

## **NP** and **NP** Completeness

### Lecture 23

Tuesday, November 29, 2022

## 23.1

### NP-Completeness: Cook-Levin Theorem

## 23.1.1

### Completeness

# NP: Non-deterministic polynomial

## Definition 23.1.

A decision problem is in **NP**, if it has a polynomial time certifier, for all the all the YES instances.

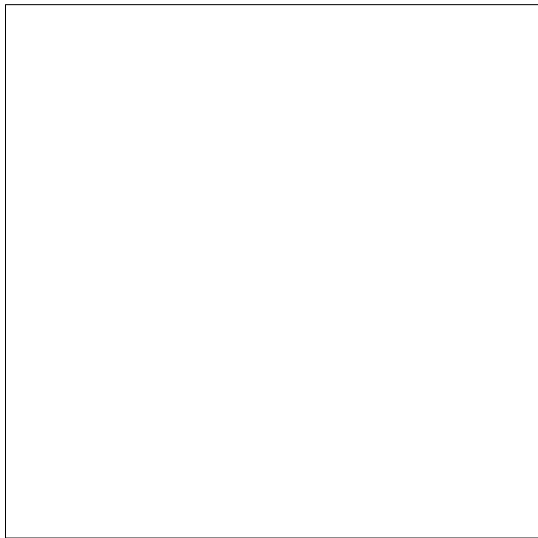
## Definition 23.2.

A decision problem is in **co-NP**, if it has a polynomial time certifier, for all the all the NO instances.

## Example 23.3.

1. **3SAT** is in **NP**.
2. But **Not3SAT** is in **co-NP**.

In the beginning...



In the beginning...

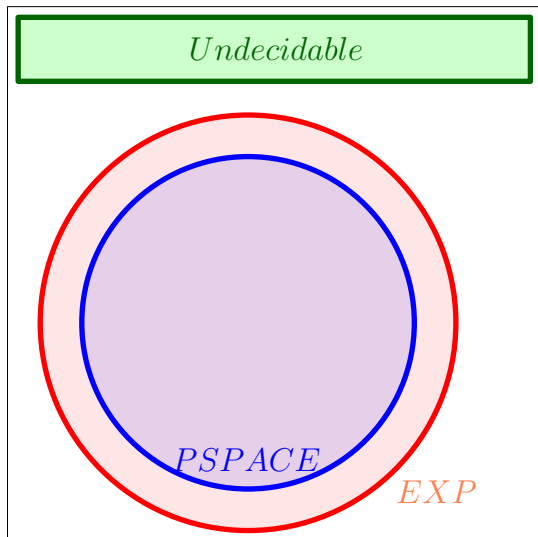
*Undecidable*

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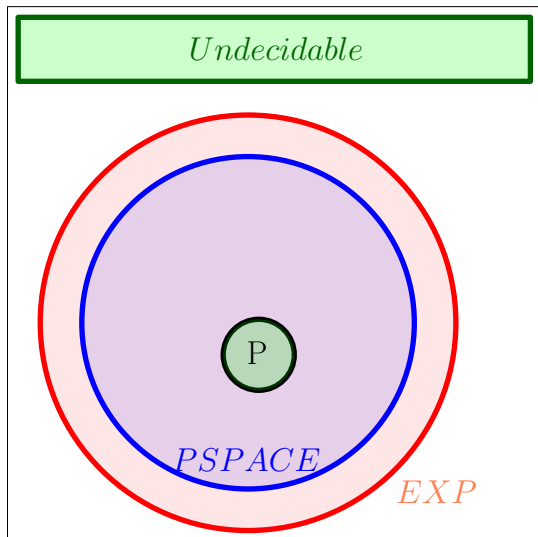
*EXP*

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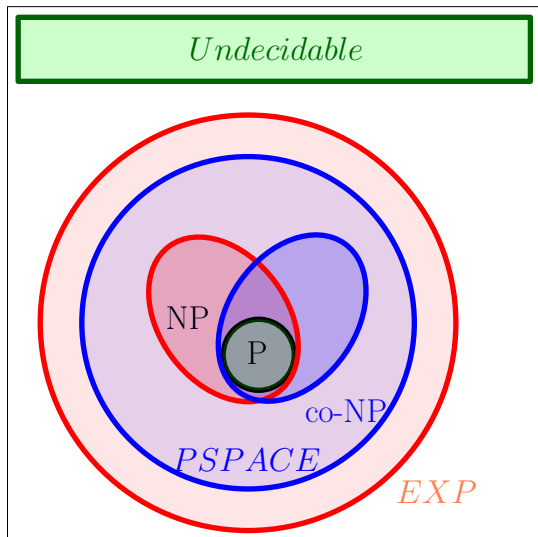




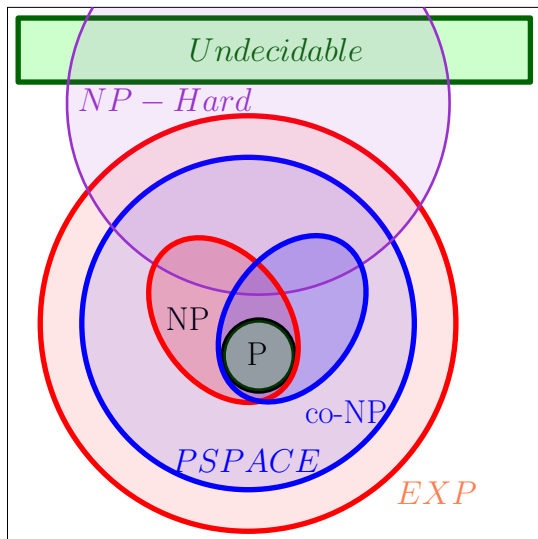
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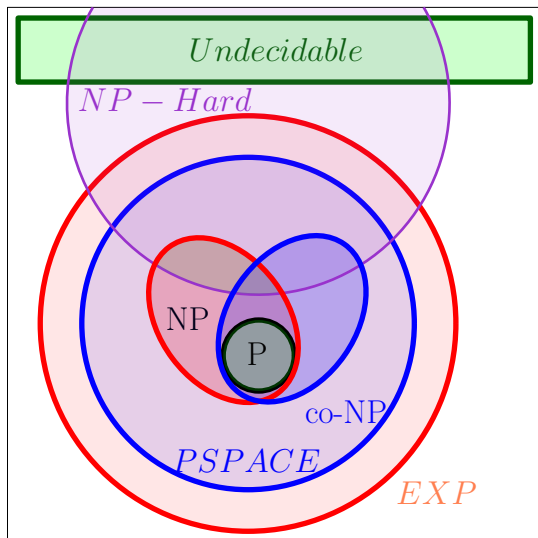
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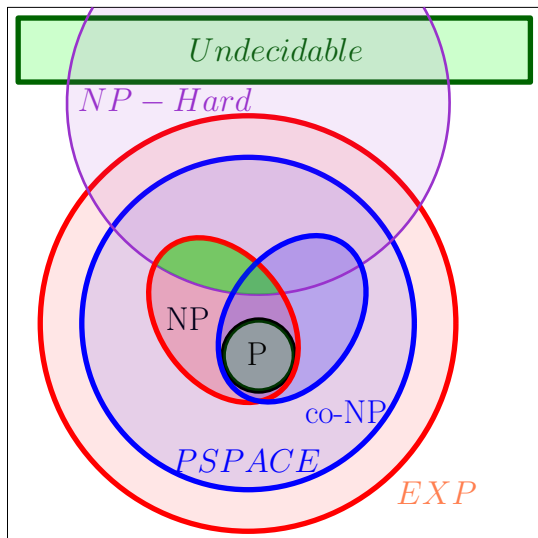
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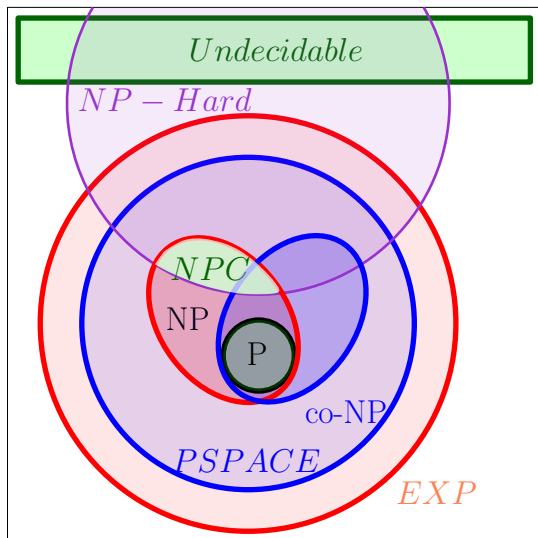
In the beginning...



In the beginning...



In the beginning...



# “Hardest” Problems

## Question

What is the hardest problem in **NP**? How do we define it?

## Towards a definition

1. Hardest problem must be in **NP**.
2. Hardest problem must be at least as “difficult” as every other problem in **NP**.

# NP-Complete Problems

## Definition 23.4.

A problem  $X$  is said to be **NP-Complete** if

1.  $X \in \mathbf{NP}$ , and
2. (Hardness) For any  $Y \in \mathbf{NP}$ ,  $Y \leq_P X$ .



# Solving NP-Complete Problems

## Proposition 23.5.

Suppose  $X$  is NP-Complete. Then  $X$  can be solved in polynomial time  $\iff P = NP$ .

### Proof.

$\Rightarrow$  Suppose  $X$  can be solved in polynomial time

0.1 Let  $Y \in NP$ . We know  $Y \leq_P X$ .

0.2 We showed that if  $Y \leq_P X$  and  $X$  can be solved in polynomial time, then  $Y$  can be solved in polynomial time.

0.3 Thus, every problem  $Y \in NP$  is such that  $Y \in P$ .

0.4  $\implies NP \subseteq P$ .

0.5 Since  $P \subseteq NP$ , we have  $P = NP$ .

$\Leftarrow$  Since  $P = NP$ , and  $X \in NP$ , we have a polynomial time algorithm for  $X$ .  $\square$

# NP-Hard Problems

## Definition 23.6.

A problem **X** is said to be **NP-Hard** if

1. (**Hardness**) For any **Y**  $\in$  **NP**, we have that **Y**  $\leq_P$  **X**.

An **NP-Hard** problem need not be in **NP**!

**Example:** Halting problem is **NP-Hard** (why?) but not **NP-Complete**.

# Consequences of proving **NP-Completeness**

If **X** is **NP-Complete**

1. Since we believe **P**  $\neq$  **NP**,
2. and solving **X** implies **P** = **NP**.

**X** is **unlikely** to be efficiently solvable.

At the very least, many smart people before you have failed to find an efficient algorithm for **X**.

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## 23.1.2

### SAT is NP-Complete

# NP-Complete Problems

## Question

Are there any problems that are **NP-Complete**?

## Answer

Yes! Many, many problems are **NP-Complete**.



# Cook-Levin Theorem

## Theorem 23.7 (Cook-Levin).

**SAT** is **NP-Complete**.

Need to show

1. **SAT** is in **NP**.
2. every **NP** problem **X** reduces in polynomial time to **SAT**.

Might see proof later...

Steve Cook won the Turing award for his theorem.

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### Other NP Complete Problems

# Proving that a problem **X** is **NP-Complete**

To prove **X** is **NP-Complete**, show

1. Show that **X** is in **NP**.
2. Give a polynomial-time reduction from a known **NP-Complete** problem such as **SAT** to **X**

**SAT**  $\leq_P$  **X** implies that every **NP** problem **Y**  $\leq_P$  **X**. Why?

Transitivity of reductions:

**Y**  $\leq_P$  **SAT** and **SAT**  $\leq_P$  **X** and hence **Y**  $\leq_P$  **X**.

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## 3-SAT is NP-Complete

- ▶ 3-SAT is in NP
- ▶  $\text{SAT} \leq_P \text{3-SAT}$  as we saw

# NP-Completeness via Reductions

1. **SAT** is **NP-Complete** due to Cook-Levin theorem
2. **SAT**  $\leq_P$  **3-SAT**
3. **3-SAT**  $\leq_P$  **Independent Set**
4. **Independent Set**  $\leq_P$  **Vertex Cover**
5. **Independent Set**  $\leq_P$  **Clique**
6. **3-SAT**  $\leq_P$  **3-Color**
7. **3-SAT**  $\leq_P$  **Hamiltonian Cycle**

Hundreds and thousands of different problems from many areas of science and engineering have been shown to be **NP-Complete**.

A surprisingly frequent phenomenon!



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## 23.2

### Reducing **3-SAT** to Independent Set

# Independent Set

**Problem:** Independent Set

**Instance:** A graph  $G$ , integer  $k$ .

**Question:** Is there an independent set in  $G$  of size  $k$ ?

Lemma 23.1.

Independent set *is in* NP.

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**Lemma 23.1.**

**Independent set** *is in* **NP**.

# 3SAT $\leq_P$ Independent Set

## The reduction 3SAT $\leq_P$ Independent Set

**Input:** Given a 3CNF formula  $\varphi$

**Goal:** Construct a graph  $G_\varphi$  and number  $k$  such that  $G_\varphi$  has an independent set of size  $k$  if and only if  $\varphi$  is satisfiable.

$G_\varphi$  should be constructable in time polynomial in size of  $\varphi$

**Importance of reduction:** Although 3SAT is much more expressive, it can be reduced to a seemingly specialized Independent Set problem.

**Notice:** We handle only 3CNF formulas – reduction would not work for other kinds of boolean formulas.

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# Interpreting 3SAT

There are two ways to think about **3SAT**

1. Find a way to assign 0/1 (false/true) to the variables such that the formula evaluates to true, that is each clause evaluates to true.
2. Pick a literal from each clause and find a truth assignment to make all of them true  
You will fail if two of the literals you pick are in **conflict**, i.e., you pick  $x_i$  and  $\neg x_i$

We will take the second view of **3SAT** to construct the reduction.



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# The Reduction

1.  $G_\varphi$  will have one vertex for each literal in a clause
2. Connect the 3 literals in a clause to form a triangle; the independent set will pick at most one vertex from each clause, which will correspond to the literal to be set to true
3. Connect 2 vertices if they label complementary literals; this ensures that the literals corresponding to the independent set do not have a conflict
4. Take  $k$  to be the number of clauses

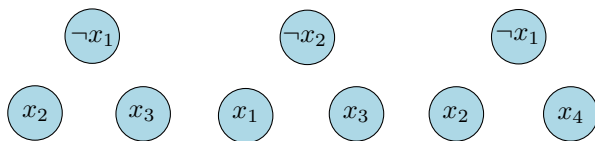


Figure: Graph for  $\varphi = (\neg x_1 \vee x_2 \vee x_3) \wedge (x_1 \vee \neg x_2 \vee x_3) \wedge (\neg x_1 \vee x_2 \vee x_4)$

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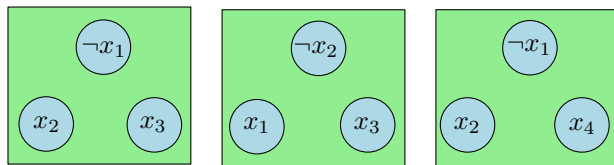


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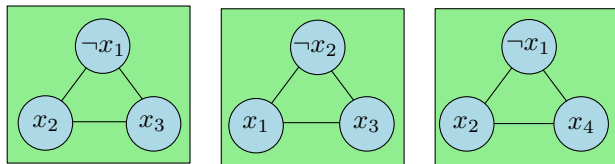


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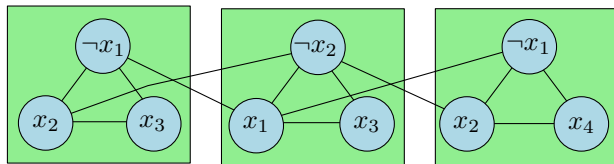


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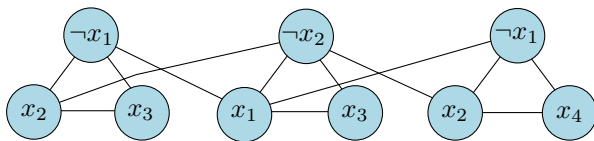


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# Correctness

## Proposition 23.2.

$\varphi$  is satisfiable iff  $G_\varphi$  has an independent set of size  $k$  (= number of clauses in  $\varphi$ ).

### Proof.

$\Rightarrow$  Let  $\mathbf{a}$  be the truth assignment satisfying  $\varphi$

- ▶ Pick one of the vertices, corresponding to true literals under  $\mathbf{a}$ , from each triangle. This is an independent set of the appropriate size. Why?



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## Proposition 23.2.

$\varphi$  is satisfiable iff  $G_\varphi$  has an independent set of size  $k$  (= number of clauses in  $\varphi$ ).

### Proof.

$\Leftarrow$  Let  $S$  be an independent set of size  $k$

1.  $S$  must contain exactly one vertex from each clause
2.  $S$  cannot contain vertices labeled by conflicting literals
3. Thus, it is possible to obtain a truth assignment that makes in the literals in  $S$  true; such an assignment satisfies one literal in every clause



# Summary

## Theorem 23.3.

**Independent set** is **NP-Complete** (i.e., **NPC**).

## 23.3

### NP-Completeness of Hamiltonian Cycle

## 23.3.1

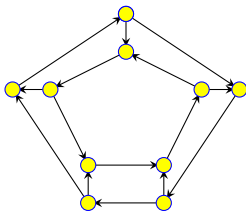
### Reduction from 3SAT to Hamiltonian Cycle: Basic idea

# Directed Hamiltonian Cycle

**Input** Given a directed graph  $G = (V, E)$  with  $n$  vertices

**Goal** Does  $G$  have a **Hamiltonian cycle**?

- ▶ A Hamiltonian cycle is a cycle in the graph that visits every vertex in  $G$  exactly once

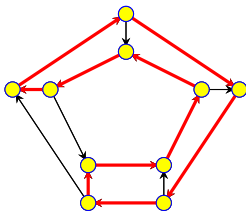


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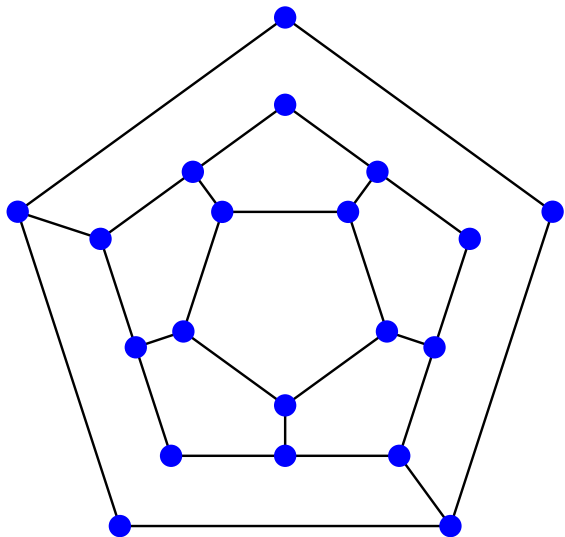
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Is the following graph Hamiltonian?



(A) Yes.

(B) No.

# Directed Hamiltonian Cycle is **NP-Complete**

- ▶ Directed Hamiltonian Cycle is in **NP**: exercise
- ▶ **Hardness**: We will show  $3SAT \leq_P \text{Directed Hamiltonian Cycle}$  .

# Reduction construction

From 3SAT to Hamiltonian cycle in directed graph

1. To show reduction, we next describe an algorithm:
  - ▶ Input: **3SAT** formula  $\varphi$
  - ▶ Output: A graph  $G_\varphi$ .
  - ▶ Running time is polynomial.
  - ▶ Requirement:  $\varphi$  is satisfiable  $\iff G_\varphi$  is Hamiltonian.
2. Given **3SAT** formula  $\varphi$  create a graph  $G_\varphi$  such that
  - ▶  $G_\varphi$  has a Hamiltonian cycle if and only if  $\varphi$  is satisfiable
  - ▶  $G_\varphi$  should be constructible from  $\varphi$  by a polynomial time algorithm  $\mathcal{A}$
3. **Notation:**  $\varphi$  has  $n$  variables  $x_1, x_2, \dots, x_n$  and  $m$  clauses  $C_1, C_2, \dots, C_m$ .

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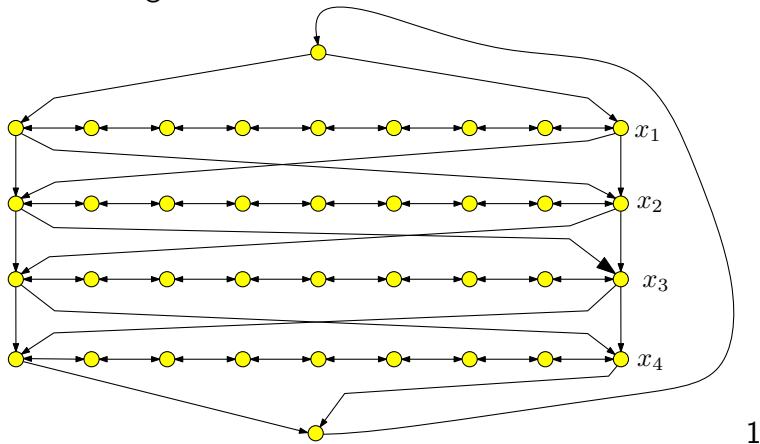
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# Encoding assignments

Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.

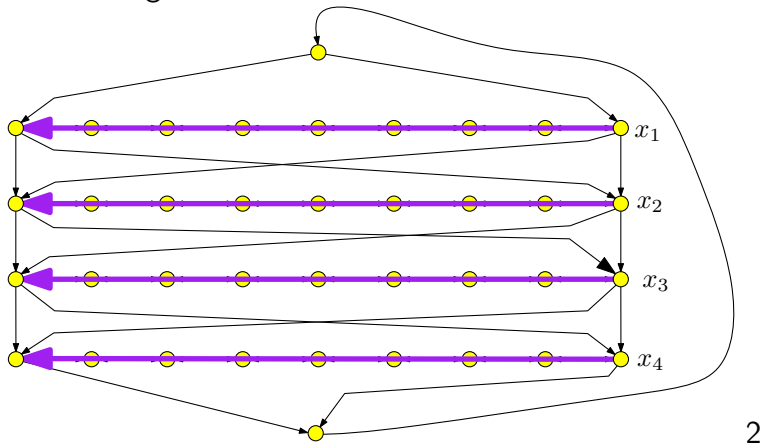




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Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.

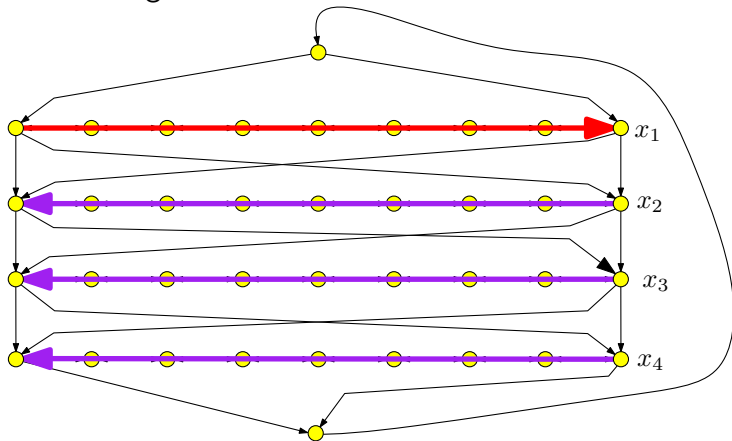


$$x_1 = 0, x_2 = 0, x_3 = 0, x_4 = 0$$

# Encoding assignments

Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.

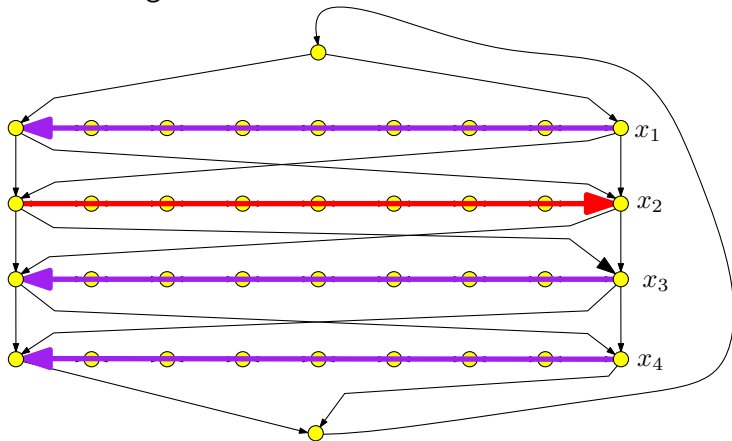


$$x_1 = 1, x_2 = 0, x_3 = 0, x_4 = 0$$

# Encoding assignments

Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.

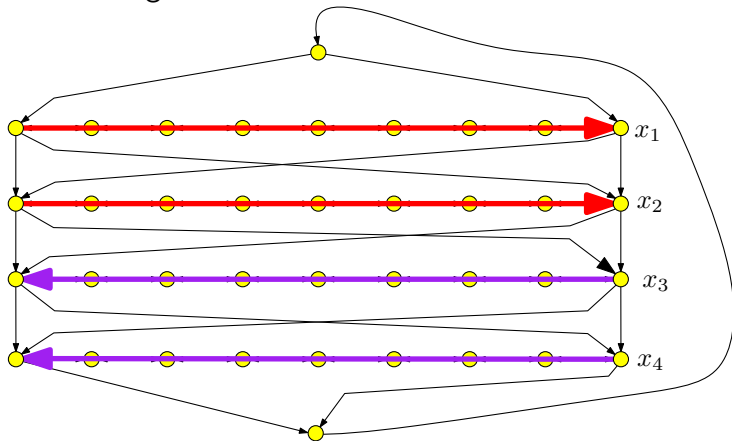


$$x_1 = 0, x_2 = 1, x_3 = 0, x_4 = 0$$

# Encoding assignments

Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.

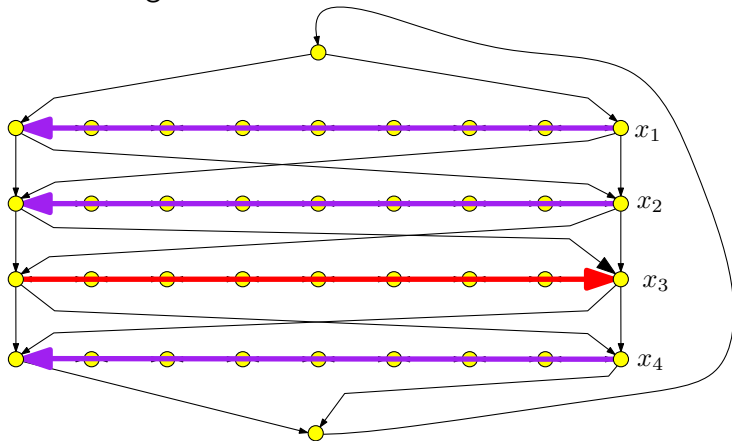


$$x_1 = 1, x_2 = 1, x_3 = 0, x_4 = 0$$

# Encoding assignments

Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.

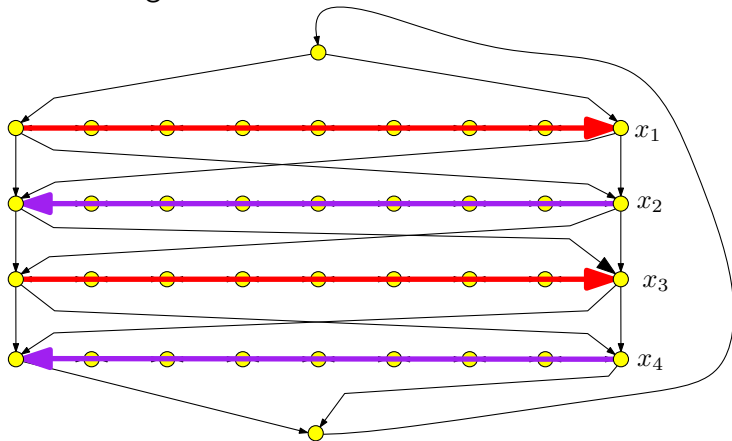


$$x_1 = 0, x_2 = 0, x_3 = 1, x_4 = 0$$

# Encoding assignments

Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.

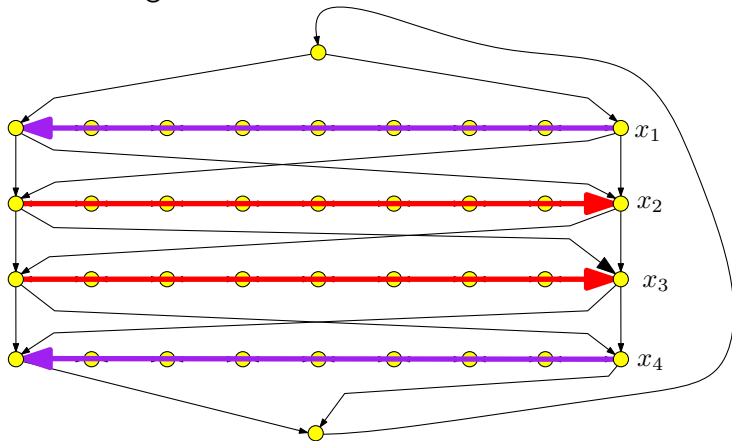


$$x_1 = 1, x_2 = 0, x_3 = 1, x_4 = 0$$

# Encoding assignments

Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.



5

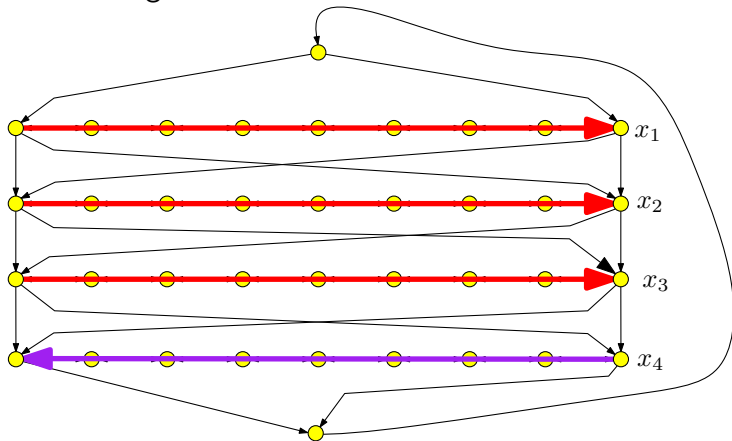
8

$$x_1 = 0, x_2 = 1, x_3 = 1, x_4 = 0$$

# Encoding assignments

Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.



5

9

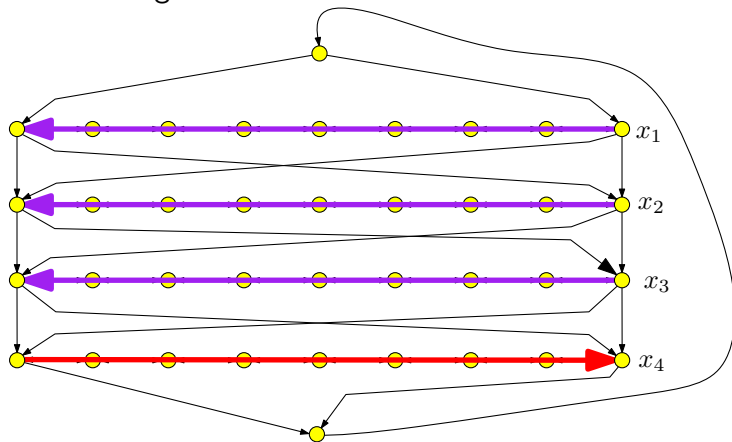
$$x_1 = 1, x_2 = 1, x_3 = 1, x_4 = 0$$



# Encoding assignments

Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.



5

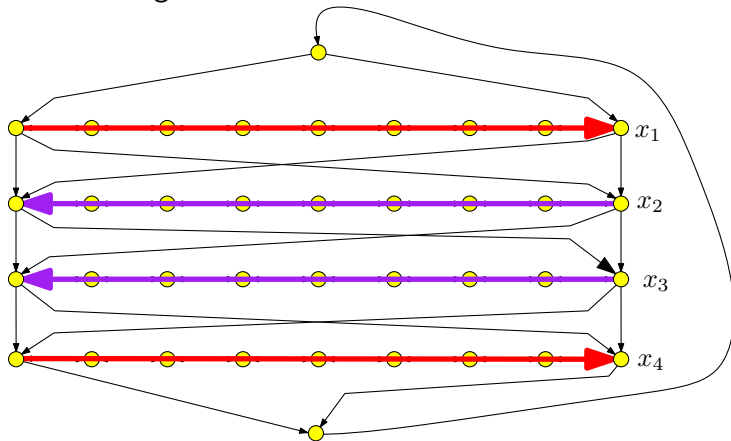
10

$$x_1 = 0, x_2 = 0, x_3 = 0, x_4 = 1$$

# Encoding assignments

Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.



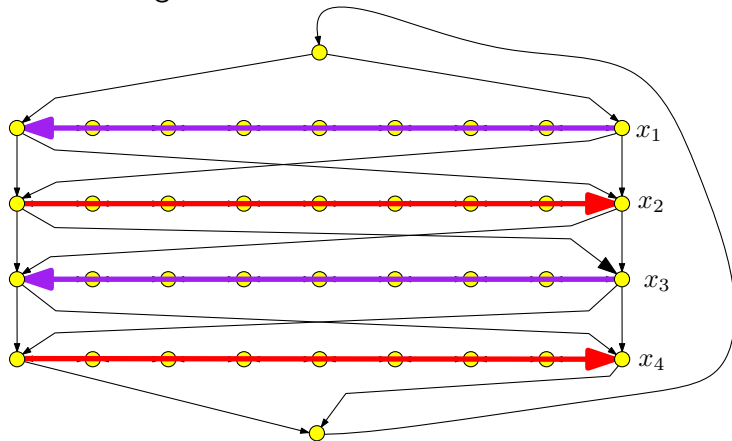
5

$$x_1 = 1, x_2 = 0, x_3 = 0, x_4 = 1$$

# Encoding assignments

Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.



12

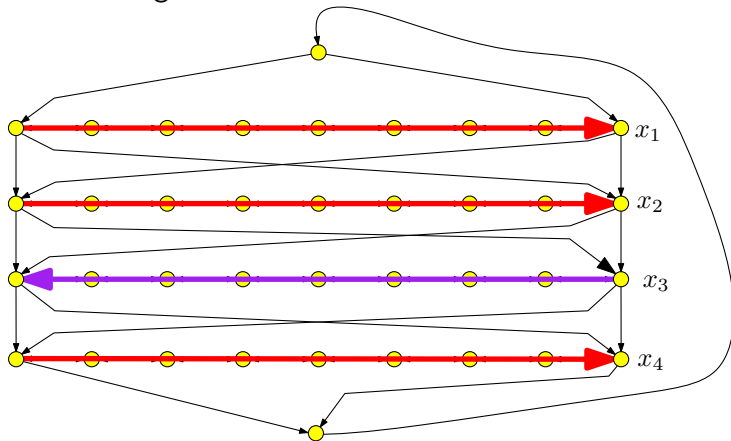
5

$$x_1 = 0, x_2 = 1, x_3 = 0, x_4 = 1$$

# Encoding assignments

Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.



13

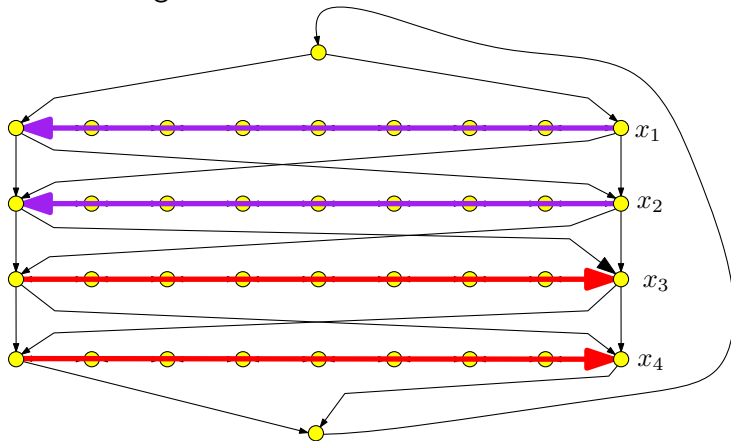
5

$$x_1 = 1, x_2 = 1, x_3 = 0, x_4 = 1$$

# Encoding assignments

Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.



14

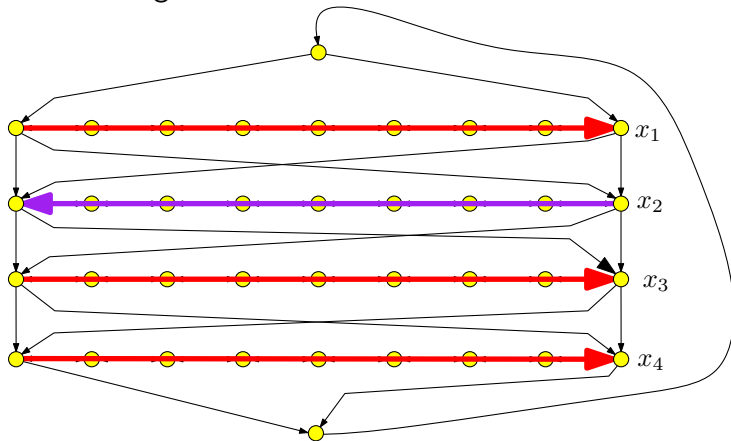
5

$$x_1 = 0, x_2 = 0, x_3 = 1, x_4 = 1$$

# Encoding assignments

Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.



15

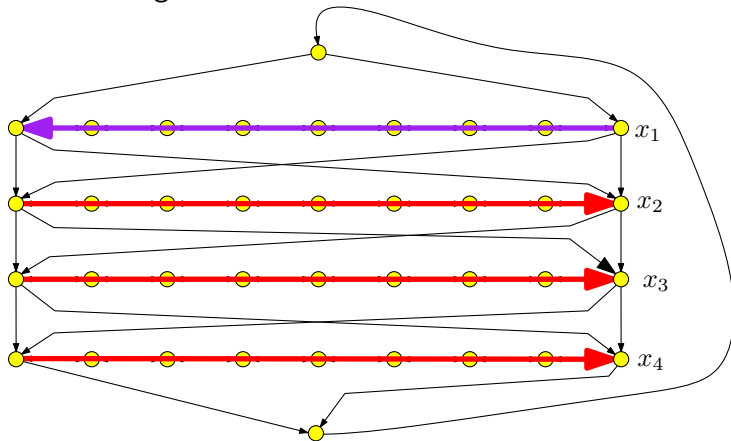
5

$$x_1 = 1, x_2 = 0, x_3 = 1, x_4 = 1$$

# Encoding assignments

Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.



16

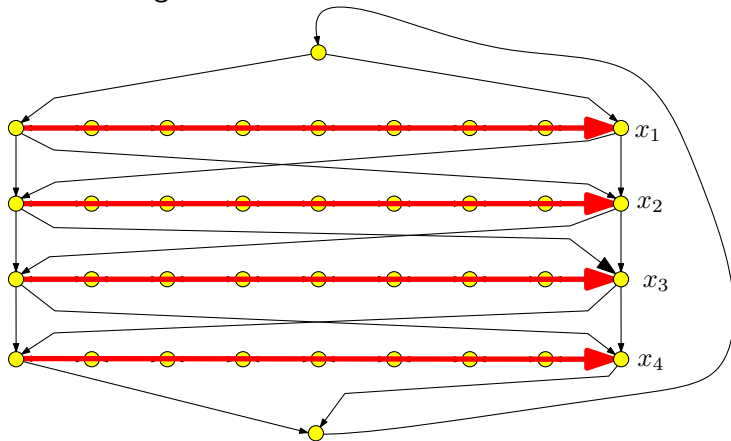
5

$$x_1 = 0, x_2 = 1, x_3 = 1, x_4 = 1$$

# Encoding assignments

Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.



17

5

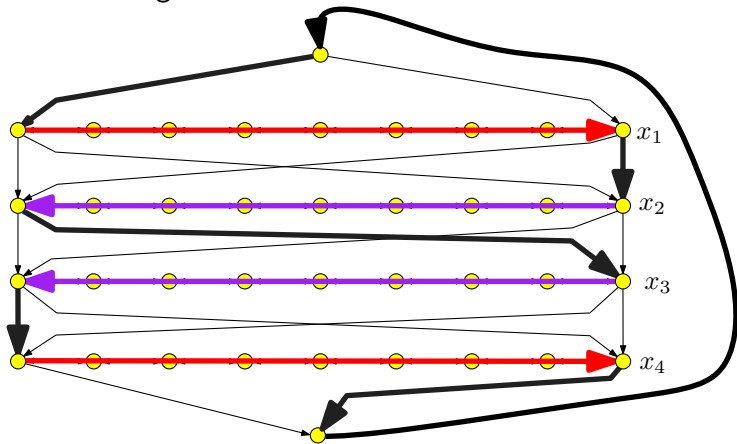
$$x_1 = 1, x_2 = 1, x_3 = 1, x_4 = 1$$



# Encoding assignments

Converting  $\varphi$  to a graph

Given a formula with  $n$  variables, we need a graph with  $2^n$  different Hamiltonian paths, that can encode their assignments.



## 23.3.2

The reduction: Encoding the formula constraints

# 3SAT $\leq_P$ Directed Hamiltonian Cycle

**Input:**  $\varphi$  formula.

**Output:** Graph  $G_\varphi$ .

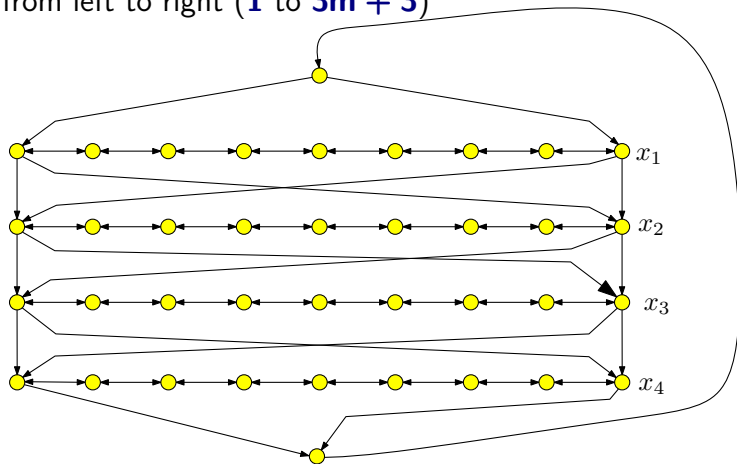
Saw: How to encode assignments...

Now need to encode constraints of  $\varphi$ .

# The reduction algorithm: Phase I

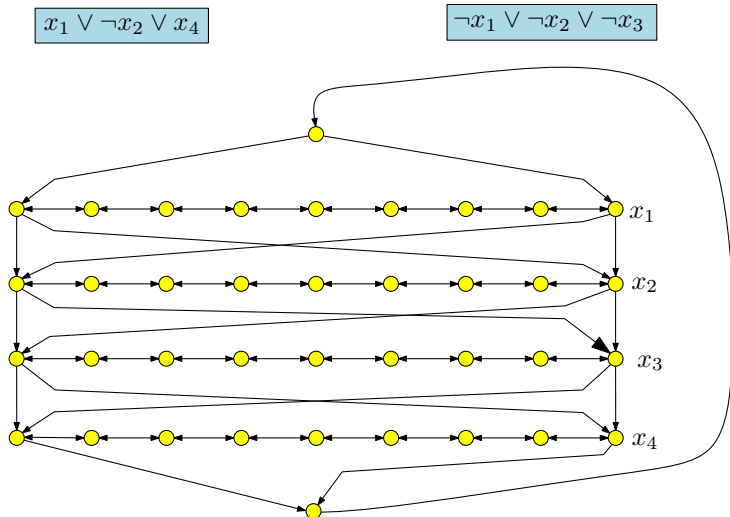
Converting  $\varphi$  to a graph

- ▶ Traverse path  $i$  from left to right iff  $x_i$  is set to true
- ▶ Each path has  $3(m + 1)$  nodes where  $m$  is number of clauses in  $\varphi$ ; nodes numbered from left to right (1 to  $3m + 3$ )



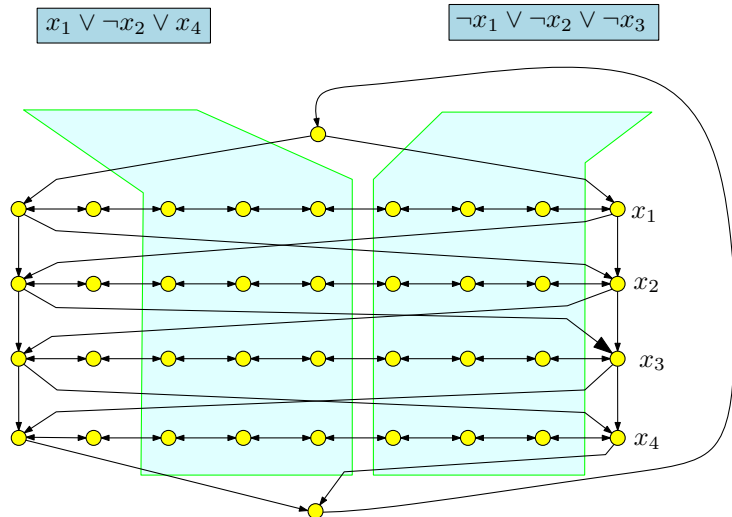
# The Reduction algorithm: Phase II

- Add vertex  $c_j$  for clause  $C_j$ .  $c_j$  has edge from vertex  $3j$  and to vertex  $3j + 1$  on path  $i$  if  $x_i$  appears in clause  $C_j$ , and has edge from vertex  $3j + 1$  and to vertex  $3j$  if  $\neg x_i$  appears in  $C_j$ .



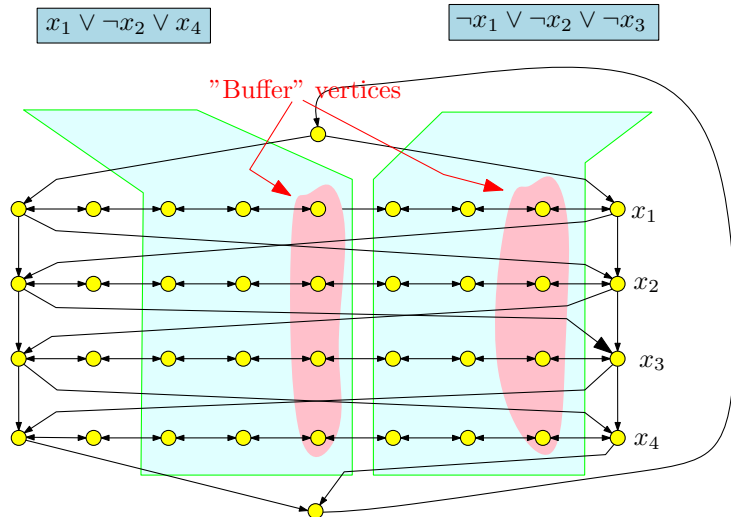
# The Reduction algorithm: Phase II

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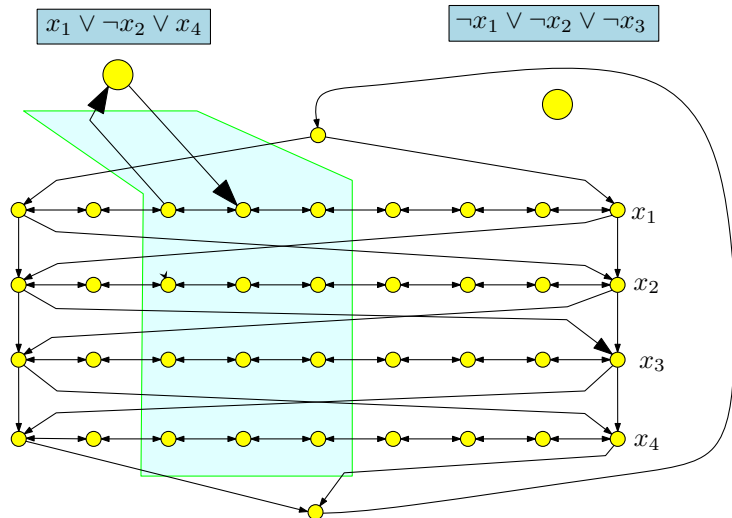
# The Reduction algorithm: Phase II

- Add vertex  $c_j$  for clause  $C_j$ .  $c_j$  has edge from vertex  $3j$  and to vertex  $3j + 1$  on path  $i$  if  $x_i$  appears in clause  $C_j$ , and has edge from vertex  $3j + 1$  and to vertex  $3j$  if  $\neg x_i$  appears in  $C_j$ .



# The Reduction algorithm: Phase II

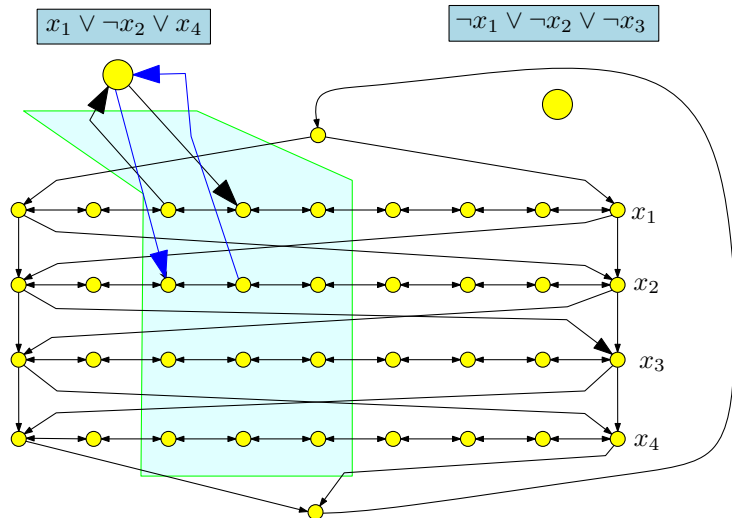
- Add vertex  $c_j$  for clause  $C_j$ .  $c_j$  has edge from vertex  $3j$  and to vertex  $3j + 1$  on path  $i$  if  $x_i$  appears in clause  $C_j$ , and has edge from vertex  $3j + 1$  and to vertex  $3j$  if  $\neg x_i$  appears in  $C_j$ .





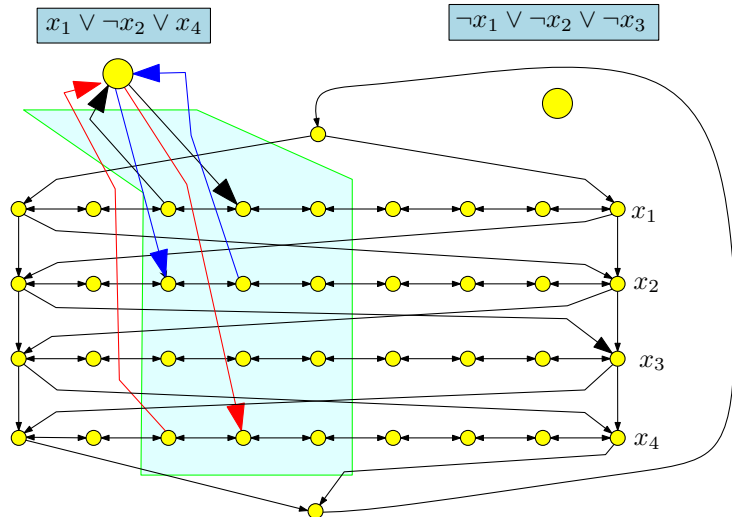
# The Reduction algorithm: Phase II

- Add vertex  $c_j$  for clause  $C_j$ .  $c_j$  has edge from vertex  $3j$  and to vertex  $3j + 1$  on path  $i$  if  $x_i$  appears in clause  $C_j$ , and has edge from vertex  $3j + 1$  and to vertex  $3j$  if  $\neg x_i$  appears in  $C_j$ .



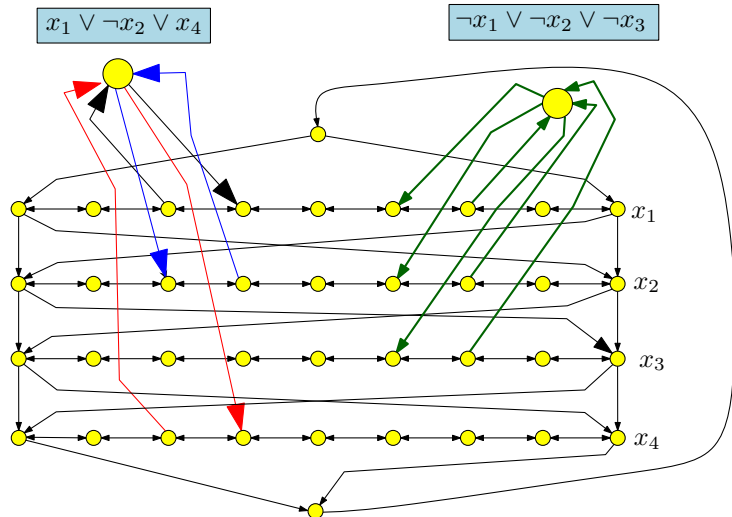
# The Reduction algorithm: Phase II

- Add vertex  $c_j$  for clause  $C_j$ .  $c_j$  has edge from vertex  $3j$  and to vertex  $3j + 1$  on path  $i$  if  $x_i$  appears in clause  $C_j$ , and has edge from vertex  $3j + 1$  and to vertex  $3j$  if  $\neg x_i$  appears in  $C_j$ .



# The Reduction algorithm: Phase II

- Add vertex  $c_j$  for clause  $C_j$ .  $c_j$  has edge from vertex  $3j$  and to vertex  $3j + 1$  on path  $i$  if  $x_i$  appears in clause  $C_j$ , and has edge from vertex  $3j + 1$  and to vertex  $3j$  if  $\neg x_i$  appears in  $C_j$ .



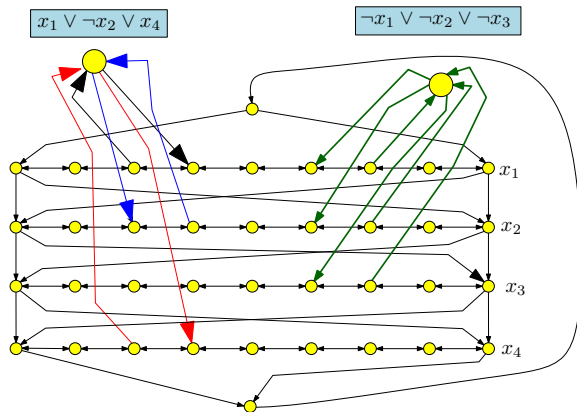
## 23.3.3

If there is a satisfying assignment, then  
there is a Hamiltonian cycle

# From satisfying assignment to Hamiltonian cycle: By figure

**3SAT** formula  $\varphi$ :

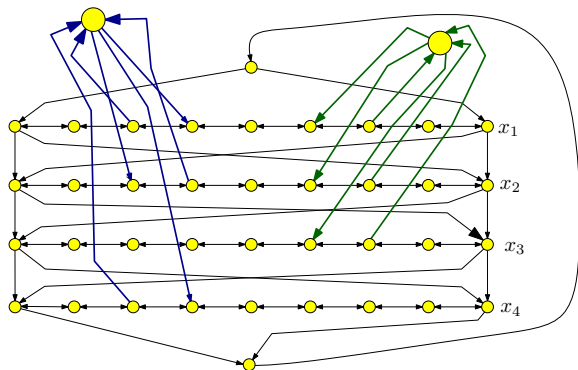
$$\varphi = (x_1 \vee \neg x_2 \vee x_4) \wedge (\neg x_1 \vee \neg x_2 \vee \neg x_3)$$



# From satisfying assignment to Hamiltonian cycle: By figure

**3SAT** formula  $\varphi$ :

$$\begin{aligned}\varphi = & \left( x_1 \vee \neg x_2 \vee x_4 \right) \\ & \wedge \left( \neg x_1 \vee \neg x_2 \vee \neg x_3 \right)\end{aligned}$$



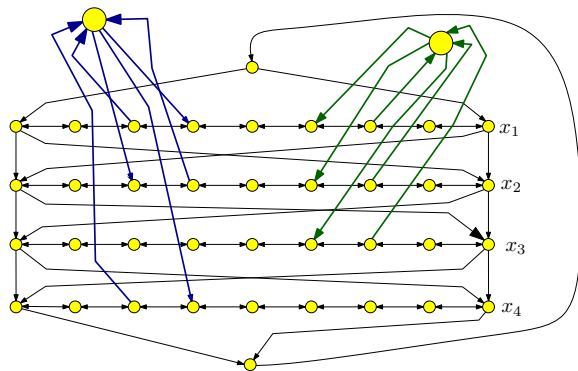
# From satisfying assignment to Hamiltonian cycle: By figure

**3SAT** formula  $\varphi$ :

$$\varphi = \left( x_1 \vee \neg x_2 \vee x_4 \right) \\ \wedge \left( \neg x_1 \vee \neg x_2 \vee \neg x_3 \right)$$

A satisfying assignment:

$$x_1 = 0, x_2 = 1, x_3 = 0, x_4 = 1$$

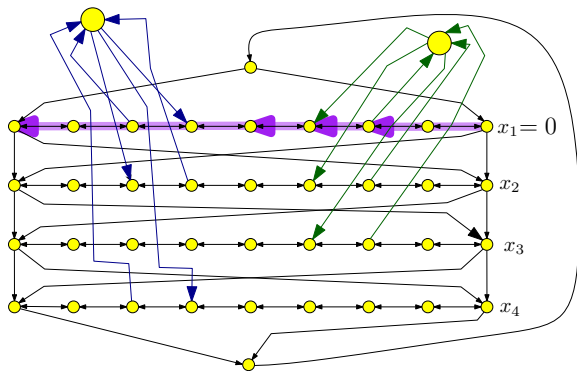


## From satisfying assignment to Hamiltonian cycle: By figure

**3SAT** formula  $\varphi$ :

$$\varphi = \left( \mathbf{x}_1 \vee \neg \mathbf{x}_2 \vee \mathbf{x}_4 \right) \\ \wedge \left( \neg \mathbf{x}_1 \vee \neg \mathbf{x}_2 \vee \neg \mathbf{x}_3 \right)$$

A satisfying assignment:

$$x_1 = 0, x_2 = 1, x_3 = 0, x_4 = 1$$




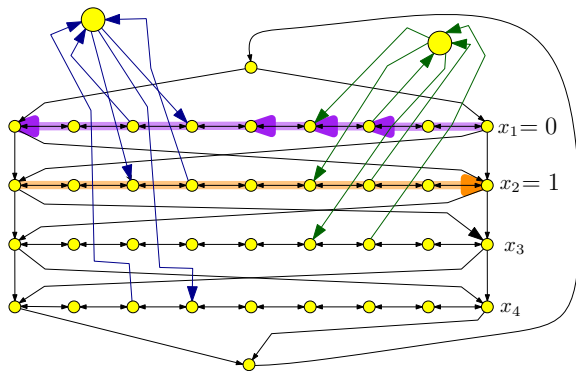
# From satisfying assignment to Hamiltonian cycle: By figure

**3SAT** formula  $\varphi$ :

$$\varphi = \left( x_1 \vee \neg x_2 \vee x_4 \right) \\ \wedge \left( \neg x_1 \vee \neg x_2 \vee \neg x_3 \right)$$

A satisfying assignment:

$$x_1 = 0, x_2 = 1, x_3 = 0, x_4 = 1$$



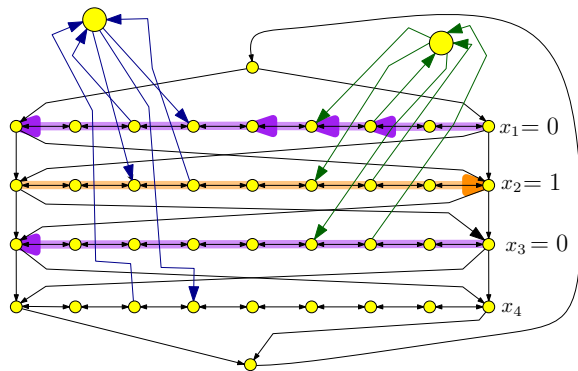
# From satisfying assignment to Hamiltonian cycle: By figure

**3SAT** formula  $\varphi$ :

$$\varphi = (x_1 \vee \neg x_2 \vee x_4) \wedge (\neg x_1 \vee \neg x_2 \vee \neg x_3)$$

A satisfying assignment:

$$x_1 = 0, x_2 = 1, x_3 = 0, x_4 = 1$$



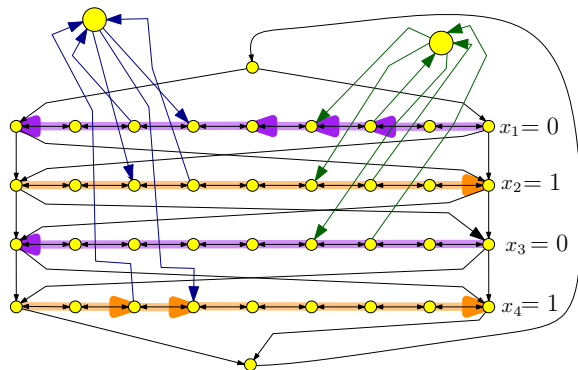
# From satisfying assignment to Hamiltonian cycle: By figure

**3SAT** formula  $\varphi$ :

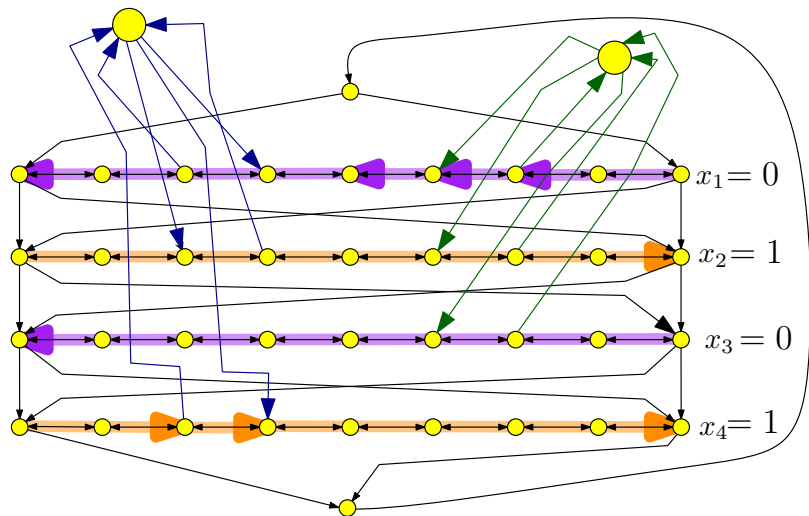
$$\varphi = (x_1 \vee \neg x_2 \vee x_4) \wedge (\neg x_1 \vee \neg x_2 \vee \neg x_3)$$

A satisfying assignment:

$$x_1 = 0, x_2 = 1, x_3 = 0, x_4 = 1$$

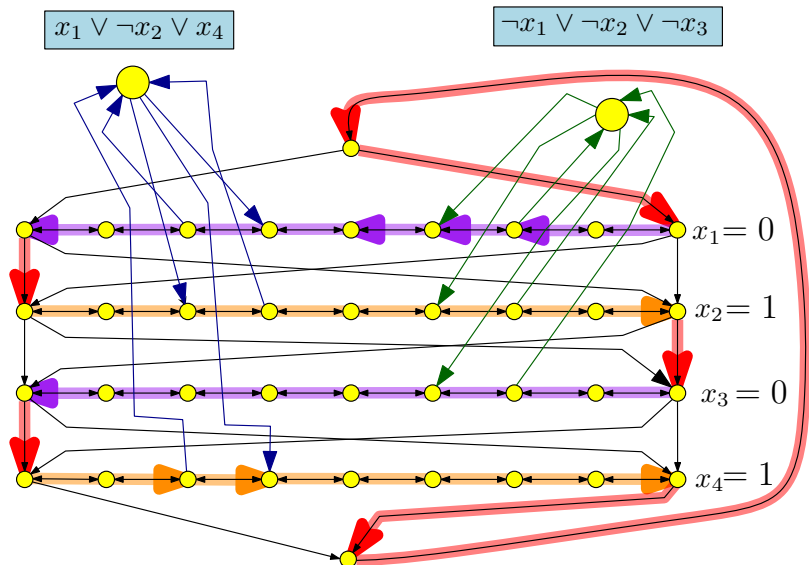


Reduction: Satisfying assignment  $\Rightarrow$  Hamiltonian cycle



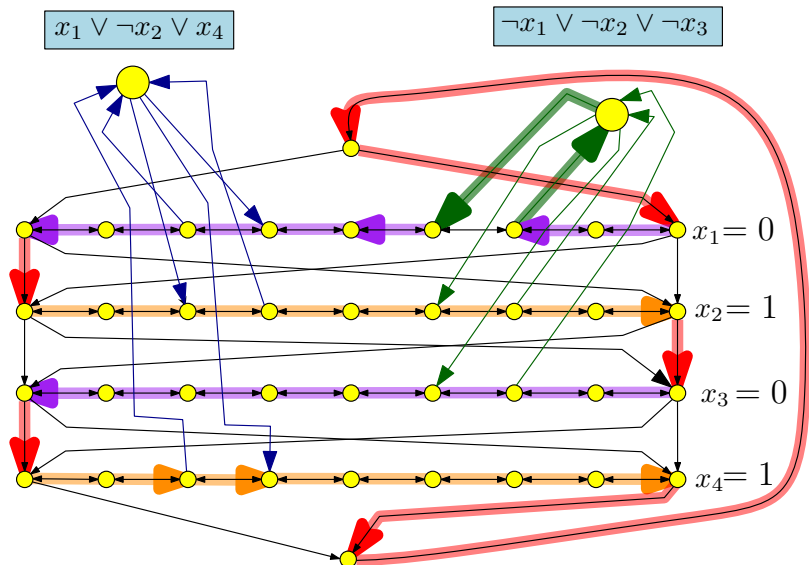
Satisfying assignment:  $x_1 = 0$ ,  $x_2 = 1$ ,  $x_3 = 0$ ,  $x_4 = 1$

# Reduction: Satisfying assignment $\Rightarrow$ Hamiltonian cycle



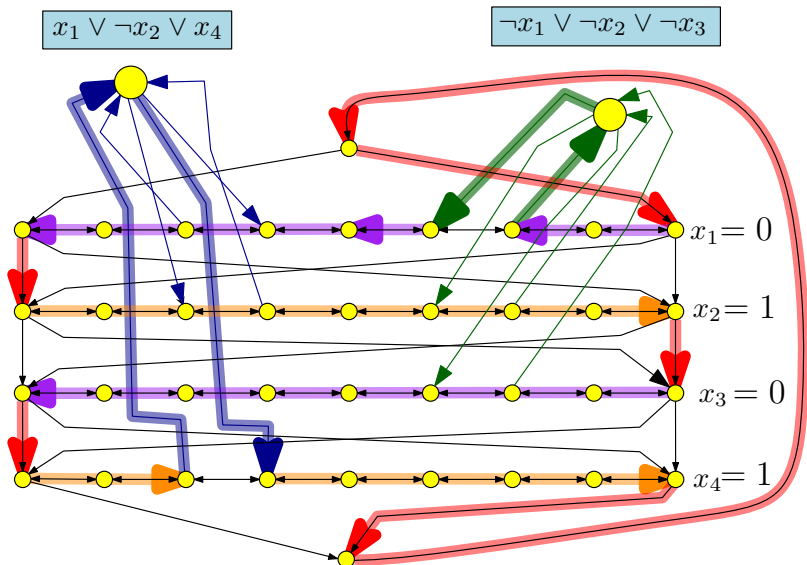
Satisfying assignment:  $x_1 = 0, x_2 = 1, x_3 = 0, x_4 = 1$

# Reduction: Satisfying assignment $\Rightarrow$ Hamiltonian cycle



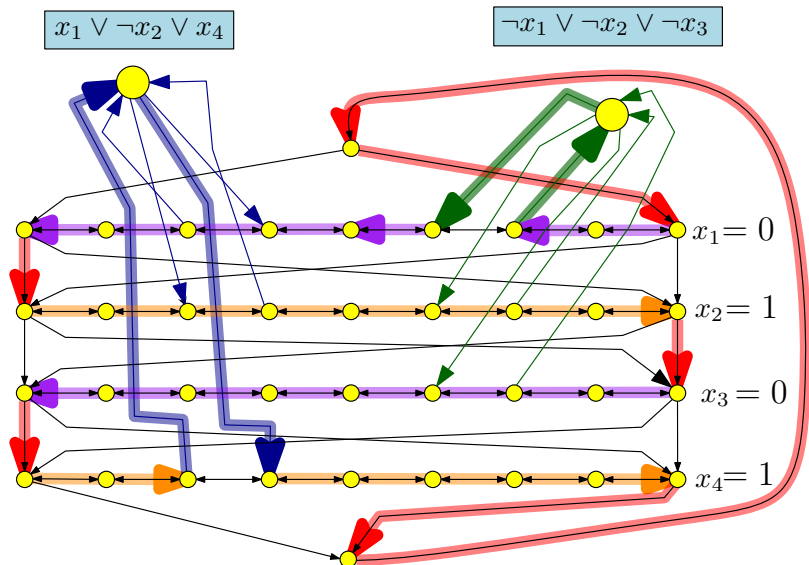
Satisfying assignment:  $x_1 = 0, x_2 = 1, x_3 = 0, x_4 = 1$

# Reduction: Satisfying assignment $\Rightarrow$ Hamiltonian cycle



Satisfying assignment:  $x_1 = 0, x_2 = 1, x_3 = 0, x_4 = 1$

# Reduction: Satisfying assignment $\Rightarrow$ Hamiltonian cycle



Satisfying assignment:  $x_1 = 0, x_2 = 1, x_3 = 0, x_4 = 1$

**Conclude:** If  $\varphi$  has a satisfying assignment then there is an Hamiltonian cycle in  $G_\varphi$ .



# Correctness Proof

## Lemma 23.1.

$\varphi$  has a satisfying assignment  $\alpha \implies G_\varphi$  has a Hamiltonian cycle.

## Proof.

Let  $\mathbf{a}$  be the satisfying assignment for  $\varphi$ . Define Hamiltonian cycle as follows

- ▶ If  $\alpha(\mathbf{x}_i) = 1$  then traverse path  $\mathbf{i}$  from left to right
- ▶ If  $\alpha(\mathbf{x}_i) = 0$  then traverse path  $\mathbf{i}$  from right to left
- ▶ For each clause, path of at least one variable is in the “right” direction to splice in the node corresponding to clause
- ▶ Clearly, resulting cycle is Hamiltonian. □

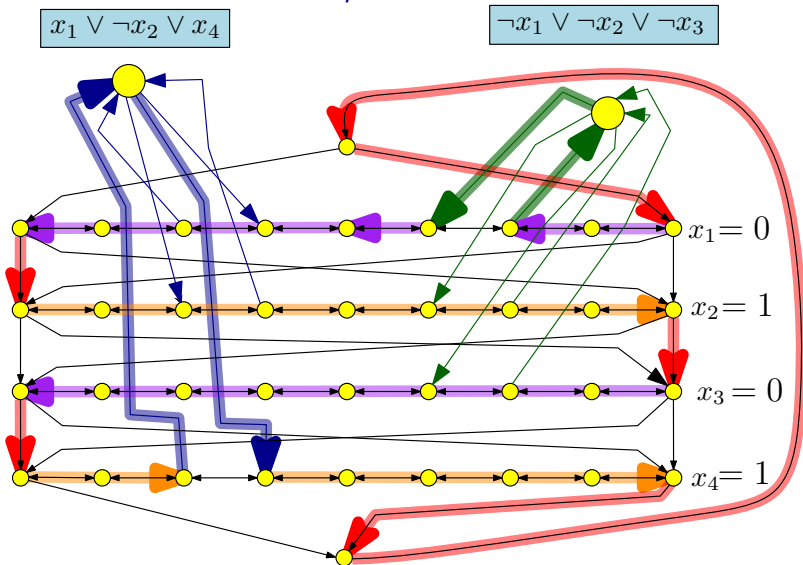
## 23.3.4

If there is a Hamiltonian cycle  $\Rightarrow$

$\exists$  satisfying assignment

Reduction: Hamiltonian cycle  $\implies \exists$  satisfying assignment

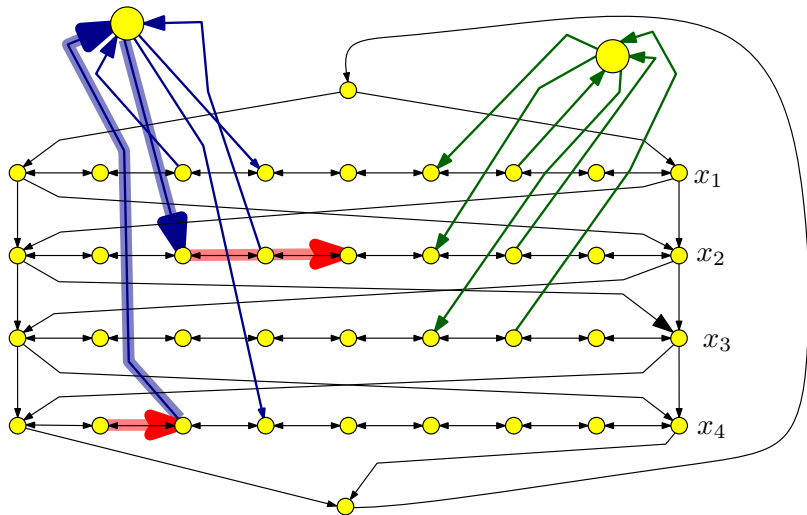
We are given a Hamiltonian cycle in  $G_\varphi$ :



Want to extract satisfying assignment...

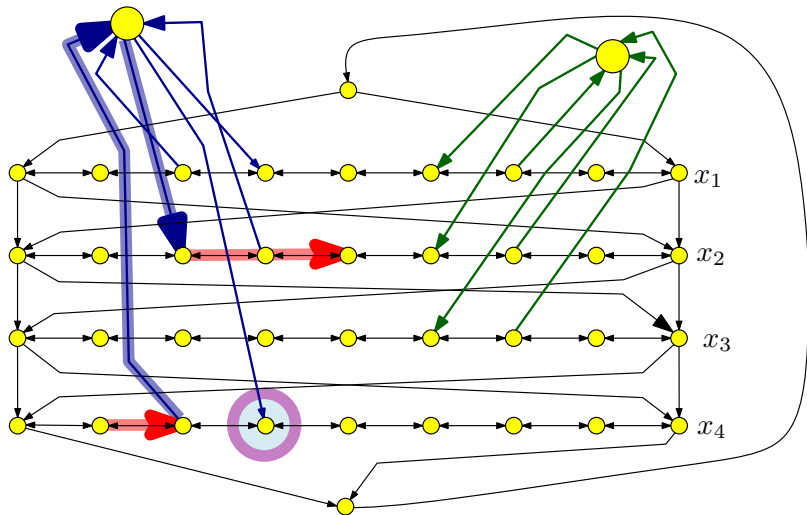
Reduction: Hamiltonian cycle  $\implies \exists$  satisfying assignment

No shenanigan: Hamiltonian cycle can not leave a row in the middle



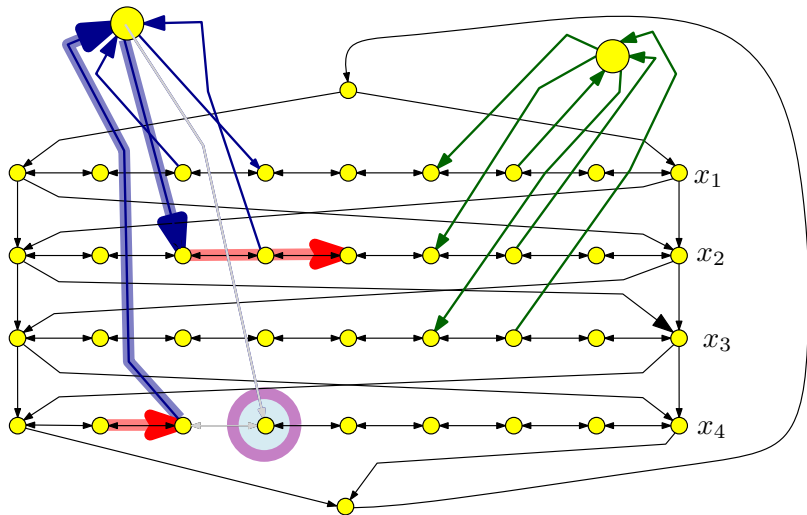
Reduction: Hamiltonian cycle  $\implies \exists$  satisfying assignment

No shenanigan: Hamiltonian cycle can not leave a row in the middle



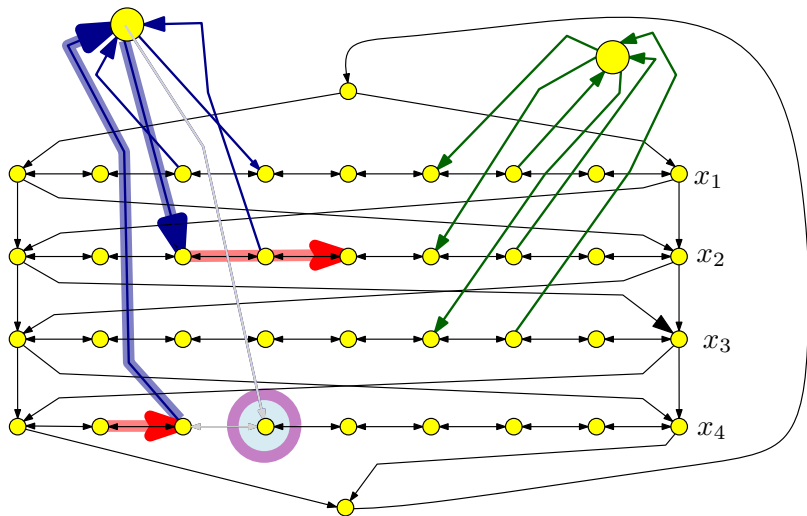
Reduction: Hamiltonian cycle  $\implies \exists$  satisfying assignment

No shenanigan: Hamiltonian cycle can not leave a row in the middle



Reduction: Hamiltonian cycle  $\implies \exists$  satisfying assignment

No shenanigan: Hamiltonian cycle can not leave a row in the middle



**Conclude:** Hamiltonian cycle must go through each row completely from left to right, or right to left. As such, can be interpreted as a valid assignment.

# Hamiltonian Cycle $\Rightarrow$ Satisfying assignment

Suppose  $\Pi$  is a Hamiltonian cycle in  $G_\varphi$

- ▶ If  $\Pi$  enters  $c_j$  (vertex for clause  $C_j$ ) from vertex  $3j$  on path  $i$  then it must leave the clause vertex on edge to  $3j + 1$  on the same path  $i$ 
  - ▶ If not, then only unvisited neighbor of  $3j + 1$  on path  $i$  is  $3j + 2$
  - ▶ Thus, we don't have two unvisited neighbors (one to enter from, and the other to leave) to have a Hamiltonian Cycle
- ▶ Similarly, if  $\Pi$  enters  $c_j$  from vertex  $3j + 1$  on path  $i$  then it must leave the clause vertex  $c_j$  on edge to  $3j$  on path  $i$

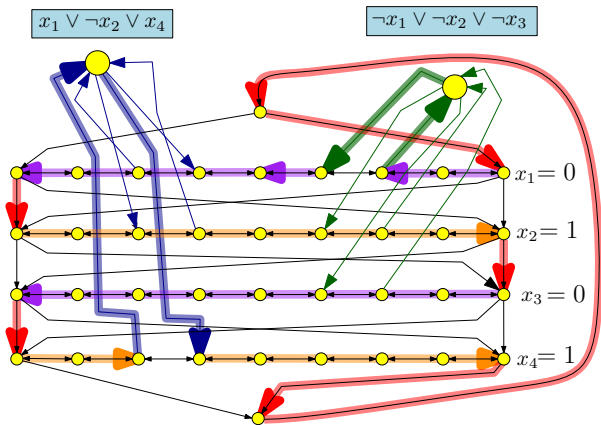


## Hamiltonian Cycle $\implies$ Satisfying assignment (contd)

- ▶ Thus, vertices visited immediately before and after  $\mathbf{C}_i$  are connected by an edge
- ▶ We can remove  $\mathbf{c}_j$  from cycle, and get Hamiltonian cycle in  $\mathbf{G} - \mathbf{c}_j$
- ▶ Consider Hamiltonian cycle in  $\mathbf{G} - \{\mathbf{c}_1, \dots, \mathbf{c}_m\}$ ; it traverses each path in only one direction, which determines the truth assignment

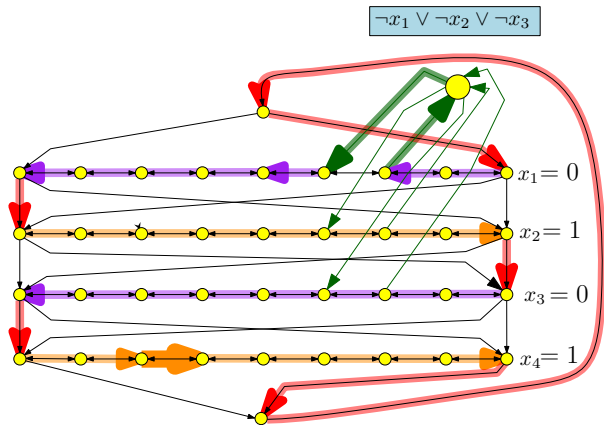
# Hamiltonian Cycle $\implies$ Satisfying assignment (contd)

- ▶ Thus, vertices visited immediately before and after  $C_i$  are connected by an edge
- ▶ We can remove  $C_j$  from cycle, and get Hamiltonian cycle in  $G - C_j$
- ▶ Consider Hamiltonian cycle in  $G - \{C_1, \dots, C_m\}$ ; it traverses each path in only one direction, which determines the truth assignment



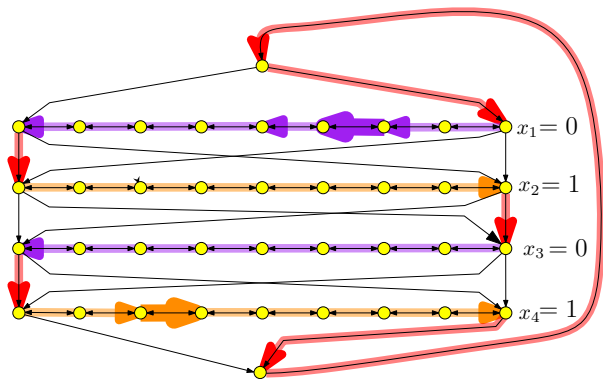
# Hamiltonian Cycle $\implies$ Satisfying assignment (contd)

- ▶ Thus, vertices visited immediately before and after  $C_i$  are connected by an edge
- ▶ We can remove  $C_j$  from cycle, and get Hamiltonian cycle in  $G - C_j$
- ▶ Consider Hamiltonian cycle in  $G - \{C_1, \dots, C_m\}$ ; it traverses each path in only one direction, which determines the truth assignment



## Hamiltonian Cycle $\implies$ Satisfying assignment (contd)

- ▶ Thus, vertices visited immediately before and after  $C_i$  are connected by an edge
- ▶ We can remove  $C_j$  from cycle, and get Hamiltonian cycle in  $G - C_j$
- ▶ Consider Hamiltonian cycle in  $G - \{C_1, \dots, C_m\}$ ; it traverses each path in only one direction, which determines the truth assignment



# Correctness Proof

We just proved:

## Lemma 23.2.

$G_\varphi$  has a Hamiltonian cycle  $\implies \varphi$  has a satisfying assignment  $\alpha$ .

## Lemma 23.3.

$\varphi$  has a satisfying assignment iff  $G_\varphi$  has a Hamiltonian cycle.

## Proof.

Follows from **Lemma 23.1** and **Lemma 23.2** . □

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# Summary

What we did:

1. Showed that **Directed Hamiltonian Cycle** is in **NP**.
2. Provided a polynomial time reduction from **3SAT** to **Directed Hamiltonian Cycle**.
3. Proved that  $\varphi$  satisfiable  $\iff G_\varphi$  is Hamiltonian.

## Theorem 23.4.

*The problem **Hamiltonian Cycle** in directed graphs is **NP-Complete**.*

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*The problem **Hamiltonian Cycle** in directed graphs is **NP-Complete**.*



## 23.4

### Hamiltonian cycle in undirected graph

# Hamiltonian Cycle

## Problem 23.1.

*Input* Given *undirected* graph  $\mathbf{G} = (\mathbf{V}, \mathbf{E})$

*Goal* Does  $\mathbf{G}$  have a Hamiltonian cycle? That is, is there a cycle that visits every vertex exactly one (except start and end vertex)?

# NP-Completeness

## Theorem 23.2.

**Hamiltonian cycle** problem for undirected graphs is **NP-Complete**.

## Proof.

- ▶ The problem is in **NP**; proof left as exercise.
- ▶ Hardness proved by reducing Directed Hamiltonian Cycle to this problem

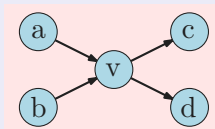


# Reduction Sketch

**Goal:** Given directed graph  $G$ , need to construct undirected graph  $G'$  such that  $G$  has Hamiltonian Path iff  $G'$  has Hamiltonian path

## Reduction

- ▶ Replace each vertex  $v$  by 3 vertices:  $v_{in}$ ,  $v$ , and  $v_{out}$
- ▶ A directed edge  $(a, b)$  is replaced by edge  $(a_{out}, b_{in})$

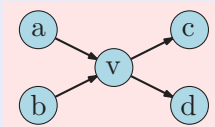


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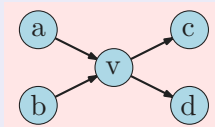


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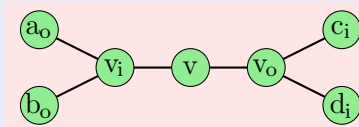
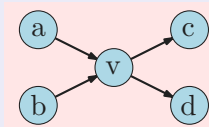


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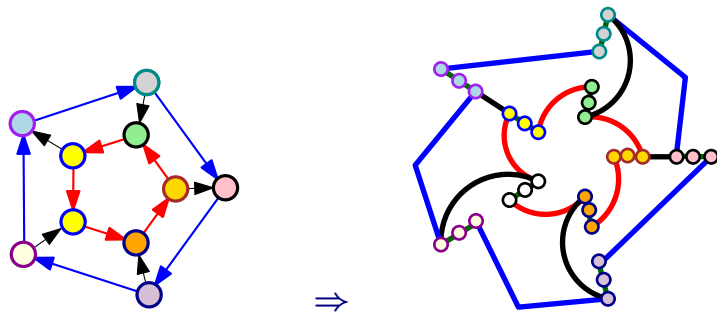
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# Hamiltonian cycle reduction

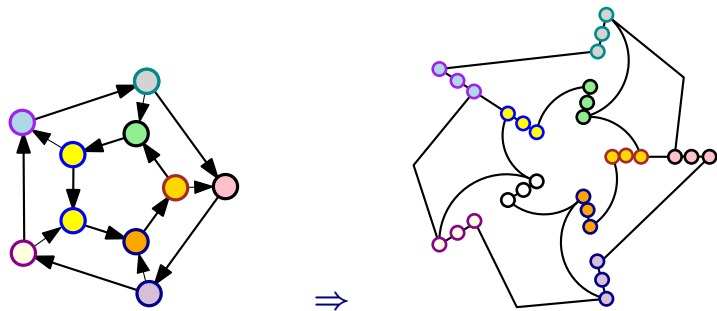
Undirected to directed case





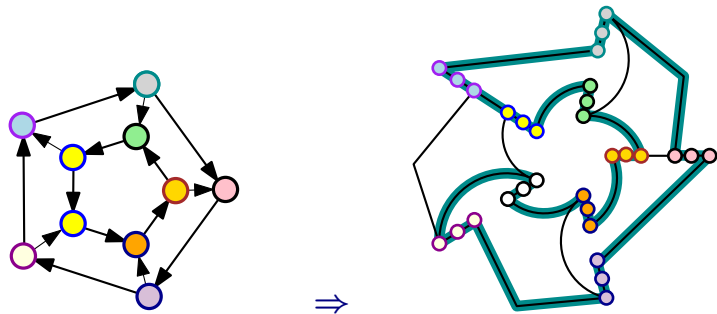
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Undirected to directed case



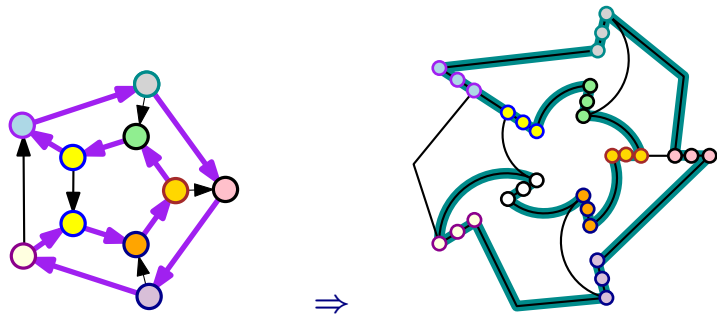
# Hamiltonian cycle reduction

Undirected to directed case



# Hamiltonian cycle reduction

Undirected to directed case



## Reduction: Wrap-up

- ▶ The reduction is polynomial time (exercise)
- ▶ The reduction is correct (exercise)