## CS/ECE 374: Algorithms \& Models of Computation

## More on SAT <br> Lecture 23 <br> April 29, 2021

## Part I

## Circuit SAT

## Circuits

## Definition

A circuit is a directed acyclic graph with

(1) Input vertices (without incoming edges) labelled with 0,1 or a distinct variable.
(2) Every other vertex is labelled $\vee, \wedge$ or $\neg$.
(3) Single node output vertex with no outgoing edges.

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## CSAT: Circuit Satisfaction

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Given a circuit as input, is there an assignment to the input variables that causes the output to get value 1 ?

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Given a circuit as input, is there an assignment to the input variables that causes the output to get value 1 ?

## Claim

## CSAT is in NP.

(1) Certificate: Assignment to input variables.
(2) Certifier: Evaluate the value of each gate in a topological sort of DAG and check the output gate value.

## Circuit SAT vs SAT

CNF formulas are a rather restricted form of Boolean formulas.

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## Circuit SAT vs SAT

CNF formulas are a rather restricted form of Boolean formulas.
Circuits are a much more powerful (and hence easier) way to express Boolean formulas

However they are equivalent in terms of polynomial-time solvability.

## Theorem

## SAT $\leq_{p} 3$ SAT $\leq_{p}$ CSAT.

Theorem<br>CSAT $\leq_{p}$ SAT $\leq_{p} 3$ SAT.

## Converting a CNF formula into a Circuit

Given 3CNF formulat $\boldsymbol{\varphi}$ with $\boldsymbol{n}$ variables and $\boldsymbol{m}$ clauses, create a Circuit $C$.

- Inputs to $C$ are the $n$ boolean variables $x_{1}, x_{2}, \ldots, x_{n}$
- Use NOT gate to generate literal $\neg x_{i}$ for each variable $x_{i}$
- For each clause ( $\ell_{1} \vee \ell_{2} \vee \ell_{3}$ ) use two OR gates to mimic formula
- Combine the outputs for the clauses using AND gates to obtain the final output


## Example

$$
\varphi=\left(x_{1} \vee \vee x_{3} \vee x_{4}\right) \wedge\left(x_{1} \vee \neg x_{2} \vee \neg x_{3}\right) \wedge\left(\neg x_{2} \vee \neg x_{3} \vee x_{4}\right)
$$

## Converting a circuit into a CNF formula


(A) Input circuit

(B) Label the nodes.

## Converting a circuit into a CNF formula


(B) Label the nodes.

(C) Introduce var for each node.

## Converting a circuit into a CNF formula

$x_{k} \quad$ (Demand a sat' assignment!)


$$
x_{j}=x_{g} \wedge x_{h}
$$

$$
x_{g}=x_{b} \vee x_{c}
$$

(C) Introduce var for each node.

$$
x_{k}=x_{i} \wedge x_{j}
$$

$$
x_{i}=\neg x_{f}
$$

$$
x_{h}=x_{d} \vee x_{e}
$$

$$
x_{f}=x_{a} \wedge x_{b}
$$

$$
x_{d}=0
$$

$$
x_{a}=1
$$

(D) Write a sub-formula for each variable that is true if the var is computed correctly.

## Converting a circuit into a CNF formula

## CNF

| $x_{k}$ | $x_{k}$ |
| :---: | :---: |
| $x_{k}=x_{i} \wedge x_{j}$ | $\left(\neg x_{k} \vee x_{i}\right) \wedge\left(\neg x_{k} \vee x_{j}\right) \wedge\left(x_{k} \vee \neg x_{i} \vee \neg x_{j}\right)$ |
| $x_{j}=x_{g} \wedge x_{h}$ | $\left(\neg x_{j} \vee x_{g}\right) \wedge\left(\neg x_{j} \vee x_{h}\right) \wedge\left(x_{j} \vee \neg x_{g} \vee \neg x_{h}\right)$ |
| $x_{i}=\neg x_{f}$ | $\left(x_{i} \vee x_{f}\right) \wedge\left(\neg x_{i} \vee \neg x_{f}\right)$ |
| $x_{h}=x_{d} \vee x_{e}$ | $\left(x_{h} \vee \neg x_{d}\right) \wedge\left(x_{h} \vee \neg x_{e}\right) \wedge\left(\neg x_{h} \vee x_{d} \vee x_{e}\right)$ |
| $x_{g}=x_{b} \vee x_{c}$ | $\left(x_{g} \vee \neg x_{b}\right) \wedge\left(x_{g} \vee \neg x_{c}\right) \wedge\left(\neg x_{g} \vee x_{b} \vee x_{c}\right)$ |
| $x_{f}=x_{a} \wedge x_{b}$ | $\left(\neg x_{f} \vee x_{a}\right) \wedge\left(\neg x_{f} \vee x_{b}\right) \wedge\left(x_{f} \vee \neg x_{a} \vee \neg x_{b}\right)$ |
| $x_{d}=0$ | $\neg x_{d}$ |
| $x_{a}=1$ | $x_{a}$ |

## Converting a circuit into a CNF formula

## CNF



We got a CNF formula that is satisfiable if and only if the original circuit is satisfiable.

## Reduction: CSAT $\leq_{P}$ SAT

(1) For each gate (vertex) $v$ in the circuit, create a variable $\boldsymbol{x}_{v}$
(2) Case $\neg: ~ v$ is labeled $\neg$ and has one incoming edge from $\boldsymbol{u}$ (so $\left.x_{v}=\neg x_{u}\right)$. In SAT formula generate, add clauses $\left(x_{u} \vee x_{v}\right)$, $\left(\neg x_{u} \vee \neg x_{v}\right)$. Observe that

$$
x_{v}=\neg x_{u} \text { is true } \Longleftrightarrow \begin{aligned}
& \left(x_{u} \vee x_{v}\right) \\
& \left(\neg x_{u} \vee \neg x_{v}\right)
\end{aligned} \text { both true. }
$$

## Reduction: CSAT $\leq_{P}$ SAT

(1) Case $\vee$ : So $x_{v}=x_{u} \vee x_{w}$. In SAT formula generated, add clauses $\left(x_{v} \vee \neg x_{u}\right),\left(x_{v} \vee \neg x_{w}\right)$, and $\left(\neg x_{v} \vee x_{u} \vee x_{w}\right)$. Again, observe that

$$
\left(x_{v}=x_{u} \vee x_{w}\right) \text { is true } \Longleftrightarrow \begin{aligned}
& \left(x_{v} \vee \neg x_{u}\right), \\
& \left(x_{v} \vee \neg x_{w}\right), \\
& \left(\neg x_{v} \vee x_{u} \vee x_{w}\right)
\end{aligned} \quad \text { all true. }
$$

## Reduction: CSAT $\leq_{P}$ SAT

(1) Case $\wedge$ : So $x_{v}=x_{u} \wedge x_{w}$. In SAT formula generated, add clauses $\left(\neg x_{v} \vee x_{u}\right)$, $\left(\neg x_{v} \vee x_{w}\right)$, and $\left(x_{v} \vee \neg x_{u} \vee \neg x_{w}\right)$. Again observe that

$$
x_{v}=x_{u} \wedge x_{w} \text { is true } \Longleftrightarrow \begin{aligned}
& \left(\neg x_{v} \vee x_{u}\right), \\
& \left(\neg x_{v} \vee x_{w}\right), \\
& \left(x_{v} \vee \neg x_{u} \vee \neg x_{w}\right)
\end{aligned} \quad \text { all true. }
$$

## Reduction: CSAT $\leq_{P}$ SAT

(1) If $v$ is an input gate with a fixed value then we do the following. If $x_{v}=1$ add clause $x_{v}$. If $x_{v}=0$ add clause $\neg x_{v}$
(2) Add the clause $x_{v}$ where $v$ is the variable for the output gate

## Correctness of Reduction

Need to show circuit $C$ is satisfiable iff $\varphi_{C}$ is satisfiable
$\Rightarrow$ Consider a satisfying assignment $a$ for $C$
(1) Find values of all gates in $\boldsymbol{C}$ under $\boldsymbol{a}$
(2) Give value of gate $\boldsymbol{v}$ to variable $\boldsymbol{x}_{\boldsymbol{v}}$; call this assignment $\boldsymbol{a}^{\prime}$
(3) $a^{\prime}$ satisfies $\varphi_{C}$ (exercise)
$\Leftarrow$ Consider a satisfying assignment a for $\varphi_{C}$
(1) Let $\boldsymbol{a}^{\prime}$ be the restriction of $\boldsymbol{a}$ to only the input variables
(2) Value of gate $\boldsymbol{v}$ under $\boldsymbol{a}^{\prime}$ is the same as value of $\boldsymbol{x}_{\boldsymbol{v}}$ in $\boldsymbol{a}$
(3) Thus, $\boldsymbol{a}^{\prime}$ satisfies $C$

## Part II

## SAT reduces to 3-SAT

## SAT $\leq_{P}$ 3SAT

## How SAT is different from 3SAT?

In SAT clauses might have arbitrary length: $1,2,3, \ldots$ variables:

$$
(x \vee y \vee z \vee w \vee u) \wedge(\neg x \vee \neg y \vee \neg z \vee w \vee u) \wedge(\neg x)
$$

In 3SAT every clause must have exactly 3 different literals.

## SAT $\leq_{p}$ 3SAT

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$$

In 3SAT every clause must have exactly 3 different literals.
To reduce from an instance of SAT to an instance of 3SAT, we must make all clauses to have exactly 3 variables...

## Basic idea

(1) Pad short clauses so they have 3 literals.
(2) Break long clauses into shorter clauses.
( Repeat the above till we have a 3CNF.

## $3 S A T \leq_{P}$ SAT

(1) 3 SAT $\leq_{P}$ SAT .
(2) Because...

A 3SAT instance is also an instance of SAT.

## SAT $\leq_{P}$ 3SAT

## Claim

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## Claim

## SAT $\leq_{p} 3 S A T$.

Given $\varphi$ a SAT formula we create a 3SAT formula $\varphi^{\prime}$ such that (1) $\varphi$ is satisfiable iff $\varphi^{\prime}$ is satisfiable.
(2) $\varphi^{\prime}$ can be constructed from $\varphi$ in time polynomial in $|\varphi|$.

## SAT $\leq_{P}$ 3SAT

## Claim

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Given $\varphi$ a SAT formula we create a 3SAT formula $\varphi^{\prime}$ such that
(1) $\varphi$ is satisfiable iff $\varphi^{\prime}$ is satisfiable.
(2) $\varphi^{\prime}$ can be constructed from $\varphi$ in time polynomial in $|\varphi|$.

Idea: if a clause of $\varphi$ is not of length 3 , replace it with several clauses of length exactly 3.

## SAT $\leq_{P}$ 3SAT

## Reduction Ideas: clause with 2 literals

(1) Case clause with 2 literals: Let $\boldsymbol{c}=\boldsymbol{\ell}_{1} \vee \boldsymbol{\ell}_{2}$. Let $\boldsymbol{u}$ be a new variable. Consider

$$
c^{\prime}=\left(\ell_{1} \vee \ell_{2} \vee u\right) \wedge\left(\ell_{1} \vee \ell_{2} \vee \neg u\right)
$$

(2) Suppose $\varphi=\psi \wedge c$. Then $\varphi^{\prime}=\psi \wedge c^{\prime}$ is satisfiable iff $\varphi$ is satisfiable.

## SAT $\leq_{P}$ 3SAT

## Reduction Ideas: clause with 1 literal

(1) Case clause with one literal: Let $\boldsymbol{c}$ be a clause with a single literal (i.e., $\boldsymbol{c}=\boldsymbol{\ell}$ ). Let $\boldsymbol{u}, \boldsymbol{v}$ be new variables. Consider

$$
\begin{aligned}
c^{\prime}= & (\ell \vee u \vee v) \wedge(\ell \vee u \vee \neg v) \\
& \wedge(\ell \vee \neg u \vee v) \wedge(\ell \vee \neg u \vee \neg v) .
\end{aligned}
$$

(2) Suppose $\varphi=\psi \wedge c$. Then $\varphi^{\prime}=\psi \wedge c^{\prime}$ is satisfiable iff $\varphi$ is satisfiable.

## SAT $\leq_{P}$ 3SAT

## Reduction Ideas: clause with more than 3 literals

(1) Case clause with five literals: Let $c=\ell_{1} \vee \ell_{2} \vee \ell_{3} \vee \ell_{4} \vee \ell_{5}$. Let $\boldsymbol{u}$ be a new variable. Consider

$$
c^{\prime}=\left(\ell_{1} \vee \ell_{2} \vee \ell_{3} \vee u\right) \wedge\left(\ell_{4} \vee \ell_{5} \vee \neg u\right)
$$

(2) Suppose $\varphi=\psi \wedge c$. Then $\varphi^{\prime}=\psi \wedge c^{\prime}$ is satisfiable iff $\varphi$ is satisfiable.

## SAT $\leq_{P}$ 3SAT

## Reduction Ideas: clause with more than 3 literals

(1) Case clause with $\boldsymbol{k}>3$ literals: Let $\boldsymbol{c}=\ell_{1} \vee \ell_{2} \vee \ldots \vee \ell_{\boldsymbol{k}}$. Let $\boldsymbol{u}$ be a new variable. Consider

$$
c^{\prime}=\left(\ell_{1} \vee \ell_{2} \ldots \ell_{k-2} \vee u\right) \wedge\left(\ell_{k-1} \vee \ell_{k} \vee \neg u\right)
$$

(2) Suppose $\varphi=\psi \wedge c$. Then $\varphi^{\prime}=\psi \wedge c^{\prime}$ is satisfiable iff $\varphi$ is satisfiable.

## Breaking a clause

## Lemma

For any boolean formulas $X$ and $Y$ and $z$ a new boolean variable. Then

$$
X \vee Y \text { is satisfiable }
$$

if and only if, $z$ can be assigned a value such that

$$
(X \vee z) \wedge(Y \vee \neg z) \text { is satisfiable }
$$

(with the same assignment to the variables appearing in $X$ and $Y$ ).

## SAT $\leq_{P}$ SAT $($ contd $)$

Let $\boldsymbol{c}=\boldsymbol{\ell}_{1} \vee \cdots \vee \boldsymbol{\ell}_{\boldsymbol{k}}$. Let $\boldsymbol{u}_{1}, \ldots \boldsymbol{u}_{\boldsymbol{k}-3}$ be new variables. Consider

$$
\begin{aligned}
c^{\prime}= & \left(\ell_{1} \vee \ell_{2} \vee u_{1}\right) \wedge\left(\ell_{3} \vee \neg u_{1} \vee u_{2}\right) \\
& \wedge\left(\ell_{4} \vee \neg u_{2} \vee u_{3}\right) \wedge \\
& \cdots \wedge\left(\ell_{k-2} \vee \neg u_{k-4} \vee u_{k-3}\right) \wedge\left(\ell_{k-1} \vee \ell_{k} \vee \neg u_{k-3}\right)
\end{aligned}
$$

## Claim

$\varphi=\psi \wedge c$ is satisfiable jiff $\varphi^{\prime}=\psi \wedge c^{\prime}$ is satisfiable.
Another way to see it - reduce size of clause by one:

$$
c^{\prime}=\left(\ell_{1} \vee \ell_{2} \ldots \vee \ell_{k-2} \vee u_{k-3}\right) \wedge\left(\ell_{k-1} \vee \ell_{k} \vee \neg u_{k-3}\right)
$$

## An Example

## Example

$$
\begin{aligned}
\varphi= & \left(\neg x_{1} \vee \neg x_{4}\right) \wedge\left(x_{1} \vee \neg x_{2} \vee \neg x_{3}\right) \\
& \wedge\left(\neg x_{2} \vee \neg x_{3} \vee x_{4} \vee x_{1}\right) \wedge\left(x_{1}\right)
\end{aligned}
$$

Equivalent form:

$$
\psi=\left(\neg x_{1} \vee \neg x_{4} \vee z\right) \wedge\left(\neg x_{1} \vee \neg x_{4} \vee \neg z\right)
$$

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\end{aligned}
$$

Equivalent form:

$$
\begin{aligned}
\psi= & \left(\neg x_{1} \vee \neg x_{4} \vee z\right) \wedge\left(\neg x_{1} \vee \neg x_{4} \vee \neg z\right) \\
& \wedge\left(x_{1} \vee \neg x_{2} \vee \neg x_{3}\right)
\end{aligned}
$$

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$$
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$$

Equivalent form:

$$
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& \wedge\left(x_{1} \vee \neg x_{2} \vee \neg x_{3}\right) \\
& \wedge\left(\neg x_{2} \vee \neg x_{3} \vee y_{1}\right) \wedge\left(x_{4} \vee x_{1} \vee \neg y_{1}\right)
\end{aligned}
$$

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$$
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& \wedge\left(x_{1} \vee \neg x_{2} \vee \neg x_{3}\right) \\
& \wedge\left(\neg x_{2} \vee \neg x_{3} \vee y_{1}\right) \wedge\left(x_{4} \vee x_{1} \vee \neg y_{1}\right) \\
& \wedge\left(x_{1} \vee u \vee v\right) \wedge\left(x_{1} \vee u \vee \neg v\right) \\
& \wedge\left(x_{1} \vee \neg u \vee v\right) \wedge\left(x_{1} \vee \neg u \vee \neg v\right)
\end{aligned}
$$

## Overall Reduction Algorithm

```
ReduceSATTo3SAT ( }\varphi\mathrm{ ):
    // \varphi: CNF formula.
    for each clause c of \varphi do
        if c does not have exactly 3 literals then
        construct c' as before
        else
        c
    \psi is conjunction of all c' constructed in loop
    return Solver3SAT( }\psi\mathrm{ )
```


## Correctness (informal)

$\varphi$ is satisfiable iff $\psi$ is satisfiable because for each clause $\boldsymbol{c}$, the new 3 CNF formula $\boldsymbol{c}^{\prime}$ is logically equivalent to $\boldsymbol{c}$.

## Part III

## Reducing Problems to SAT and Circuit SAT

## Power of SAT and CSAT

SAT and CSAT are meta-problems
Allow us to express/model problem using constraints. In essense they allow programming with constraints of certain restricted type.

Goal: examples to drive home the point

## Reduce Directed Hamilton Path to SAT

Given directed graph $G=(\boldsymbol{V}, \boldsymbol{E})$, does it have a Hamilton path?
Given $G$ obtain CNF formula $\varphi_{G}$ such that $G$ has a Hamilton Path iff $\varphi_{G}$ is satisfiable

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Alternative view: Program/express using constraints

- What are variables?
- What are the constraints?


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Alternative view: Program/express using constraints

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One approach: $G$ has a Hamilton path iff there is a permutation of the $\boldsymbol{n}$ vertices such that for each $\boldsymbol{i}$ there is an edge from vertex in position $\boldsymbol{i}$ to vertex in position $(\boldsymbol{i}+1)$

How do we express permutations?

## Reduction continued

Define variable $\boldsymbol{x}(\boldsymbol{u}, \boldsymbol{i})$ if vertex $\boldsymbol{u}$ in position $\boldsymbol{i}$ in the permutation. Total of $\boldsymbol{n}^{2}$ variables where $\boldsymbol{n}=|\boldsymbol{V}|$.

Constraints?

- For each $\boldsymbol{u}$, exactly one of $\boldsymbol{x}(\boldsymbol{u}, 1), \boldsymbol{x}(\boldsymbol{u}, 2), \ldots, \boldsymbol{x}(\boldsymbol{u}, \boldsymbol{n})$ should be true


## Reduction continued

Define variable $\boldsymbol{x}(\boldsymbol{u}, \boldsymbol{i})$ if vertex $\boldsymbol{u}$ in position $\boldsymbol{i}$ in the permutation. Total of $\boldsymbol{n}^{2}$ variables where $\boldsymbol{n}=|\boldsymbol{V}|$.

Constraints?

- For each $\boldsymbol{u}$, exactly one of $\boldsymbol{x}(\boldsymbol{u}, 1), \boldsymbol{x}(\boldsymbol{u}, 2), \ldots, \boldsymbol{x}(\boldsymbol{u}, \boldsymbol{n})$ should be true
- $\bigvee_{\boldsymbol{i}=1}^{\boldsymbol{n}} \boldsymbol{x}(\boldsymbol{u}, \boldsymbol{i})$ to ensure that $\boldsymbol{x}(\boldsymbol{u}, \boldsymbol{i})$ is 1 for at least one $\boldsymbol{i}$
- For $\boldsymbol{i} \neq \boldsymbol{j}$ we add constraint $\neg \boldsymbol{x}(\boldsymbol{u}, \boldsymbol{i}) \vee \neg \boldsymbol{x}(\boldsymbol{u}, \boldsymbol{j})$ to ensure that we cannot choose both to be 1 for any pair.
- For each $\boldsymbol{u}$ we have a total of $(1+\boldsymbol{n}(\boldsymbol{n}-1) / 2)$ constraints. Total of $\boldsymbol{n}(1+\boldsymbol{n}(\boldsymbol{n}-1) / 2)$ over all vertices.
- $\boldsymbol{x}(\boldsymbol{u}, \boldsymbol{i})$ and $\boldsymbol{x}(\boldsymbol{v}, \boldsymbol{i}+1)$ implies edge $(\boldsymbol{u}, \boldsymbol{v})$ in $E(\boldsymbol{G})$


## Reduction continued

Define variable $\boldsymbol{x}(\boldsymbol{u}, \boldsymbol{i})$ if vertex $\boldsymbol{u}$ in position $\boldsymbol{i}$ in the permutation. Total of $\boldsymbol{n}^{2}$ variables where $\boldsymbol{n}=|\boldsymbol{V}|$.

## Constraints?

- For each $\boldsymbol{u}$, exactly one of $\boldsymbol{x}(\boldsymbol{u}, 1), \boldsymbol{x}(\boldsymbol{u}, 2), \ldots, \boldsymbol{x}(\boldsymbol{u}, \boldsymbol{n})$ should be true
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- $\boldsymbol{x}(\boldsymbol{u}, \boldsymbol{i})$ and $\boldsymbol{x}(\boldsymbol{v}, \boldsymbol{i}+1)$ implies edge $(\boldsymbol{u}, \boldsymbol{v})$ in $E(\boldsymbol{G})$
$(x(u, i) \wedge x(v, i+1)) \Rightarrow z(u, v)$ where $z(u, v)$ is 1 if
$(u, v) \in E$ otherwise $0(z(u, v)$ is a constant, not a variable but to help notation). Convert implication constraint to CNF.


## Vertex Cover to CSAT

Given graph $\boldsymbol{G}=(\boldsymbol{V}, \boldsymbol{E})$ and integer $\boldsymbol{k}$, does $\boldsymbol{G}$ have a vertex cover of size at most $k$ ?

Recall $S \subseteq \boldsymbol{V}$ is a vertex cover if each edge $(\boldsymbol{u}, \boldsymbol{v})$ is covered by $S$, that means $u \in S$ or $v \in S$.

How do we reduce to CSAT/SAT? What are the variables?

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How do we reduce to CSAT/SAT? What are the variables?
$x_{u}, u \in V$ to indicate whether we choose $u$
Constraints?

- For each edge $(u, v) \in E$ a constraint $\left(x_{u} \vee x_{v}\right)$. Total of $|E|$ constraints.


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How do we reduce to CSAT/SAT? What are the variables?
$x_{u}, u \in V$ to indicate whether we choose $u$
Constraints?

- For each edge $(u, v) \in E$ a constraint $\left(x_{u} \vee x_{v}\right)$. Total of $|E|$ constraints.
- $\sum_{u \in V} x_{u} \leq k$. Not a boolean constraint! How?


## Vertex Cover to CSAT

Expressing $\sum_{\boldsymbol{u} \in \boldsymbol{V}} \boldsymbol{x}_{\boldsymbol{u}} \leq \boldsymbol{k}$ as a circuit.

- Given inputs $\boldsymbol{x}_{\boldsymbol{u}}, \boldsymbol{u} \in \boldsymbol{V}$ can create an addition circuit that outputs the sum $\sum_{\boldsymbol{u}} x_{\boldsymbol{u}}$ as a $\lceil\log n\rceil$ bit binary number
- Given two $r$-bit binary inputs $y_{1}, y_{2}, \ldots, y_{r}$ and $z_{1}, z_{2}, \ldots, z_{r}$ one can develop a boolean circuit to compare which one is greater
- Hence circuit to do $\sum_{\boldsymbol{u}} \boldsymbol{x}_{\boldsymbol{u}}$ and compare output to input integer $k$ written in binary


## Vertex Cover to CSAT

Expressing $\sum_{\boldsymbol{u} \in \boldsymbol{V}} \boldsymbol{x}_{\boldsymbol{u}} \leq \boldsymbol{k}$ as a circuit.

- Given inputs $\boldsymbol{x}_{\boldsymbol{u}}, \boldsymbol{u} \in \boldsymbol{V}$ can create an addition circuit that outputs the sum $\sum_{\boldsymbol{u}} x_{\boldsymbol{u}}$ as a $\lceil\log n\rceil$ bit binary number
- Given two $r$-bit binary inputs $y_{1}, y_{2}, \ldots, y_{r}$ and $z_{1}, z_{2}, \ldots, z_{r}$ one can develop a boolean circuit to compare which one is greater
- Hence circuit to do $\sum_{\boldsymbol{u}} \boldsymbol{x}_{\boldsymbol{u}}$ and compare output to input integer $k$ written in binary

Combine with the constraints to cover edges to obtain a CSAT instance with input variables $\boldsymbol{x}_{\boldsymbol{u}}, \boldsymbol{u} \in V$

## Cook-Levin Theorem

## Theorem (Cook-Levin)

## SAT is NP-Complete.

How did they prove it? And why SAT or CSAT?
Proof is in retrospect simple.

- Fix any non-deterministic TM $M$ and string $w$
- Does $M$ accept $\boldsymbol{w}$ in $\boldsymbol{p}(|\boldsymbol{w}|)$ steps where $\boldsymbol{p}()$ is some fixed polynomial?
- Can express computation of $M$ on $w$ using a polynomial sized circuit (or CNF formula) due to expressive power of constraints and local computation of TMs
- Thus, can reduce an arbitrary NP problem (since it corresponds to some non-deterministic poly-time TM M) to SAT


## Mathematical Programming

SAT, CSAT are boolean constraint satisfaction problems.
Other frameworks: constraints involving linear inequalities, convex functions, polynomials etc

Useful to know: Integer Linear Programming (ILP), Linear Programming (LP), Mixed Integer Linear Programming (MIP), Convex Programming

Commercial packages available. ILP, MIP are NP-Hard but many small to medium problems can be solved in practice. Powerful and expressive constraint involving numbers, not just booleans.

## Linear Programming

## Problem

Real variables $x_{1}, x_{2}, \ldots, x_{n}$. Solve

$$
\begin{array}{ll}
\text { maximize/minimize } & \sum_{j=1}^{n} c_{j} x_{j} \\
\text { subject to } & \sum_{j=1}^{n} a_{i j} x_{j} \leq b_{i} \quad \text { for } i=1 \ldots p \\
& \sum_{j=1}^{n} a_{i j} x_{j}=b_{i} \quad \text { for } i=p+1 \ldots \boldsymbol{q} \\
& \sum_{j=1}^{n} a_{i j} x_{j} \geq b_{i} \quad \text { for } i=q+1 \ldots m
\end{array}
$$

Input is matrix $\boldsymbol{A}=\left(a_{i j}\right) \in \mathbb{R}^{\boldsymbol{m} \times \boldsymbol{n}}$, column vector $\boldsymbol{b}=\left(\boldsymbol{b}_{\boldsymbol{i}}\right) \in \mathbb{R}^{\boldsymbol{m}}$, and row vector $\boldsymbol{c}=\left(\boldsymbol{c}_{\boldsymbol{j}}\right) \in \mathbb{R}^{\boldsymbol{n}}$

Constraints are linear equations and inequalities. Objective is a linear function

## Integer Linear Programming

## Problem

Integer variables $x_{1}, x_{2}, \ldots, x_{n}$. Solve

$$
\begin{array}{lll}
\operatorname{maximize} / \text { minimize } & \sum_{j=1}^{n} c_{j} x_{j} & \\
\text { subject to } & \sum_{j=1}^{n} a_{i j} x_{j} \leq b_{i} \text { for } \boldsymbol{i}=1 \ldots \boldsymbol{p} \\
& \sum_{j=1}^{n} a_{i j} x_{j}=b_{i} \text { for } \boldsymbol{i}=\boldsymbol{p + 1 \ldots \boldsymbol { q }} \\
& \sum_{j=1}^{n} a_{i j} x_{j} \geq b_{i} & \text { for } i=\boldsymbol{q}+1 \ldots \boldsymbol{n} \\
& x_{i} \in \mathbb{Z} & \text { for } i=1 \text { to } \boldsymbol{d}
\end{array}
$$

Input is matrix $\boldsymbol{A}=\left(\boldsymbol{a}_{i j}\right) \in \mathbb{R}^{\boldsymbol{m} \times \boldsymbol{n}}$, column vector $\boldsymbol{b}=\left(\boldsymbol{b}_{\boldsymbol{i}}\right) \in \mathbb{R}^{\boldsymbol{m}}$, and row vector $\boldsymbol{c}=\left(\boldsymbol{c}_{j}\right) \in \mathbb{R}^{\boldsymbol{n}}$

Constraints are linear equations and inequalities. Objective is a linear function but variables need to take integer values

## Convex Programming

Problem

Real variables $x_{1}, x_{2}, \ldots, x_{n} . x \in \mathbb{R}^{\boldsymbol{n}}$ Solve

$$
\operatorname{minimize} \quad f(x)
$$

subject to $g_{i}(x) \leq b_{i}$ for $\boldsymbol{i}=1 \ldots m$
$\boldsymbol{f}, \boldsymbol{g}_{1}, \boldsymbol{g}_{2}, \ldots, \boldsymbol{g}_{\boldsymbol{m}}$ are convex functions

## Mathematical Programming

- LP is a specical case of Convex Programming
- LP can be solved in polynomial time
- Convex programs can be solved arbitrarily well in polynomial time (exact solution is tricky because of irrational solutions)
- ILP and MIP are NP-Hard (decision versions are NP-Complete).


## Mathematical Programming

- LP is a specical case of Convex Programming
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Why is convex programming solvable?

- For convex programs, local optimum is a global optimum!
- Local optimum can be found by local search! Gradient descent! Even for non-convex programs
- Gradient descent doesn't give a poly-time algorithm (gives a pseudo-polytime algorithm) but shows why efficiency is possible.


## Interplay of Discrete and Continuous Optimization

Both are fundamental and important and interplay has lot of impact!

- Machine learning: (deep) learning uses continuous optimization to train neural networks for classification and other discrete tasks
- Combinatorial optimization: use LP/SDP and other convex programming methods to solve combinatorial problems
- Scientific and numerical computing
- Statistics

