recognize the *i*-th closest node? $d'(s, u) = min(d'(s, u), \operatorname{dist}(s, v) + \ell(v, u))$ $d'(s, u) \ge d(s, u)$ $d'(s, v) = min_{u \in V-X} d'(s, u) \text{ is the } i\text{-th closest node, and } d'(s, v) = d(s, v)$

Part II

Negative Edges: Bellman-Ford

What are the distances computed by Dijkstra's algorithm?



The distance as computed by Dijkstra algorithm starting from *s*:

- s = 0, x = 5, y = 1, z = 0.
- s = 0, x = 1, y = 2,z = 5.
- s = 0, x = 5, y = 1,z = 2.

IDK.













With negative length edges, Dijkstra's algorithm can fail





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False assumption: Dijkstra's algorithm is based on the assumption that if $s = v_0 \rightarrow v_1 \rightarrow v_2 \ldots \rightarrow v_k$ is a shortest path from s to v_k then $dist(s, v_i) \leq dist(s, v_{i+1})$ for $0 \leq i < k$. Holds true only for non-negative edge lengths.

Anything we can learn from Dijkstra?

 $d'(s, u) = \min(d'(s, u), \operatorname{dist}(s, v) + \ell(v, u))$ • $d'(s, u) \ge d(s, u)$ still true.

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if $s = v_0 \rightarrow v_1 \rightarrow v_2 \ldots \rightarrow v_k$ is a shortest path from s to v_k

- for 1 ≤ i < k: s = v₀ → v₁ → v₂ → ... → v_i is a shortest path from s to v_i, i.e. subpath of a shortest path is still a shortest path.
- Not true: dist(s, v_i) ≤ dist(s, v_{i+1}), the intermediate set is no longer X; in fact, it can be anything

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- if $s = v_0 \rightarrow v_1 \rightarrow v_2 \ldots \rightarrow v_k$ is a shortest path from s to v_k
 - for $1 \leq i < k$: $s = v_0 \rightarrow v_1 \rightarrow v_2 \rightarrow \ldots \rightarrow v_i$ is a shortest path from s to v_i , i.e. subpath of a shortest path is still a shortest path.
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Solution: Update all edges |V| - 1 times!

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```
for each u \in V do
   d(u) \leftarrow \infty
d(s) \leftarrow 0
for k = 1 to n - 1 do
           for each \mathbf{v} \in \mathbf{V} do
                  for each edge (u, v) \in In(v) do
                        d(v) = \min\{d(v), d(u) + \ell(u, v)\}
for each \mathbf{v} \in \mathbf{V} do
           dist(s, v) \leftarrow d(v)
```

Running time: O(mn)

Part III

Bellman-Ford and DP



Shortest Paths and Recursion

- **(**) Compute the shortest path distance from *s* to *t* recursively?
- What are the smaller sub-problems?

Shortest Paths and Recursion

- One of the shortest path distance from s to t recursively?
- What are the smaller sub-problems?

Lemma

Let G be a directed graph with arbitrary edge lengths. If

 $s = v_0 \rightarrow v_1 \rightarrow v_2 \rightarrow \ldots \rightarrow v_k$ is a shortest path from s to v_k then for $1 \leq i < k$:

• $s = v_0 \rightarrow v_1 \rightarrow v_2 \rightarrow \ldots \rightarrow v_i$ is a shortest path from s to v_i

Shortest Paths and Recursion

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Sub-problem idea: paths of fewer hops/edges

Single-source problem: fix source *s*.

d(v, k): shortest path length from s to v using at most k edges.

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Recursion for d(v, k):

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d(v, k): shortest path length from s to v using at most k edges. Note: dist(s, v) = d(v, n - 1).

Recursion for d(v, k):

$$d(v,k) = \min \begin{cases} \min_{u \in ln(v)} (d(u,k-1) + \ell(u,v)). \\ d(v,k-1) \end{cases}$$

Base case: d(s, 0) = 0 and $d(v, 0) = \infty$ for all $v \neq s$.

Example





```
for each \boldsymbol{\mu} \in \boldsymbol{V} do
      d(u,0) \leftarrow \infty
d(s,0) \leftarrow 0
for k = 1 to n - 1 do
            for each \mathbf{v} \in \mathbf{V} do
                  d(v,k) \leftarrow d(v,k-1)
                   for each edge (u, v) \in In(v) do
                         d(v, k) = \min\{d(v, k), d(u, k-1) + \ell(u, v)\}
for each \mathbf{v} \in \mathbf{V} do
            dist(s, v) \leftarrow d(v, n-1)
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Running time:

```
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Running time: O(mn) Space:



Running time: O(mn) Space: $O(n^2)$

```
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for each \mathbf{v} \in \mathbf{V} do
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```

Running time: O(mn) Space: $O(n^2)$ Space can be reduced to O(n).

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```

Running time: O(mn) Space: O(n)

Negative Length Cycles

Definition

A cycle C is a negative length cycle if the sum of the edge lengths of C is negative.



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Shortest Paths and Negative Cycles

Given G = (V, E) with edge lengths and s, t. Suppose

- G has a negative length cycle C, and
- **2** s can reach C and C can reach t.

Question: What is the shortest **distance** from *s* to *t*?



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- G has a negative length cycle C, and
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 $-\infty$

Bellman-Ford: Negative Cycle Detection

Check if distances change in iteration *n*.

```
for each \boldsymbol{\mu} \in \boldsymbol{V} do
    d(u) \leftarrow \infty
d(s) \leftarrow 0
for k = 1 to n - 1 do
           for each \mathbf{v} \in \mathbf{V} do
                 for each edge (u, v) \in In(v) do
                       d(v) = \min\{d(v), d(u) + \ell(u, v)\}
(* One more iteration to check if distances change *)
for each \mathbf{v} \in \mathbf{V} do
     for each edge (u, v) \in In(v) do
           if (d(v) > d(u) + \ell(u, v))
                 Output "Negative Cycle"
for each \mathbf{v} \in \mathbf{V} do
           dist(s, v) \leftarrow d(v)
```

Negative Cycle Detection

Negative Cycle Detection

Given directed graph G with arbitrary edge lengths, does it have a negative length cycle?

Negative Cycle Detection

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Given directed graph G with arbitrary edge lengths, does it have a negative length cycle?

- Bellman-Ford checks whether there is a negative cycle C that is reachable from a specific vertex s. There may negative cycles not reachable from s.
- In Bellman-Ford |V| times, once from each node u?

Negative Cycle Detection

- Add a new node s' and connect it to all nodes of G with zero length edges. Bellman-Ford from s' will find a negative length cycle if there is one. Exercise: why does this work?
- Negative cycle detection can be done with one Bellman-Ford invocation.