## Algorithms \& Models of Computation

## CS/ECE 374, Fall 2020

## Circuit satisfiability and Cook-Levin Theorem

Lecture 24
Thursday, December 3, 2020

Algorithms \& Models of Computation CS/ECE 374, Fall 2020
24.1

Recap

## Recap

NP: languages that have non-deterministic polynomial time algorithms
A language $L$ is NP-Complete if and only if

- $L$ is in NP
- for every $\boldsymbol{L}^{\prime}$ in $N P, L^{\prime} S_{p} L$
$\boldsymbol{L}$ is NP-Hard if for every $\boldsymbol{L}^{\prime}$ in $\mathbf{N P}, \boldsymbol{L}^{\prime} \leq_{p} \boldsymbol{L}$.

Theorem 24.1 (Cook-Levin).

## SAT is NP-Complete.

## Recap

NP: languages that have non-deterministic polynomial time algorithms
A language $L$ is NP-Complete if and only if

- $L$ is in NP
- for every $\boldsymbol{L}^{\prime}$ in $\mathbf{N P}, \boldsymbol{L}^{\prime} \leq_{P} \boldsymbol{L}$
$\boldsymbol{L}$ is NP-Hard if for every $\boldsymbol{L}^{\prime}$ in $\mathbf{N P}, \boldsymbol{L}^{\prime} \leq_{p} \boldsymbol{L}$.

Theorem 24.1 (Cook-Levin)
SAT is NP-Complete.

## Recap

NP: languages that have non-deterministic polynomial time algorithms
A language $L$ is NP-Complete if and only if

- $\boldsymbol{L}$ is in NP
- for every $\boldsymbol{L}^{\prime}$ in $\mathbf{N P}, \boldsymbol{L}^{\prime} \leq_{P} \boldsymbol{L}$
$\boldsymbol{L}$ is $\mathbf{N P}$-Hard if for every $\boldsymbol{L}^{\prime}$ in $\mathbf{N P}, \boldsymbol{L}^{\prime} \leq_{P} \boldsymbol{L}$.


## Theorem 24.1 (Cook-Levin).

 SAT is NP-Complete.
## Recap

NP: languages that have non-deterministic polynomial time algorithms
A language $L$ is NP-Complete if and only if

- $\boldsymbol{L}$ is in NP
- for every $\boldsymbol{L}^{\prime}$ in $\mathbf{N P}, \boldsymbol{L}^{\prime} \leq_{P} \boldsymbol{L}$
$\boldsymbol{L}$ is $\mathbf{N P}$-Hard if for every $\boldsymbol{L}^{\prime}$ in $\mathbf{N P}, \boldsymbol{L}^{\prime} \leq_{P} \boldsymbol{L}$.


## Theorem 24.1 (Cook-Levin).

SAT is NP-Complete.

## Pictorial View



## $\mathbf{P}$ and $\mathbf{N P}$

Possible scenarios:

1. $\mathbf{P}=\mathbf{N P}$.
2. $P \neq N P$

Question: Suppose $\mathbf{P} \neq \mathbf{N P}$. Is every problem in NP $\backslash \mathbf{P}$ also NP-Complete?
Theorem 21.2 (Ladnor).
If $\mathrm{P} \neq \mathrm{NP}$ then there is a problem/language $X \in \mathrm{NP} \backslash \mathrm{P}$ such that $X$ is not NP-Complete.

## $\mathbf{P}$ and $\mathbf{N P}$

Possible scenarios:

1. $P=N P$.
2. $P \neq N P$

Question: Suppose $\mathbf{P} \neq \mathbf{N P}$. Is every problem in NP $\backslash \mathbf{P}$ also NP-Complete?
Theorem 24.2 (Ladner).
If $\mathbf{P} \neq \mathbf{N P}$ then there is a problem/language $\boldsymbol{X} \in \mathbf{N P} \backslash \mathbf{P}$ such that $\boldsymbol{X}$ is not NP-Complete.

## $\mathbf{P}$ and $\mathbf{N P}$

Possible scenarios:

1. $\mathbf{P}=\mathbf{N P}$.
2. $\mathbf{P} \neq \mathrm{NP}$

Question: Suppose $\mathbf{P} \neq \mathbf{N P}$. Is every problem in NP $\backslash \mathbf{P}$ also NP-Complete?
Theorem 24.2 (Ladner).
If $\mathbf{P} \neq \mathbf{N P}$ then there is a problem/language $\boldsymbol{X} \in \mathbf{N P} \backslash \mathbf{P}$ such that $\boldsymbol{X}$ is not NP-Complete.

## What do we know so far

1. Independent Set $\leq_{P}$ Clique, Clique $\leq_{P}$ Independent Set. $\Longrightarrow$ Clique $\approx_{p}$ Independent Set.
2. Vertex Cover $\leq_{p}$ Independent Set, Independent Set $\leq_{p}$ Vertex Cover $\Longrightarrow$ Independent Set $\approx_{p}$ Vertex Cover
3. 3 SAT $\leq_{p}$ SAT, SAT $\leq_{p}$ 3SAT $\Longrightarrow$ 3SAT $\approx_{p}$ SAT.
4. 3 SAT $\leq_{p}$ Independent Set

Exercise (or Cook-Levin theorem): Independent Set $\leq_{p}$ SAT $\Longrightarrow$ 3SAT $\approx_{p}$ Independent Set.
5. SAT $\leq_{p}$ Hamiltonian Cycle Exercise (or Cook-Levin theorem): Hamiltonian Cycle $\leq_{P}$ 3SAT $\Longrightarrow$ Hamiltonian Cycle $\approx_{P}$ 3SAT
6. Clique $\approx_{p}$ Independent Set $\approx_{p}$ Vertex Cover $\approx_{p}$ 3SAT $\approx_{P}$ SAT $\approx_{P}$ Hamiltonian Cycle

## What do we know so far

1. Independent Set $\leq_{P}$ Clique, Clique $\leq_{P}$ Independent Set.
$\Longrightarrow$ Clique $\approx_{p}$ Independent Set.
2. Vertex Cover $\leq_{P}$ Independent Set, Independent Set $\leq_{P}$ Vertex Cover. $\Longrightarrow$ Independent Set $\approx_{P}$ Vertex Cover.
3. 3 SAT $\leq_{p}$ SAT, SAT $\leq_{p}$ 3SAT $\Longrightarrow 3 S A T \approx_{p}$ SAT.
4. 3 SAT $\leq_{p}$ Independent Set

Exercise (or Cook-Levin theorem): Independent Set $\leq_{p}$ SAT $\Longrightarrow$ 3SAT $\approx_{p}$ Independent Set.
5. SAT $\leq_{P}$ Hamiltonian Cycle Exercise (or Cook-Levin theorem): Hamiltonian Cycle $\leq_{p}$ 3SAT $\Longrightarrow$ Hamiltonian Cycle $\approx_{p}$ 3SAT
6. Clique $\approx_{P}$ Independent Set $\approx_{p}$ Vertex Cover $\approx_{P}$ 3SAT $\approx_{p}$ SAT $\approx_{p}$ Hamiltonian Cycle

## What do we know so far

1. Independent Set $\leq_{P}$ Clique, Clique $\leq_{P}$ Independent Set.
$\Longrightarrow$ Clique $\approx_{p}$ Independent Set.
2. Vertex Cover $\leq_{P}$ Independent Set, Independent Set $\leq_{P}$ Vertex Cover. $\Longrightarrow$ Independent Set $\approx_{p}$ Vertex Cover.
3. $3 \mathrm{SAT} \leq_{P}$ SAT, SAT $\leq_{P}$ 3SAT $\Longrightarrow$ 3SAT $\approx_{P}$ SAT.
4. 3 SAT $\leq_{p}$ Independent Set Exercise (or Cook-Levin theorem): Independent Set $\leq_{P}$ SAT $\Longrightarrow$ 3SAT $\approx_{p}$ Independent Set
5. SAT $\leq_{p}$ Hamiltonian Cycle Exercise (or Cook-Levin theorem): Hamiltonian Cycle $\leq_{P}$ 3SAT $\Rightarrow$ Hamiltonian Cycle $\approx_{P}$ 3SAT
6. Clique $\approx_{p}$ Independent Set $\approx_{p}$ Vertex Cover $\approx_{p}$ 3SAT $\approx_{P}$ SAT $\approx_{P}$ Hamiltonian Cycle

## What do we know so far

1. Independent Set $\leq_{P}$ Clique, Clique $\leq_{P}$ Independent Set.
$\Longrightarrow$ Clique $\approx_{p}$ Independent Set.
2. Vertex Cover $\leq_{P}$ Independent Set, Independent Set $\leq_{P}$ Vertex Cover. $\Longrightarrow$ Independent Set $\approx_{p}$ Vertex Cover.
3. $3 \mathrm{SAT} \leq_{P}$ SAT, SAT $\leq_{P}$ 3SAT $\Rightarrow$ 3SAT $\approx_{P}$ SAT.
4. 3 SAT $\leq_{P}$ Independent Set .

Exercise (or Cook-Levin theorem): Independent Set $\leq_{P}$ SAT
$\Longrightarrow$ 3SAT $\approx_{P}$ Independent Set.
5. SAT $\leq_{p}$ Hamiltonian Cycle

Exercise (or Cook-Levin theorem): Hamiltonian Cycle $\leq_{P}$ 3SAT $\Rightarrow$ Hamiltonian Cycle $\approx_{P}$ 3SAT
6. Clique $\approx_{p}$ Independent Set $\approx_{p}$ Vertex Cover $\approx_{p}$ 3SAT $\approx_{p}$ SAT $\approx_{p}$ Hamiltonian Cycle

## What do we know so far

1. Independent Set $\leq_{P}$ Clique, Clique $\leq_{P}$ Independent Set.
$\Longrightarrow$ Clique $\approx_{p}$ Independent Set.
2. Vertex Cover $\leq_{P}$ Independent Set, Independent Set $\leq_{P}$ Vertex Cover. $\Longrightarrow$ Independent Set $\approx_{P}$ Vertex Cover.
3. $3 \mathrm{SAT} \leq_{P}$ SAT, SAT $\leq_{P}$ 3SAT $\Rightarrow$ 3SAT $\approx_{P}$ SAT.
4. 3 SAT $\leq_{P}$ Independent Set .

Exercise (or Cook-Levin theorem): Independent Set $\leq_{P}$ SAT
$\Longrightarrow$ 3SAT $\approx_{P}$ Independent Set.
5. SAT $\leq_{P}$ Hamiltonian Cycle

Exercise (or Cook-Levin theorem): Hamiltonian Cycle $\leq_{P}$ 3SAT $\Longrightarrow$ Hamiltonian Cycle $\approx_{P}$ 3SAT
6. Clique $\approx_{p}$ Independent Set $\approx_{p}$ Vertex Cover $\approx_{p}$ 3SAT $\approx_{p}$ SAT $\approx_{p}$ Hamiltonian Cycle

What do we know so far

1. Independent Set $\leq_{P}$ Clique, Clique $\leq_{P}$ Independent Set.
$\Longrightarrow$ Clique $\approx_{p}$ Independent Set.
2. Vertex Cover $\leq_{P}$ Independent Set, Independent Set $\leq_{P}$ Vertex Cover. $\Longrightarrow$ Independent Set $\approx_{p}$ Vertex Cover.
3. $3 \mathrm{SAT} \leq_{P}$ SAT, SAT $\leq_{P}$ 3SAT $\Longrightarrow$ 3SAT $\approx_{P}$ SAT.
4. 3 SAT $\leq_{p}$ Independent Set .

Exercise (or Cook-Levin theorem): Independent Set $\leq_{p}$ SAT
$\Longrightarrow$ 3SAT $\approx_{P}$ Independent Set.
5. SAT $\leq_{P}$ Hamiltonian Cycle

Exercise (or Cook-Levin theorem): Hamiltonian Cycle $\leq_{P}$ 3SAT
$\Longrightarrow$ Hamiltonian Cycle $\approx_{p}$ 3SAT
6. Clique ${\underset{\sim}{P}}$ Independent Set ${\underset{\sim}{P}}$ Vertex Cover ${\underset{\sim}{P}}_{P}$ 3SAT $\approx_{P}$ SAT $\approx_{P}$ Hamiltonian Cycle

## NP Completeness

## Clique $\approx_{p}$ Independent Set $\approx_{p}$ Vertex Cover $\approx_{p} 3$ SAT $\approx_{p}$ SAT $\approx_{p}$ Hamiltonian Cycle

## All these problems are in NP.

SAT is NPC.

All these problems are NP-Complete.

## NP Completeness

# Clique $\approx_{p}$ Independent Set $\approx_{p}$ Vertex Cover $\approx_{p} 3$ SAT $\approx_{p}$ SAT $\approx_{p}$ Hamiltonian Cycle 

All these problems are in NP.

## SAT is NPC

All these problems are NP-Complete.

## NP Completeness

# Clique $\approx_{p}$ Independent Set $\approx_{p}$ Vertex Cover $\approx_{p} 3$ SAT $\approx_{p}$ SAT $\approx_{p}$ Hamiltonian Cycle 

All these problems are in NP.

SAT is NPC.

All these problems are NP-Complete.

## NP Completeness

# Clique $\approx_{p}$ Independent Set $\approx_{p}$ Vertex Cover $\approx_{p} 3$ SAT $\approx_{p}$ SAT $\approx_{p}$ Hamiltonian Cycle 

All these problems are in NP.

## SAT is NPC.

All these problems are NP-Complete.

## THE END

(for now)

## Algorithms \& Models of Computation

## CS/ECE 374, Fall 2020

24.2

Circuit SAT

Algorithms \& Models of Computation

## CS/ECE 374, Fall 2020

24.2.1

The circuit satisfiability (CSAT) problem

## Circuits

## Definition 24.1.

A circuit is a directed acyclic graph with


1. Input vertices (without incoming edges) labelled with $\mathbf{0}, \mathbf{1}$ or a distinct variable.
2. Every other vertex is labelled $\vee, \wedge$ or ᄀ.
3. Single node output vertex with no outgoing edges.
[^0]
## Circuits

## Definition 24.1.

A circuit is a directed acyclic graph with


1. Input vertices (without incoming edges) labelled with $\mathbf{0}, \mathbf{1}$ or a distinct variable.
2. Every other vertex is labelled $\vee, \wedge$ or $\neg$.
3. Single node output vertex with no outgoing edges.

Can safely assume every node has at most two incoming edges.

## CSAT: Circuit Satisfaction

## Definition 24.2 (Circuit Satisfaction (CSAT).).

Given a circuit as input, is there an assignment to the input variables that causes the output to get value $\mathbf{1}$ ?

## CSAT: Circuit Satisfaction

## Definition 24.2 (Circuit Satisfaction (CSAT).).

Given a circuit as input, is there an assignment to the input variables that causes the output to get value $\mathbf{1 ?}$

## Claim 24.3.

CSAT is in NP.

1. Certificate: Assignment to input variables.
2. Certifier: Evaluate the value of each gate in a topological sort of DAG and check the output gate value.

## Circuit SAT vs SAT

CNF formulas are a rather restricted form of Boolean formulas.

Circuits are a much more powerful (and hence easier) way to express Boolean formulas

However they are equivalent in terms of polynomial-time solvability.

## Circuit SAT vs SAT

CNF formulas are a rather restricted form of Boolean formulas.

Circuits are a much more powerful (and hence easier) way to express Boolean formulas

However they are equivalent in terms of polynomial-time solvability.

## Converting a CNF formula into a Circuit

 $3 S A T \leq_{p}$ CSATGiven 3CNF formula $\boldsymbol{\varphi}$ with $\boldsymbol{n}$ variables and $\boldsymbol{m}$ clauses, create a Circuit $\boldsymbol{C}$.

- Inputs to $C$ are the $\boldsymbol{n}$ boolean variables $x_{1}, x_{2}, \ldots, x_{n}$
- Use NOT gate to generate literal $\neg \boldsymbol{x}_{\boldsymbol{i}}$ for each variable $\boldsymbol{x}_{\boldsymbol{i}}$
- For each clause ( $\ell_{1} \vee \ell_{2} \vee \ell_{3}$ ) use two OR gates to mimic formula
- Combine the outputs for the clauses using AND gates to obtain the final output


## Example

## 3SAT $\leq_{p}$ CSAT

$$
\varphi=\left(x_{1} \vee \vee x_{3} \vee x_{4}\right) \wedge\left(x_{1} \vee \neg x_{2} \vee \neg x_{3}\right) \wedge\left(\neg x_{2} \vee \neg x_{3} \vee x_{4}\right)
$$

## Example

## $3 S A T \leq_{p}$ CSAT

$$
\varphi=\left(x_{1} \vee \vee x_{3} \vee x_{4}\right) \wedge\left(x_{1} \vee \neg x_{2} \vee \neg x_{3}\right) \wedge\left(\neg x_{2} \vee \neg x_{3} \vee x_{4}\right)
$$



## Example

## $3 S A T \leq_{p}$ CSAT

$$
\varphi=\left(x_{1} \vee \vee x_{3} \vee x_{4}\right) \wedge\left(x_{1} \vee \neg x_{2} \vee \neg x_{3}\right) \wedge\left(\neg x_{2} \vee \neg x_{3} \vee x_{4}\right)
$$



## Example

## $3 S A T \leq_{p}$ CSAT

$$
\varphi=\left(x_{1} \vee \vee x_{3} \vee x_{4}\right) \wedge\left(x_{1} \vee \neg x_{2} \vee \neg x_{3}\right) \wedge\left(\neg x_{2} \vee \neg x_{3} \vee x_{4}\right)
$$



## Example

## $3 S A T \leq_{p}$ CSAT

$$
\varphi=\left(x_{1} \vee \vee x_{3} \vee x_{4}\right) \wedge\left(x_{1} \vee \neg x_{2} \vee \neg x_{3}\right) \wedge\left(\neg x_{2} \vee \neg x_{3} \vee x_{4}\right)
$$



## Example

## $3 S A T \leq_{p}$ CSAT

$$
\varphi=\left(x_{1} \vee \vee x_{3} \vee x_{4}\right) \wedge\left(x_{1} \vee \neg x_{2} \vee \neg x_{3}\right) \wedge\left(\neg x_{2} \vee \neg x_{3} \vee x_{4}\right)
$$



## Example

## $3 S A T \leq_{p}$ CSAT

$$
\varphi=\left(x_{1} \vee \vee x_{3} \vee x_{4}\right) \wedge\left(x_{1} \vee \neg x_{2} \vee \neg x_{3}\right) \wedge\left(\neg x_{2} \vee \neg x_{3} \vee x_{4}\right)
$$



## Example

## $3 S A T \leq_{p}$ CSAT

$$
\varphi=\left(x_{1} \vee \vee x_{3} \vee x_{4}\right) \wedge\left(x_{1} \vee \neg x_{2} \vee \neg x_{3}\right) \wedge\left(\neg x_{2} \vee \neg x_{3} \vee x_{4}\right)
$$



## 3 SAT $\leq_{p}$ CSAT

Lemma 24.4.
$S A T \leq_{p} 3 S A T \leq_{p} C S A T$.

## THE END

(for now)

Algorithms \& Models of Computation

## CS/ECE 374, Fall 2020

### 24.2.2

Towards reducing CSAT to 3SAT

Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ |  |  |  |  |
| :--- | :--- | :--- | :--- | :---: | :---: | :---: |

Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ | $z=x \wedge \boldsymbol{y}$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |

Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ | $z=x \wedge y$ |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 |
| 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 0 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 1 | 0 | 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 | 1 | 0 | 1 | 1 |
| 1 | 0 | 1 | 0 | 1 | 1 | 0 | 1 |
| 1 | 1 | 0 | 0 | 1 | 1 | 1 | 0 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ | $z=x \wedge y$ | $z \vee \bar{x}$ vee $\bar{y}$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 |
| 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 0 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 1 | 0 | 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 | 1 | 0 | 1 | 1 |
| 1 | 0 | 1 | 0 | 1 | 1 | 0 | 1 |
| 1 | 1 | 0 | 0 | 1 | 1 | 1 | 0 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ | $z=x \wedge y$ | $z \vee \bar{x}$ vee $\bar{y}$ | $\bar{z} \vee x \vee y$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 |
| 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 0 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 1 | 0 | 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 | 1 | 0 | 1 | 1 |
| 1 | 0 | 1 | 0 | 1 | 1 | 0 | 1 |
| 1 | 1 | 0 | 0 | 1 | 1 | 1 | 0 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ | $z=x \wedge y \vee \bar{x}$ vee $\bar{y}$ | $\bar{z} \vee x \vee y$ | $\bar{z} \vee x \vee \bar{y}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 |
| 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 0 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 1 | 0 | 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 | 1 | 0 | 1 | 1 |
| 1 | 0 | 1 | 0 | 1 | 1 | 0 | 1 |
| 1 | 1 | 0 | 0 | 1 | 1 | 1 | 0 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

## Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ | $z=x \wedge y$ | $z \vee \bar{x}$ vee $\bar{y}$ | $\bar{z} \vee x \vee y$ | $\bar{z} \vee x \vee \bar{y}$ | $\bar{z} \vee \bar{x} \vee y$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 |
| 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 0 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 1 | 0 | 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 | 1 | 0 | 1 | 1 |
| 1 | 0 | 1 | 0 | 1 | 1 | 0 | 1 |
| 1 | 1 | 0 | 0 | 1 | 1 | 1 | 0 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ | $z=x \wedge y$ | $z \vee \bar{x}$ vee $\bar{y}$ | $\bar{z} \vee x \vee y$ | $\bar{z} \vee x \vee \bar{y}$ | $\bar{z} \vee \bar{x} \vee y$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 |
| 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 0 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 1 | 0 | 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 | 1 | 0 | 1 | 1 |
| 1 | 0 | 1 | 0 | 1 | 1 | 0 | 1 |
| 1 | 1 | 0 | 0 | 1 | 1 | 1 | 0 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

## Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ | $z=x \wedge y$ | $z \vee \bar{x}$ vee $\bar{y}$ | $\bar{z} \vee x \vee y$ | $\bar{z} \vee x \vee \bar{y}$ | $\bar{z} \vee \bar{x} \vee y$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 |
| 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 0 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 1 | 0 | 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 | 1 | 0 | 1 | 1 |
| 1 | 0 | 1 | 0 | 1 | 1 | 0 | 1 |
| 1 | 1 | 0 | 0 | 1 | 1 | 1 | 0 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

$$
\begin{aligned}
& (z=x \wedge y) \\
& \equiv \\
& (z \vee \bar{x} \vee \bar{y}) \wedge(\bar{z} \vee x \vee y) \wedge(\bar{z} \vee x \vee \bar{y}) \wedge(\bar{z} \vee \bar{x} \vee y)
\end{aligned}
$$

Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

| $z z$ | $x$ | $y$ | $\|l\| l \mid$ |  |
| :--- | :--- | :--- | :--- | :--- |
| 0 | 0 | 0 |  |  |
| 0 | 0 | 1 |  |  |
| 0 | 1 | 0 |  |  |
| 0 | 1 | 1 |  |  |
| 1 | 0 | 0 |  |  |
| 1 | 0 | 1 |  |  |
| 1 | 1 | 0 |  |  |
| 1 | 1 | 1 |  |  |

Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ | $z=x \wedge y$ |  |
| :---: | :---: | :---: | :---: | :--- |
| 0 | 0 | 0 | 1 |  |
| 0 | 0 | 1 | 1 |  |
| 0 | 1 | 0 | 1 |  |
| 0 | 1 | 1 | 0 |  |
| 1 | 0 | 0 | 0 |  |
| 1 | 0 | 1 | 0 |  |
| 1 | 1 | 0 | 0 |  |
| 1 | 1 | 1 | 1 |  |

Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ | $z=x \wedge y$ | clauses |
| :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 1 |  |
| 0 | 0 | 1 | 1 |  |
| 0 | 1 | 0 | 1 |  |
| 0 | 1 | 1 | 0 |  |
| 1 | 0 | 0 | 0 |  |
| 1 | 0 | 1 | 0 |  |
| 1 | 1 | 0 | 0 |  |
| 1 | 1 | 1 | 1 |  |

## Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ | $z=x \wedge y$ | clauses |
| :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 1 |  |
| 0 | 0 | 1 | 1 |  |
| 0 | 1 | 0 | 1 |  |
| 0 | 1 | 1 | 0 | $z \vee \bar{x} \vee \bar{y}$ |
| 1 | 0 | 0 | 0 | $\bar{z} \vee x \vee y$ |
| 1 | 0 | 1 | 0 | $\bar{z} \vee x \vee y$ |
| 1 | 1 | 0 | 0 | $\bar{z} \vee x \vee y$ |
| 1 | 1 | 1 | 1 |  |

## Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ | $z=x \wedge y$ | clauses |
| :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 1 |  |
| 0 | 0 | 1 | 1 |  |
| 0 | 1 | 0 | 1 |  |
| 0 | 1 | 1 | 0 | $z \vee \bar{x} \vee \bar{y}$ |
| 1 | 0 | 0 | 0 | $\bar{z} \vee x \vee y$ |
| 1 | 0 | 1 | 0 | $\bar{z} \vee x \vee y$ |
| 1 | 1 | 0 | 0 | $\bar{z} \vee x \vee y$ |
| 1 | 1 | 1 | 1 |  |

$$
\begin{aligned}
& (z=x \wedge y) \\
& \equiv \\
& (z \vee \bar{x} \vee \bar{y}) \wedge(\bar{z} \vee x \vee y) \wedge(\bar{z} \vee x \vee \bar{y}) \wedge(\bar{z} \vee \bar{x} \vee y)
\end{aligned}
$$

## Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

Simplify further if you want to

1. Using that $(\boldsymbol{x} \vee \boldsymbol{y}) \wedge(\boldsymbol{x} \vee \overline{\boldsymbol{y}})=\boldsymbol{x}$, we have that:
$1.2(\overline{\boldsymbol{z}} \vee \boldsymbol{x} \vee \boldsymbol{y}) \wedge(\overline{\boldsymbol{z}} \vee \overline{\boldsymbol{x}} \vee \boldsymbol{y})=(\overline{\boldsymbol{z}} \vee \boldsymbol{y})$
2. Using the above two observation, we have that our formula $\psi \equiv(z \vee \bar{x} \vee \bar{y}) \wedge(\bar{z} \vee x \vee y) \wedge(\bar{z} \vee x \vee \bar{y}) \wedge(\bar{z} \vee \bar{x} \vee y)$ is equivalent to $\psi \equiv(\boldsymbol{z} \vee \overline{\boldsymbol{x}} \vee \overline{\boldsymbol{y}}) \wedge(\overline{\boldsymbol{z}} \vee \boldsymbol{x}) \wedge(\overline{\boldsymbol{z}} \vee \boldsymbol{y})$

## Lemma 24.5.

$$
\equiv(z \vee \bar{x} \vee \bar{y}) \wedge(\bar{z} \vee x) \wedge(\bar{z} \vee y)
$$

## Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

Simplify further if you want to

1. Using that $(\boldsymbol{x} \vee \boldsymbol{y}) \wedge(\boldsymbol{x} \vee \overline{\boldsymbol{y}})=\boldsymbol{x}$, we have that:

$$
\begin{aligned}
& 1.1(\overline{\boldsymbol{z}} \vee \boldsymbol{x} \vee \boldsymbol{u}) \wedge(\overline{\boldsymbol{z}} \vee \boldsymbol{x} \vee \overline{\boldsymbol{y}})=(\overline{\mathbf{z}} \vee \boldsymbol{x}) \\
& 1.2(\overline{\boldsymbol{z}} \vee \boldsymbol{x} \vee \boldsymbol{y}) \wedge(\overline{\boldsymbol{z}} \vee \overline{\boldsymbol{x}} \vee \boldsymbol{y})=(\overline{\boldsymbol{z}} \vee \boldsymbol{y})
\end{aligned}
$$

## 2. Using the above two observation, we have that our formula



## Lemma 24.5

$\equiv(z \vee \bar{x} \vee \bar{y}) \wedge(\bar{z} \vee x) \wedge(\bar{z} \vee y)$

## Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

## Simplify further if you want to

1. Using that $(\boldsymbol{x} \vee \boldsymbol{y}) \wedge(\boldsymbol{x} \vee \overline{\boldsymbol{y}})=\boldsymbol{x}$, we have that:
$1.1(\overline{\boldsymbol{z}} \vee \boldsymbol{x} \vee \boldsymbol{u}) \wedge(\overline{\boldsymbol{z}} \vee \boldsymbol{x} \vee \overline{\boldsymbol{y}})=(\overline{\boldsymbol{z}} \vee \boldsymbol{x})$
$1.2(\overline{\boldsymbol{z}} \vee \boldsymbol{x} \vee \boldsymbol{y}) \wedge(\overline{\boldsymbol{z}} \vee \overline{\boldsymbol{x}} \vee \boldsymbol{y})=(\overline{\boldsymbol{z}} \vee \boldsymbol{y})$
2. Using the above two observation, we have that our formula

$$
\psi \equiv(z \vee \bar{x} \vee \bar{y}) \wedge(\bar{z} \vee x \vee y) \wedge(\bar{z} \vee x \vee \bar{y}) \wedge(\bar{z} \vee \bar{x} \vee y)
$$

is equivalent to $\psi \equiv(z \vee \bar{x} \vee \bar{y}) \wedge(\bar{z} \vee x) \wedge(\bar{z} \vee y)$

## Lemma 24.5

$(z-x \wedge y)=(z \vee \bar{x} \vee \bar{y}) \wedge(\bar{z} \vee x) \wedge(\bar{z} \vee y)$

## Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

## Simplify further if you want to

1. Using that $(\boldsymbol{x} \vee \boldsymbol{y}) \wedge(\boldsymbol{x} \vee \overline{\boldsymbol{y}})=\boldsymbol{x}$, we have that:

$$
\begin{aligned}
& 1.1(\overline{\boldsymbol{z}} \vee \boldsymbol{x} \vee \boldsymbol{u}) \wedge(\overline{\boldsymbol{z}} \vee \boldsymbol{x} \vee \overline{\boldsymbol{y}})=(\overline{\boldsymbol{z}} \vee \boldsymbol{x}) \\
& 1.2(\overline{\boldsymbol{z}} \vee \boldsymbol{x} \vee \boldsymbol{y}) \wedge(\overline{\boldsymbol{z}} \vee \overline{\boldsymbol{x}} \vee \boldsymbol{y})=(\overline{\boldsymbol{z}} \vee \boldsymbol{y})
\end{aligned}
$$

2. Using the above two observation, we have that our formula

$$
\psi \equiv(z \vee \bar{x} \vee \bar{y}) \wedge(\bar{z} \vee x \vee y) \wedge(\bar{z} \vee x \vee \bar{y}) \wedge(\bar{z} \vee \bar{x} \vee y)
$$

$$
\text { is equivalent to } \psi \equiv(\boldsymbol{z} \vee \overline{\boldsymbol{x}} \vee \overline{\boldsymbol{y}}) \wedge(\overline{\boldsymbol{z}} \vee \boldsymbol{x}) \wedge(\overline{\boldsymbol{z}} \vee \boldsymbol{y})
$$

## Converting $\mathbf{z}=\mathbf{x} \wedge \mathbf{y}$ to 3SAT

## Simplify further if you want to

1. Using that $(\boldsymbol{x} \vee \boldsymbol{y}) \wedge(\boldsymbol{x} \vee \overline{\boldsymbol{y}})=\boldsymbol{x}$, we have that:

$$
\begin{aligned}
& 1.1(\overline{\boldsymbol{z}} \vee \boldsymbol{x} \vee \boldsymbol{u}) \wedge(\overline{\boldsymbol{z}} \vee \boldsymbol{x} \vee \overline{\boldsymbol{y}})=(\overline{\boldsymbol{z}} \vee \boldsymbol{x}) \\
& 1.2(\overline{\boldsymbol{z}} \vee \boldsymbol{x} \vee \boldsymbol{y}) \wedge(\overline{\boldsymbol{z}} \vee \overline{\boldsymbol{x}} \vee \boldsymbol{y})=(\overline{\boldsymbol{z}} \vee \boldsymbol{y})
\end{aligned}
$$

2. Using the above two observation, we have that our formula

$$
\psi \equiv(z \vee \bar{x} \vee \bar{y}) \wedge(\bar{z} \vee x \vee y) \wedge(\bar{z} \vee x \vee \bar{y}) \wedge(\bar{z} \vee \bar{x} \vee \boldsymbol{y})
$$

$$
\text { is equivalent to } \psi \equiv(\boldsymbol{z} \vee \overline{\boldsymbol{x}} \vee \overline{\boldsymbol{y}}) \wedge(\overline{\boldsymbol{z}} \vee \boldsymbol{x}) \wedge(\overline{\boldsymbol{z}} \vee \boldsymbol{y})
$$

## Lemma 24.5.

$(z=x \wedge y) \equiv(z \vee \bar{x} \vee \bar{y}) \wedge(\bar{z} \vee x) \wedge(\bar{z} \vee y)$

Converting $\mathbf{z}=\mathbf{x} \vee \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ | $\mid$ |  |
| :--- | :--- | :--- | :--- | :--- |
| 0 | 0 | 0 |  |  |
| 0 | 0 | 1 |  |  |
| 0 | 1 | 0 |  |  |
| 0 | 1 | 1 |  |  |
| 1 | 0 | 0 |  |  |
| 1 | 0 | 1 |  |  |
| 1 | 1 | 0 |  |  |
| 1 | 1 | 1 |  |  |

Converting $\mathbf{z}=\mathbf{x} \vee \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ | $z=x \vee y$ |  |
| :---: | :---: | :---: | :---: | :--- |
| 0 | 0 | 0 | 1 |  |
| 0 | 0 | 1 | 0 |  |
| 0 | 1 | 0 | 0 |  |
| 0 | 1 | 1 | 0 |  |
| 1 | 0 | 0 | 0 |  |
| 1 | 0 | 1 | 1 |  |
| 1 | 1 | 0 | 1 |  |
| 1 | 1 | 1 | 1 |  |

Converting $\mathbf{z}=\mathbf{x} \vee \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ | $z=x \vee y$ | clauses |
| :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 1 |  |
| 0 | 0 | 1 | 0 |  |
| 0 | 1 | 0 | 0 |  |
| 0 | 1 | 1 | 0 |  |
| 1 | 0 | 0 | 0 |  |
| 1 | 0 | 1 | 1 |  |
| 1 | 1 | 0 | 1 |  |
| 1 | 1 | 1 | 1 |  |

## Converting $\mathbf{z}=\mathbf{x} \vee \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ | $z=x \vee y$ | clauses |
| :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 1 |  |
| 0 | 0 | 1 | 0 | $z \vee x \vee \bar{y}$ |
| 0 | 1 | 0 | 0 | $z \vee \bar{x} \vee y$ |
| 0 | 1 | 1 | 0 | $z \vee \bar{x} \vee \bar{y}$ |
| 1 | 0 | 0 | 0 | $\bar{z} \vee x \vee y$ |
| 1 | 0 | 1 | 1 |  |
| 1 | 1 | 0 | 1 |  |
| 1 | 1 | 1 | 1 |  |

## Converting $\mathbf{z}=\mathbf{x} \vee \mathbf{y}$ to 3SAT

| $z$ | $x$ | $y$ | $z=x \vee y$ | clauses |
| :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 1 |  |
| 0 | 0 | 1 | 0 | $z \vee x \vee \bar{y}$ |
| 0 | 1 | 0 | 0 | $z \vee \bar{x} \vee y$ |
| 0 | 1 | 1 | 0 | $z \vee \bar{x} \vee \bar{y}$ |
| 1 | 0 | 0 | 0 | $\bar{z} \vee x \vee y$ |
| 1 | 0 | 1 | 1 |  |
| 1 | 1 | 0 | 1 |  |
| 1 | 1 | 1 | 1 |  |

$$
\begin{aligned}
& (z=x \vee y) \\
& \equiv \\
& (z \vee x \vee \bar{y}) \wedge(z \vee \bar{x} \vee y) \wedge(z \vee \bar{x} \vee \bar{y}) \wedge(\bar{z} \vee x \vee y)
\end{aligned}
$$

## Converting $\mathbf{z}=\mathbf{x} \vee \mathbf{y}$ to 3SAT

Simplify further if you want to
$(z=\boldsymbol{z} \vee \boldsymbol{y}) \equiv(\boldsymbol{z} \vee \boldsymbol{x} \vee \overline{\boldsymbol{y}}) \wedge(\boldsymbol{z} \vee \overline{\boldsymbol{x}} \vee \boldsymbol{y}) \wedge(\boldsymbol{z} \vee \overline{\boldsymbol{x}} \vee \overline{\boldsymbol{y}}) \wedge(\bar{z} \vee \boldsymbol{x} \vee \boldsymbol{y})$

1. Using that $(\boldsymbol{x} \vee \boldsymbol{y}) \wedge(\boldsymbol{x} \vee \overline{\boldsymbol{y}})=\boldsymbol{x}$, we have that:
2. Using the above two observation, we have the following.

## Lemma 24.6.

The formula $z=x \vee y$ is equivalent to the CNF formula

$$
\equiv(z \vee \bar{y}) \wedge(z \vee \bar{x}) \wedge(\bar{z} \vee x \vee y)
$$

## Converting $\mathbf{z}=\mathbf{x} \vee \mathbf{y}$ to 3SAT

Simplify further if you want to
$(z=x \vee y) \equiv(z \vee x \vee \bar{y}) \wedge(z \vee \bar{x} \vee y) \wedge(z \vee \bar{x} \vee \bar{y}) \wedge(\bar{z} \vee x \vee y)$

1. Using that $(\boldsymbol{x} \vee \boldsymbol{y}) \wedge(\boldsymbol{x} \vee \overline{\boldsymbol{y}})=\boldsymbol{x}$, we have that:
$1.1(\boldsymbol{z} \vee \boldsymbol{x} \vee \overline{\boldsymbol{y}}) \wedge(\boldsymbol{z} \vee \overline{\boldsymbol{x}} \vee \overline{\boldsymbol{y}})=\boldsymbol{z} \vee \overline{\boldsymbol{y}}$.
$1.2(\boldsymbol{z} \vee \overline{\boldsymbol{x}} \vee \boldsymbol{y}) \wedge(\boldsymbol{z} \vee \overline{\boldsymbol{x}} \vee \overline{\boldsymbol{y}})=\boldsymbol{z} \vee \overline{\boldsymbol{x}}$
2. Using the above two observation, we have the following.

Lemma 24.6.
The formula $\boldsymbol{z}=\boldsymbol{x} \vee y$ is equivalent to the CNE formula

$$
\equiv(z \vee \bar{y}) \wedge(z \vee \bar{x}) \wedge(\bar{z} \vee x \vee y)
$$

## Converting $\mathbf{z}=\mathbf{x} \vee \mathbf{y}$ to 3SAT

Simplify further if you want to
$(z=x \vee y) \equiv(z \vee x \vee \bar{y}) \wedge(z \vee \bar{x} \vee y) \wedge(z \vee \bar{x} \vee \bar{y}) \wedge(\bar{z} \vee x \vee y)$

1. Using that $(\boldsymbol{x} \vee \boldsymbol{y}) \wedge(\boldsymbol{x} \vee \overline{\boldsymbol{y}})=\boldsymbol{x}$, we have that:
$1.1(\boldsymbol{z} \vee \boldsymbol{x} \vee \overline{\boldsymbol{y}}) \wedge(\boldsymbol{z} \vee \overline{\boldsymbol{x}} \vee \overline{\boldsymbol{y}})=\boldsymbol{z} \vee \overline{\boldsymbol{y}}$.
$1.2(\boldsymbol{z} \vee \overline{\boldsymbol{x}} \vee \boldsymbol{y}) \wedge(\boldsymbol{z} \vee \overline{\boldsymbol{x}} \vee \overline{\boldsymbol{y}})=\boldsymbol{z} \vee \overline{\boldsymbol{x}}$
2. Using the above two observation, we have the following.
$\square$
The formula $\boldsymbol{z}=\boldsymbol{x} \vee \boldsymbol{y}$ is equivalent to the CNF formula $\equiv(z \vee \bar{y}) \wedge(z \vee \bar{x}) \wedge(\bar{z} \vee x \vee y)$

## Converting $\mathbf{z}=\mathbf{x} \vee \mathbf{y}$ to 3SAT

Simplify further if you want to
$(z=x \vee y) \equiv(z \vee x \vee \bar{y}) \wedge(z \vee \bar{x} \vee y) \wedge(z \vee \bar{x} \vee \bar{y}) \wedge(\bar{z} \vee x \vee y)$

1. Using that $(\boldsymbol{x} \vee \boldsymbol{y}) \wedge(\boldsymbol{x} \vee \overline{\boldsymbol{y}})=\boldsymbol{x}$, we have that:
$1.1(z \vee \boldsymbol{x} \vee \overline{\boldsymbol{y}}) \wedge(\boldsymbol{z} \vee \overline{\boldsymbol{x}} \vee \overline{\boldsymbol{y}})=\boldsymbol{z} \vee \overline{\boldsymbol{y}}$.
$1.2(\boldsymbol{z} \vee \overline{\boldsymbol{x}} \vee \boldsymbol{y}) \wedge(\boldsymbol{z} \vee \overline{\boldsymbol{x}} \vee \overline{\boldsymbol{y}})=\boldsymbol{z} \vee \overline{\boldsymbol{x}}$
2. Using the above two observation, we have the following.

## Lemma 24.6.

The formula $\boldsymbol{z}=\boldsymbol{x} \vee \boldsymbol{y}$ is equivalent to the CNF formula $(z=x \vee y) \equiv(z \vee \bar{y}) \wedge(z \vee \bar{x}) \wedge(\bar{z} \vee x \vee y)$

## Converting $\boldsymbol{z}=\overline{\boldsymbol{x}}$ to CNF

Lemma 24.7.
$z=\bar{x} \quad \equiv \quad(z \vee x) \wedge(\bar{z} \vee \bar{x})$.

## Summary of formulas we derived

## Lemma 24.8.

The following identities hold:

1. $z=\bar{x} \quad \equiv \quad(\boldsymbol{z} \vee \boldsymbol{x}) \wedge(\bar{z} \vee \bar{x})$.
2. $(z=\boldsymbol{z} \vee \boldsymbol{y}) \equiv(\boldsymbol{z} \vee \overline{\boldsymbol{y}}) \wedge(\boldsymbol{z} \vee \overline{\boldsymbol{x}}) \wedge(\overline{\boldsymbol{z}} \vee \boldsymbol{x} \vee \boldsymbol{y})$
3. $(\boldsymbol{z}=\boldsymbol{x} \wedge \boldsymbol{y}) \equiv(\boldsymbol{z} \vee \overline{\boldsymbol{x}} \vee \overline{\boldsymbol{y}}) \wedge(\bar{z} \vee \boldsymbol{x}) \wedge(\overline{\boldsymbol{z}} \vee \boldsymbol{y})$

## THE END

(for now)

Algorithms \& Models of Computation

## CS/ECE 374, Fall 2020

### 24.2.3

Reduction from CSAT to SAT

## Converting a circuit into a CNF formula

## Label the nodes


(A) Input circuit

(B) Label the nodes.

## Converting a circuit into a CNF formula

Introduce a variable for each node

(B) Label the nodes.

(C) Introduce var for each node.

## Converting a circuit into a CNF formula

Write a sub-formula for each variable that is true if the var is computed correctly.

$$
\begin{aligned}
& x_{k} \quad(\text { Demand a sat' assignment!) } \\
& x_{k}=\boldsymbol{x}_{\boldsymbol{i}} \wedge \boldsymbol{x}_{\boldsymbol{j}} \\
& \boldsymbol{x}_{\boldsymbol{j}}=\boldsymbol{x}_{\boldsymbol{g}} \wedge \boldsymbol{x}_{\boldsymbol{h}} \\
& \boldsymbol{x}_{\boldsymbol{i}}=\neg \boldsymbol{x}_{\boldsymbol{f}} \\
& \boldsymbol{x}_{\boldsymbol{h}}=\boldsymbol{x}_{\boldsymbol{d}} \vee \boldsymbol{x}_{\boldsymbol{e}} \\
& \boldsymbol{x}_{\boldsymbol{g}}=\boldsymbol{x}_{\boldsymbol{b}} \vee \boldsymbol{x}_{\boldsymbol{c}} \\
& \boldsymbol{x}_{\boldsymbol{f}}=\boldsymbol{x}_{\boldsymbol{a}} \wedge \boldsymbol{x}_{\boldsymbol{b}} \\
& \boldsymbol{x}_{\boldsymbol{d}}=\mathbf{0} \\
& \boldsymbol{x}_{\boldsymbol{a}}=\mathbf{1}
\end{aligned}
$$

(D) Write a sub-formula for each variable that is true if the var is computed correctly.

## Converting a circuit into a CNF formula

## Convert each sub-formula to an equivalent CNF formula

| $\chi_{k}$ | $x_{k}$ |
| :---: | :---: |
| $x_{k}=x_{i} \wedge x_{j}$ | $\left(\neg x_{k} \vee x_{i}\right) \wedge\left(\neg x_{k} \vee x_{j}\right) \wedge\left(x_{k} \vee \neg x_{i} \vee \neg x_{j}\right)$ |
| $x_{j}=x_{g} \wedge x_{h}$ | $\left(\neg x_{j} \vee x_{g}\right) \wedge\left(\neg x_{j} \vee x_{h}\right) \wedge\left(x_{j} \vee \neg x_{g} \vee \neg x_{h}\right)$ |
| $x_{i}=\neg x_{f}$ | $\left(x_{i} \vee x_{f}\right) \wedge\left(\neg x_{i} \vee \neg x_{f}\right)$ |
| $x_{h}=x_{d} \vee x_{e}$ | $\left(x_{h} \vee \neg x_{d}\right) \wedge\left(x_{h} \vee \neg x_{e}\right) \wedge\left(\neg x_{h} \vee x_{d} \vee x_{e}\right)$ |
| $x_{g}=x_{b} \vee x_{c}$ | $\left(x_{g} \vee \neg x_{b}\right) \wedge\left(x_{g} \vee \neg x_{c}\right) \wedge\left(\neg x_{g} \vee x_{b} \vee x_{c}\right)$ |
| $x_{f}=x_{a} \wedge x_{b}$ | $\left(\neg x_{f} \vee x_{a}\right) \wedge\left(\neg x_{f} \vee x_{b}\right) \wedge\left(x_{f} \vee \neg x_{a} \vee \neg x_{b}\right)$ |
| $x_{d}=0$ | $\neg x_{d}$ |
| $x_{a}=1$ | $x_{a}$ |

## From Lemma 24.8

## Converting a circuit into a CNF formula

## Convert each sub-formula to an equivalent CNF formula

| $\boldsymbol{x}_{\boldsymbol{k}}$ | $\boldsymbol{x}_{\boldsymbol{k}}$ |
| :---: | :---: |
| $\boldsymbol{x}_{\boldsymbol{k}}=\boldsymbol{x}_{\boldsymbol{i}} \wedge \boldsymbol{x}_{\boldsymbol{j}}$ | $\left(\neg \boldsymbol{x}_{\boldsymbol{k}} \vee \boldsymbol{x}_{\boldsymbol{i}}\right) \wedge\left(\neg \boldsymbol{x}_{\boldsymbol{k}} \vee \boldsymbol{x}_{\boldsymbol{j}}\right) \wedge\left(\boldsymbol{x}_{\boldsymbol{k}} \vee \neg \boldsymbol{x}_{\boldsymbol{i}} \vee \neg \boldsymbol{x}_{\boldsymbol{j}}\right)$ |
| $\boldsymbol{x}_{\boldsymbol{j}}=\boldsymbol{x}_{\boldsymbol{g}} \wedge \boldsymbol{x}_{\boldsymbol{h}}$ | $\left(\neg \boldsymbol{x}_{\boldsymbol{j}} \vee \boldsymbol{x}_{\boldsymbol{g}}\right) \wedge\left(\neg \boldsymbol{x}_{\boldsymbol{j}} \vee \boldsymbol{x}_{\boldsymbol{h}}\right) \wedge\left(\boldsymbol{x}_{\boldsymbol{j}} \vee \neg \boldsymbol{x}_{\boldsymbol{g}} \vee \neg \boldsymbol{x}_{\boldsymbol{h}}\right)$ |
| $\boldsymbol{x}_{\boldsymbol{i}}=\neg \boldsymbol{x}_{\boldsymbol{f}}$ | $\left(\boldsymbol{x}_{\boldsymbol{i}} \vee \boldsymbol{x}_{\boldsymbol{f}}\right) \wedge\left(\neg \boldsymbol{x}_{\boldsymbol{i}} \vee \neg \boldsymbol{x}_{\boldsymbol{f}}\right)$ |
| $\boldsymbol{x}_{\boldsymbol{h}}=\boldsymbol{x}_{\boldsymbol{d}} \vee \boldsymbol{x}_{\boldsymbol{e}}$ | $\left(\boldsymbol{x}_{\boldsymbol{h}} \vee \neg \boldsymbol{x}_{\boldsymbol{d}}\right) \wedge\left(\boldsymbol{x}_{\boldsymbol{h}} \vee \neg \boldsymbol{x}_{\boldsymbol{e}}\right) \wedge\left(\neg \boldsymbol{x}_{\boldsymbol{h}} \vee \boldsymbol{x}_{\boldsymbol{d}} \vee \boldsymbol{x}_{\boldsymbol{e}}\right)$ |
| $\boldsymbol{x}_{\boldsymbol{g}}=\boldsymbol{x}_{\boldsymbol{b}} \vee \boldsymbol{x}_{\boldsymbol{c}}$ | $\left(\boldsymbol{x}_{\boldsymbol{g}} \vee \neg \boldsymbol{x}_{\boldsymbol{b}}\right) \wedge\left(\boldsymbol{x}_{\boldsymbol{g}} \vee \neg \boldsymbol{x}_{\boldsymbol{c}}\right) \wedge\left(\neg \boldsymbol{x}_{\boldsymbol{g}} \vee \boldsymbol{x}_{\boldsymbol{b}} \vee \boldsymbol{x}_{\boldsymbol{c}}\right)$ |
| $\boldsymbol{x}_{\boldsymbol{f}}=\boldsymbol{x}_{\boldsymbol{a}} \wedge \boldsymbol{x}_{\boldsymbol{b}}$ | $\left(\neg \boldsymbol{x}_{\boldsymbol{f}} \vee \boldsymbol{x}_{\boldsymbol{a}}\right) \wedge\left(\neg \boldsymbol{x}_{\boldsymbol{f}} \vee \boldsymbol{x}_{\boldsymbol{b}}\right) \wedge\left(\boldsymbol{x}_{\boldsymbol{f}} \vee \neg \boldsymbol{x}_{\boldsymbol{a}} \vee \neg \boldsymbol{x}_{\boldsymbol{b}}\right)$ |
| $\boldsymbol{x}_{\boldsymbol{d}}=\mathbf{0}$ | $\neg \neg \boldsymbol{x}_{\boldsymbol{d}}$ |
| $\boldsymbol{x}_{\boldsymbol{a}}=\mathbf{1}$ | $\boldsymbol{x}_{\boldsymbol{a}}$ |

From Lemma 24.8 :

1. $z=\bar{x} \quad \equiv \quad(z \vee x) \wedge(\bar{z} \vee \bar{x})$
2. $(\boldsymbol{z}=\boldsymbol{x} \vee \boldsymbol{y}) \equiv(\boldsymbol{z} \vee \overline{\boldsymbol{y}}) \wedge(\boldsymbol{z} \vee \overline{\boldsymbol{x}}) \wedge(\overline{\boldsymbol{z}} \vee \boldsymbol{x} \vee \boldsymbol{y})$
3. $(\boldsymbol{z}=\boldsymbol{x} \wedge \boldsymbol{y}) \equiv(\boldsymbol{z} \vee \overline{\boldsymbol{x}} \vee \overline{\boldsymbol{y}}) \wedge(\overline{\boldsymbol{z}} \vee \boldsymbol{x}) \wedge(\overline{\boldsymbol{z}} \vee \boldsymbol{y})$

## Converting a circuit into a CNF formula

Take the conjunction of all the CNF sub-formulas


$$
\begin{aligned}
& x_{k} \wedge\left(\neg x_{k} \vee x_{i}\right) \wedge\left(\neg x_{k} \vee x_{j}\right) \\
& \wedge\left(x_{k} \vee \neg x_{i} \vee \neg x_{j}\right) \wedge\left(\neg x_{j} \vee x_{g}\right) \\
& \wedge\left(\neg x_{j} \vee x_{h}\right) \wedge\left(x_{j} \vee \neg x_{g} \vee \neg x_{h}\right) \\
& \wedge\left(x_{i} \vee x_{f}\right) \wedge\left(\neg x_{i} \vee \neg x_{f}\right) \\
& \wedge\left(x_{h} \vee \neg x_{d}\right) \wedge\left(x_{h} \vee \neg x_{e}\right) \\
& \wedge\left(\neg x_{h} \vee x_{d} \vee x_{e}\right) \wedge\left(x_{g} \vee \neg x_{b}\right) \\
& \wedge\left(x_{g} \vee \neg x_{c}\right) \wedge\left(\neg x_{g} \vee x_{b} \vee x_{c}\right) \\
& \wedge\left(\neg x_{f} \vee x_{a}\right) \wedge\left(\neg x_{f} \vee x_{b}\right) \\
& \wedge\left(x_{f} \vee \neg x_{a} \vee \neg x_{b}\right) \wedge\left(\neg x_{d}\right) \wedge x_{a}
\end{aligned}
$$

We got a CNF formula that is satisfiable if and only if the original circuit is satisfiable.

## Correctness of Reduction

Need to show circuit $C$ is satisfiable if and only if $\varphi_{C}$ is satisfiable
$\Rightarrow$ Consider a satisfying assignment a for $\boldsymbol{C}$

1. Find values of all gates in $\boldsymbol{C}$ under $\boldsymbol{a}$
2. Give value of gate $\boldsymbol{v}$ to variable $\boldsymbol{x}_{\boldsymbol{v}}$; call this assignment $\boldsymbol{a}^{\prime}$
3. $\boldsymbol{a}^{\prime}$ satisfies $\varphi_{C}$ (exercise)
$\Leftarrow$ Consider a satisfying assignment $\boldsymbol{a}$ for $\varphi_{C}$
4. Let $\boldsymbol{a}^{\prime}$ be the restriction of $\boldsymbol{a}$ to only the input variables
5. Value of gate $\boldsymbol{v}$ under $\boldsymbol{a}^{\prime}$ is the same as value of $\boldsymbol{x}_{\boldsymbol{v}}$ in $\boldsymbol{a}$
6. Thus, $\boldsymbol{a}^{\prime}$ satisfies $\boldsymbol{C}$

## The result

Lemma 24.9.
$C S A T \leq_{p} S A T \leq_{p} 3 S A T$.
Theorem 24.10.
CSAT is NP-Complete.

## The result

Lemma 24.9.
CSAT $\leq_{p}$ SAT $\leq_{p} 3 S A T$.
Theorem 24.10.
CSAT is NP-Complete.

## THE END

(for now)

Algorithms \& Models of Computation
CS/ECE 374, Fall 2020
24.3

NP-Completeness of Graph Coloring

Algorithms \& Models of Computation CS/ECE 374, Fall 2020
24.3.1

The coloring problem

## Graph Coloring

## Problem: Graph Coloring

Instance: $\boldsymbol{G}=(\boldsymbol{V}, \boldsymbol{E})$ : Undirected graph, integer $\boldsymbol{k}$.
Question: Can the vertices of the graph be colored using $\boldsymbol{k}$ colors so that vertices connected by an edge do not get the same color?

## Graph 3-Coloring

## Problem: 3 Coloring

Instance: $\boldsymbol{G}=(\boldsymbol{V}, \boldsymbol{E})$ : Undirected graph.
Question: Can the vertices of the graph be colored using 3 colors so that vertices connected by an edge do not get the same color?


## Graph 3-Coloring

## Problem: 3 Coloring

Instance: $\boldsymbol{G}=(\boldsymbol{V}, \boldsymbol{E})$ : Undirected graph.
Question: Can the vertices of the graph be colored using 3 colors so that vertices connected by an edge do not get the same color?


## Graph Coloring

1. Observation: If $G$ is colored with $\boldsymbol{k}$ colors then each color class (nodes of same color) form an independent set in $G$.
2. $G$ can be partitioned into $k$ independent sets $\Longleftrightarrow G$ is $k$-colorable.
3. Graph 2-Coloring can be decided in polynomial time.
4. $G$ is 2 -colorable $\Longleftrightarrow G$ is bipartite.
5. There is a linear time algorithm to check if $G$ is bipartite using BFS (we saw this earlier)

## Graph Coloring

1. Observation: If $G$ is colored with $\boldsymbol{k}$ colors then each color class (nodes of same color) form an independent set in $G$.
2. $G$ can be partitioned into $\boldsymbol{k}$ independent sets $\Longleftrightarrow G$ is $\boldsymbol{k}$-colorable.
3. Graph 2-Coloring can be decided in polynomial time.
4. $G$ is 2 -colorable $\Longleftrightarrow G$ is bipartite.
5. There is a linear time algorithm to check if $G$ is bipartite using BFS (we saw this earlier)

## Graph Coloring

1. Observation: If $G$ is colored with $\boldsymbol{k}$ colors then each color class (nodes of same color) form an independent set in $G$.
2. $G$ can be partitioned into $\boldsymbol{k}$ independent sets $\Longleftrightarrow G$ is $\boldsymbol{k}$-colorable.
3. Graph 2-Coloring can be decided in polynomial time.
4. $G$ is 2-colorable $\Longleftrightarrow G$ is bipartite.
5. There is a linear time algorithm to check if $G$ is bipartite using BFS (we saw this earlier).

## Graph Coloring

1. Observation: If $G$ is colored with $\boldsymbol{k}$ colors then each color class (nodes of same color) form an independent set in $G$.
2. $G$ can be partitioned into $\boldsymbol{k}$ independent sets $\Longleftrightarrow G$ is $\boldsymbol{k}$-colorable.
3. Graph 2-Coloring can be decided in polynomial time.
4. $G$ is 2 -colorable $\Longleftrightarrow G$ is bipartite.
5. There is a linear time algorithm to check if $G$ is bipartite using BFS (we saw this earlier)

## Graph Coloring

1. Observation: If $G$ is colored with $\boldsymbol{k}$ colors then each color class (nodes of same color) form an independent set in $G$.
2. $G$ can be partitioned into $\boldsymbol{k}$ independent sets $\Longleftrightarrow G$ is $\boldsymbol{k}$-colorable.
3. Graph 2-Coloring can be decided in polynomial time.
4. $G$ is 2 -colorable $\Longleftrightarrow G$ is bipartite.
5. There is a linear time algorithm to check if $G$ is bipartite using BFS (we saw this earlier).

## THE END

(for now)

Algorithms \& Models of Computation
CS/ECE 374, Fall 2020
24.3.2

Problems related to graph coloring

## Register allocation during compilation

1. When a compiler generates the assembly/VM code it needs to allocation registers to values being handled.
2. Need to make sure registers are not in conflict.
3. Build a conflict graph.
4. Color the conflict graph.
5. Every color is a register.
6. If not enough registers, then use memory/stack to store values.
7. CISC v.s. RISC

## Register allocation during compilation

1. When a compiler generates the assembly/VM code it needs to allocation registers to values being handled.
2. Need to make sure registers are not in conflict.
3. Build a conflict graph.
4. Color the conflict graph.
5. Every color is a register.
6. If not enough registers, then use memory/stack to store values.
7. CISC v.s. RISC.

## Graph Coloring and Register Allocation

## Register Allocation

Assign variables to (at most) $\boldsymbol{k}$ registers such that variables needed at the same time are not assigned to the same register

## Interference Graph

Vertices are variables, and there is an edge between two vertices, if the two variables are "live" at the same time.

## Observations

- [Chaitin] Register allocation problem is equivalent to coloring the interference graph with $\boldsymbol{k}$ colors
- Moreover, 3 -COLOR $\leq_{P}$ k-Register Allocation, for any $\boldsymbol{k} \geq \mathbf{3}$


## Class Room Scheduling

1. Given $\boldsymbol{n}$ classes and their meeting times, are $\boldsymbol{k}$ rooms sufficient?
2. Reduce to Graph k-Coloring problem
3. Create graph G

- a node $\boldsymbol{v}_{i}$ for each class $i$
$>$ an edge between $v_{i}$ and $v_{j}$ if classes $i$ and $j$ conflict

4. Exercise: $G$ is $\boldsymbol{k}$-colorable $\Longleftrightarrow \boldsymbol{k}$ rooms are sufficient.

## Class Room Scheduling

1. Given $\boldsymbol{n}$ classes and their meeting times, are $\boldsymbol{k}$ rooms sufficient?
2. Reduce to Graph $\boldsymbol{k}$-Coloring problem
3. Create graph G

- a node $\boldsymbol{v}_{\boldsymbol{i}}$ for each class $\boldsymbol{i}$
- an edge between $\boldsymbol{v}_{\boldsymbol{i}}$ and $\boldsymbol{v}_{\boldsymbol{j}}$ if classes $i$ and $j$ conflict

4. Exercise: $G$ is $k$-colorable $\Longleftrightarrow k$ rooms are sufficient

## Class Room Scheduling

1. Given $\boldsymbol{n}$ classes and their meeting times, are $\boldsymbol{k}$ rooms sufficient?
2. Reduce to Graph $\boldsymbol{k}$-Coloring problem
3. Create graph $G$

- a node $\boldsymbol{v}_{\boldsymbol{i}}$ for each class $\boldsymbol{i}$
- an edge between $\boldsymbol{v}_{\boldsymbol{i}}$ and $\boldsymbol{v}_{\boldsymbol{j}}$ if classes $\boldsymbol{i}$ and $\boldsymbol{j}$ conflict

4. Exercise: $G$ is $k$-colorable $\Longleftrightarrow k$ rooms are sufficient

## Class Room Scheduling

1. Given $\boldsymbol{n}$ classes and their meeting times, are $\boldsymbol{k}$ rooms sufficient?
2. Reduce to Graph $\boldsymbol{k}$-Coloring problem
3. Create graph $G$

- a node $\boldsymbol{v}_{\boldsymbol{i}}$ for each class $\boldsymbol{i}$
- an edge between $\boldsymbol{v}_{\boldsymbol{i}}$ and $\boldsymbol{v}_{\boldsymbol{j}}$ if classes $\boldsymbol{i}$ and $\boldsymbol{j}$ conflict

4. Exercise: $G$ is $\boldsymbol{k}$-colorable $\Longleftrightarrow \boldsymbol{k}$ rooms are sufficient.

## Frequency Assignments in Cellular Networks

1. Cellular telephone systems that use Frequency Division Multiple Access (FDMA) (example: GSM in Europe and Asia and AT\&T in USA)

- Breakup a frequency range $[\boldsymbol{a}, \boldsymbol{b}]$ into disjoint bands of frequencies $\left[a_{0}, b_{0}\right],\left[a_{1}, b_{1}\right], \ldots,\left[a_{k}, b_{k}\right]$
- Each cell phone tower (simplifying) gets one band
- Constraint: nearby towers cannot be assigned same band, otherwise signals will interference

2. Problem: given $k$ bands and some region with $n$ towers, is there a way to assign the bands to avoid interference?
3. Can reduce to $k$-coloring by creating interference/conflict graph on towers.

## Frequency Assignments in Cellular Networks

1. Cellular telephone systems that use Frequency Division Multiple Access (FDMA) (example: GSM in Europe and Asia and AT\&T in USA)

- Breakup a frequency range $[\boldsymbol{a}, \boldsymbol{b}]$ into disjoint bands of frequencies $\left[a_{0}, b_{0}\right],\left[a_{1}, b_{1}\right], \ldots,\left[a_{k}, b_{k}\right]$
- Each cell phone tower (simplifying) gets one band
- Constraint: nearby towers cannot be assigned same band, otherwise signals will interference

2. Problem: given $\boldsymbol{k}$ bands and some region with $\boldsymbol{n}$ towers, is there a way to assign the bands to avoid interference?
3. Can reduce to $k$-coloring by creating interference/conflict graph on towers.

## Frequency Assignments in Cellular Networks

1. Cellular telephone systems that use Frequency Division Multiple Access (FDMA) (example: GSM in Europe and Asia and AT\&T in USA)

- Breakup a frequency range $[\boldsymbol{a}, \boldsymbol{b}]$ into disjoint bands of frequencies $\left[a_{0}, b_{0}\right],\left[a_{1}, b_{1}\right], \ldots,\left[a_{k}, b_{k}\right]$
- Each cell phone tower (simplifying) gets one band
- Constraint: nearby towers cannot be assigned same band, otherwise signals will interference

2. Problem: given $\boldsymbol{k}$ bands and some region with $\boldsymbol{n}$ towers, is there a way to assign the bands to avoid interference?
3. Can reduce to $\boldsymbol{k}$-coloring by creating interference/conflict graph on towers.

## THE END

(for now)

Algorithms \& Models of Computation CS/ECE 374, Fall 2020

### 24.3.3 <br> Showing NP-Completeness of 3 COLORING

Algorithms \& Models of Computation
CS/ECE 374, Fall 2020
24.3.3.1

The variable assignment gadget

## 3-Coloring is NP-Complete

- 3-Coloring is in NP.
- Certificate: for each node a color from $\{\mathbf{1}, \mathbf{2}, \mathbf{3}\}$.
- Certifier: Check if for each edge ( $\boldsymbol{u}, \boldsymbol{v}$ ), the color of $\boldsymbol{u}$ is different from that of $\boldsymbol{v}$.
- Hardness: We will show 3 -SAT $\leq_{p} 3$-Coloring.


## Reduction idea

1. $\varphi$ : Given 3SAT formula (i.e., 3CNF formula).
2. $\varphi$ : variables $x_{1}, \ldots, x_{n}$ and clauses $C_{1}, \ldots, C_{m}$
3. Create graph $G_{\varphi}$ s.t. $G_{\varphi}$ 3-colorable $\Longleftrightarrow \varphi$ satisfiable.

## Reduction idea

1. $\varphi$ : Given 3SAT formula (i.e., 3CNF formula).
2. $\varphi$ : variables $x_{1}, \ldots, x_{n}$ and clauses $C_{1}, \ldots, C_{m}$.
3. Create graph $G_{\varphi}$ s.t. $G_{\varphi}$ 3-colorable $\Longleftrightarrow \varphi$ satisfiable.

## Reduction idea

1. $\varphi$ : Given 3SAT formula (i.e., 3CNF formula).
2. $\varphi$ : variables $x_{1}, \ldots, x_{n}$ and clauses $C_{1}, \ldots, C_{m}$.
3. Create graph $\boldsymbol{G}_{\varphi}$ s.t. $\boldsymbol{G}_{\varphi}$ 3-colorable $\Longleftrightarrow \varphi$ satisfiable.

- encode assignment $\boldsymbol{x}_{1}, \ldots, \boldsymbol{x}_{\boldsymbol{n}}$ in colors assigned nodes of $\boldsymbol{G}_{\varphi}$.
- for each variable $\boldsymbol{x}_{\boldsymbol{i}}$ two nodes $\boldsymbol{v}_{\boldsymbol{i}}$ and $\overline{\boldsymbol{v}}_{\boldsymbol{i}}$ connected in a triangle with common Base - If graph is 3-colored, either $\boldsymbol{v}_{\boldsymbol{i}}$ or $\overline{\boldsymbol{v}}_{\boldsymbol{i}}$ gets the same color as True. Interpret this as a truth assignment to $v_{i}$
- Need to add constraints to ensure clauses are satisfied (next phase)


## Reduction idea

1. $\varphi$ : Given 3SAT formula (i.e., 3CNF formula).
2. $\varphi$ : variables $x_{1}, \ldots, x_{n}$ and clauses $C_{1}, \ldots, C_{m}$.
3. Create graph $\boldsymbol{G}_{\varphi}$ s.t. $\boldsymbol{G}_{\varphi}$ 3-colorable $\Longleftrightarrow \varphi$ satisfiable.

- encode assignment $\boldsymbol{x}_{1}, \ldots, \boldsymbol{x}_{\boldsymbol{n}}$ in colors assigned nodes of $\boldsymbol{G}_{\varphi}$.
- create triangle with node True, False, Base
$\rightarrow$ for each variable $x_{i}$ two nodes $v_{i}$ and $\bar{v}_{i}$ connected in a triangle with common Base $\rightarrow$ If graph is 3-colored, either $\boldsymbol{v}_{\boldsymbol{i}}$ or $\overline{\boldsymbol{v}}_{\boldsymbol{i}}$ gets the same color as True. Interpret this as a truth assignment to $\boldsymbol{v}_{\boldsymbol{i}}$
$\rightarrow$ Need to add constraints to ensure clauses are satisfied (next phase)


## Reduction idea

1. $\varphi$ : Given 3SAT formula (i.e., 3CNF formula).
2. $\varphi$ : variables $x_{1}, \ldots, x_{n}$ and clauses $C_{1}, \ldots, C_{m}$.
3. Create graph $\boldsymbol{G}_{\varphi}$ s.t. $\boldsymbol{G}_{\varphi}$ 3-colorable $\Longleftrightarrow \varphi$ satisfiable.

- encode assignment $\boldsymbol{x}_{1}, \ldots, \boldsymbol{x}_{\boldsymbol{n}}$ in colors assigned nodes of $\boldsymbol{G}_{\varphi}$.
- create triangle with node True, False, Base
- for each variable $\boldsymbol{x}_{\boldsymbol{i}}$ two nodes $\boldsymbol{v}_{\boldsymbol{i}}$ and $\overline{\boldsymbol{v}}_{\boldsymbol{i}}$ connected in a triangle with common Base
truth assignment to $\boldsymbol{v}_{\boldsymbol{i}}$
$\rightarrow$ Need to add constraints to ensure clauses are satisfied (next phase)


## Reduction idea

1. $\varphi$ : Given 3SAT formula (i.e., 3CNF formula).
2. $\varphi$ : variables $x_{1}, \ldots, x_{n}$ and clauses $C_{1}, \ldots, C_{m}$.
3. Create graph $\boldsymbol{G}_{\varphi}$ s.t. $\boldsymbol{G}_{\varphi}$ 3-colorable $\Longleftrightarrow \varphi$ satisfiable.

- encode assignment $\boldsymbol{x}_{1}, \ldots, \boldsymbol{x}_{\boldsymbol{n}}$ in colors assigned nodes of $\boldsymbol{G}_{\varphi}$.
- create triangle with node True, False, Base
- for each variable $\boldsymbol{x}_{\boldsymbol{i}}$ two nodes $\boldsymbol{v}_{\boldsymbol{i}}$ and $\overline{\boldsymbol{v}}_{\boldsymbol{i}}$ connected in a triangle with common Base
- If graph is 3-colored, either $\boldsymbol{v}_{\boldsymbol{i}}$ or $\overline{\boldsymbol{v}}_{\boldsymbol{i}}$ gets the same color as True. Interpret this as a truth assignment to $\boldsymbol{v}_{\boldsymbol{i}}$
$\rightarrow$ Need to add constraints to ensure clauses are satisfied (next phase)


## Reduction idea

1. $\varphi$ : Given 3SAT formula (i.e., 3CNF formula).
2. $\varphi$ : variables $x_{1}, \ldots, x_{n}$ and clauses $C_{1}, \ldots, C_{m}$.
3. Create graph $\boldsymbol{G}_{\varphi}$ s.t. $\boldsymbol{G}_{\varphi}$ 3-colorable $\Longleftrightarrow \varphi$ satisfiable.

- encode assignment $\boldsymbol{x}_{1}, \ldots, \boldsymbol{x}_{\boldsymbol{n}}$ in colors assigned nodes of $\boldsymbol{G}_{\varphi}$.
- create triangle with node True, False, Base
- for each variable $\boldsymbol{x}_{\boldsymbol{i}}$ two nodes $\boldsymbol{v}_{\boldsymbol{i}}$ and $\overline{\boldsymbol{v}}_{\boldsymbol{i}}$ connected in a triangle with common Base
- If graph is 3 -colored, either $\boldsymbol{v}_{\boldsymbol{i}}$ or $\overline{\boldsymbol{v}}_{\boldsymbol{i}}$ gets the same color as True. Interpret this as a truth assignment to $\boldsymbol{v}_{\boldsymbol{i}}$
- Need to add constraints to ensure clauses are satisfied (next phase)

Assignment encoding using 3-coloring


## THE END

(for now)

Algorithms \& Models of Computation CS/ECE 374, Fall 2020

### 24.3.3.2

The clause gadget

## 3 color this gadget.

## Clicker question

You are given three colors: red, green and blue. Can the following graph be three colored in a valid way (assuming the two nodes are already colored as indicated).

(A) Yes.
(B) No.

## 3 color this gadget II

## Clicker question

You are given three colors: red, green and blue. Can the following graph be three colored in a valid way (assuming the two nodes are already colored as indicated).

(A) Yes.
(B) No.

## Clause Satisfiability Gadget

1. For each clause $\boldsymbol{C}_{\boldsymbol{j}}=(\boldsymbol{a} \vee \boldsymbol{b} \vee \boldsymbol{c})$, create a small gadget graph

- gadget graph connects to nodes corresponding to $\boldsymbol{a}, \boldsymbol{b}, \boldsymbol{c}$
- needs to implement OR


## Clause Satisfiability Gadget

1. For each clause $\boldsymbol{C}_{\boldsymbol{j}}=(\boldsymbol{a} \vee \boldsymbol{b} \vee \boldsymbol{c})$, create a small gadget graph

- gadget graph connects to nodes corresponding to $\boldsymbol{a}, \boldsymbol{b}, \boldsymbol{c}$
- needs to implement OR

2. OR-gadget-graph:


## OR-Gadget Graph

Property: if $\boldsymbol{a}, \boldsymbol{b}, \boldsymbol{c}$ are colored False in a 3-coloring then output node of OR-gadget has to be colored False.

Property: if one of $\boldsymbol{a}, \boldsymbol{b}, \boldsymbol{c}$ is colored True then OR-gadget can be 3-colored such that output node of OR-gadget is colored True.

## Reduction

- create triangle with nodes True, False, Base
- for each variable $\boldsymbol{x}_{\boldsymbol{i}}$ two nodes $\boldsymbol{v}_{\boldsymbol{i}}$ and $\overline{\boldsymbol{v}}_{\boldsymbol{i}}$ connected in a triangle with common Base
- for each clause $\boldsymbol{C}_{\boldsymbol{j}}=(\boldsymbol{a} \vee \boldsymbol{b} \vee \boldsymbol{c})$, add OR-gadget graph with input nodes $\boldsymbol{a}, \boldsymbol{b}, \boldsymbol{c}$ and connect output node of gadget to both False and Base



## Reduction



## Claim 24.1.

No legal 3-coloring of above graph (with coloring of nodes $\boldsymbol{T}, \boldsymbol{F}, \boldsymbol{B}$ fixed) in which $\boldsymbol{a}, \boldsymbol{b}, \boldsymbol{c}$ are colored False. If any of $\boldsymbol{a}, \boldsymbol{b}, \boldsymbol{c}$ are colored True then there is a legal 3-coloring of above graph.

3 coloring of the clause gadget

|  |  |  |
| :---: | :---: | :---: |
|  |  |  |
|  |  |  |

## Reduction Outline

Example 24.2.
$\varphi=(u \vee \neg \boldsymbol{v} \vee \boldsymbol{w}) \wedge(v \vee x \vee \neg \boldsymbol{y})$


## Correctness of Reduction

$\varphi$ is satisfiable implies $\boldsymbol{G}_{\varphi}$ is 3-colorable

- if $\boldsymbol{x}_{\boldsymbol{i}}$ is assigned True, color $\boldsymbol{v}_{\boldsymbol{i}}$ True and $\overline{\boldsymbol{v}}_{\boldsymbol{i}}$ False
$\Rightarrow$ for each clause $C_{j}=(a \vee b \vee c)$ at least one of $a, b, c$ is colored True. OR-gadget for $\boldsymbol{C}_{\boldsymbol{j}}$ can be 3-colored such that output is True.


## Correctness of Reduction

$\varphi$ is satisfiable implies $\boldsymbol{G}_{\varphi}$ is 3-colorable

- if $\boldsymbol{x}_{\boldsymbol{i}}$ is assigned True, color $\boldsymbol{v}_{\boldsymbol{i}}$ True and $\overline{\boldsymbol{v}}_{\boldsymbol{i}}$ False
- for each clause $\boldsymbol{C}_{\boldsymbol{j}}=(\boldsymbol{a} \vee \boldsymbol{b} \vee \boldsymbol{c})$ at least one of $\boldsymbol{a}, \boldsymbol{b}, \boldsymbol{c}$ is colored True. OR-gadget for $\boldsymbol{C}_{\boldsymbol{j}}$ can be 3-colored such that output is True.


## Correctness of Reduction

$\varphi$ is satisfiable implies $\boldsymbol{G}_{\varphi}$ is 3-colorable

- if $\boldsymbol{x}_{\boldsymbol{i}}$ is assigned True, color $\boldsymbol{v}_{\boldsymbol{i}}$ True and $\overline{\boldsymbol{v}}_{\boldsymbol{i}}$ False
- for each clause $\boldsymbol{C}_{\boldsymbol{j}}=(\boldsymbol{a} \vee \boldsymbol{b} \vee \boldsymbol{c})$ at least one of $\boldsymbol{a}, \boldsymbol{b}, \boldsymbol{c}$ is colored True. OR-gadget for $\boldsymbol{C}_{\boldsymbol{j}}$ can be 3-colored such that output is True.


## Correctness of Reduction

$\varphi$ is satisfiable implies $\boldsymbol{G}_{\varphi}$ is 3-colorable

- if $\boldsymbol{x}_{\boldsymbol{i}}$ is assigned True, color $\boldsymbol{v}_{\boldsymbol{i}}$ True and $\overline{\boldsymbol{v}}_{\boldsymbol{i}}$ False
- for each clause $\boldsymbol{C}_{\boldsymbol{j}}=(\boldsymbol{a} \vee \boldsymbol{b} \vee \boldsymbol{c})$ at least one of $\boldsymbol{a}, \boldsymbol{b}, \boldsymbol{c}$ is colored True. OR-gadget for $\boldsymbol{C}_{\boldsymbol{j}}$ can be 3-colored such that output is True.
$\boldsymbol{G}_{\varphi}$ is 3 -colorable implies $\varphi$ is satisfiable
- if $\boldsymbol{v}_{\boldsymbol{i}}$ is colored True then set $\boldsymbol{x}_{\boldsymbol{i}}$ to be True, this is a legal truth assignment
 Base and False!


## Correctness of Reduction

$\varphi$ is satisfiable implies $\boldsymbol{G}_{\varphi}$ is 3-colorable

- if $\boldsymbol{x}_{\boldsymbol{i}}$ is assigned True, color $\boldsymbol{v}_{\boldsymbol{i}}$ True and $\overline{\boldsymbol{v}}_{\boldsymbol{i}}$ False
- for each clause $\boldsymbol{C}_{\boldsymbol{j}}=(\boldsymbol{a} \vee \boldsymbol{b} \vee \boldsymbol{c})$ at least one of $\boldsymbol{a}, \boldsymbol{b}, \boldsymbol{c}$ is colored True. OR-gadget for $\boldsymbol{C}_{\boldsymbol{j}}$ can be 3-colored such that output is True.
$\boldsymbol{G}_{\varphi}$ is 3-colorable implies $\varphi$ is satisfiable
- if $\boldsymbol{v}_{\boldsymbol{i}}$ is colored True then set $\boldsymbol{x}_{\boldsymbol{i}}$ to be True, this is a legal truth assignment
- consider any clause $\boldsymbol{C}_{\boldsymbol{j}}=(\boldsymbol{a} \vee \boldsymbol{b} \vee \boldsymbol{c})$. it cannot be that all $\boldsymbol{a}, \boldsymbol{b}, \boldsymbol{c}$ are False. If so, output of OR-gadget for $\boldsymbol{C}_{\boldsymbol{j}}$ has to be colored False but output is connected to Base and False!


## Graph generated in reduction...

## ... from 3SAT to 3COLOR

$(\boldsymbol{a} \vee \boldsymbol{b} \vee \boldsymbol{c}) \wedge(\boldsymbol{b} \vee \overline{\boldsymbol{c}} \vee \overline{\boldsymbol{d}}) \wedge(\overline{\boldsymbol{a}} \vee \boldsymbol{c} \vee \boldsymbol{d}) \wedge(\boldsymbol{a} \vee \overline{\boldsymbol{b}} \vee \overline{\mathbf{d}})$


## Graph generated in reduction...

## ... from 3SAT to 3COLOR

$$
(\boldsymbol{a} \vee \boldsymbol{b} \vee \boldsymbol{c}) \wedge(\boldsymbol{b} \vee \overline{\boldsymbol{c}} \vee \overline{\boldsymbol{d}}) \wedge(\overline{\boldsymbol{a}} \vee \boldsymbol{c} \vee \boldsymbol{d}) \wedge(\boldsymbol{a} \vee \overline{\boldsymbol{b}} \vee \overline{\boldsymbol{d}})
$$



## Graph generated in reduction...

## ... from 3SAT to 3COLOR

$$
(\boldsymbol{a} \vee \boldsymbol{b} \vee \boldsymbol{c}) \wedge(\boldsymbol{b} \vee \overline{\boldsymbol{c}} \vee \overline{\boldsymbol{d}}) \wedge(\overline{\boldsymbol{a}} \vee \boldsymbol{c} \vee \boldsymbol{d}) \wedge(\boldsymbol{a} \vee \overline{\boldsymbol{b}} \vee \overline{\boldsymbol{d}})
$$



## Graph generated in reduction...

## ... from 3SAT to 3COLOR

$$
(\boldsymbol{a} \vee \boldsymbol{b} \vee \boldsymbol{c}) \wedge(\boldsymbol{b} \vee \bar{c} \vee \overline{\boldsymbol{d}}) \wedge(\overline{\boldsymbol{a}} \vee \boldsymbol{c} \vee \boldsymbol{d}) \wedge(\boldsymbol{a} \vee \overline{\boldsymbol{b}} \vee \overline{\boldsymbol{d}})
$$



## Graph generated in reduction...

## ... from 3SAT to 3COLOR

$$
(\boldsymbol{a} \vee \boldsymbol{b} \vee \boldsymbol{c}) \wedge(\boldsymbol{b} \vee \overline{\boldsymbol{c}} \vee \overline{\boldsymbol{d}}) \wedge(\overline{\boldsymbol{a}} \vee \boldsymbol{c} \vee \boldsymbol{d}) \wedge(\boldsymbol{a} \vee \overline{\boldsymbol{b}} \vee \overline{\boldsymbol{d}})
$$



## Graph generated in reduction...

## ... from 3SAT to 3COLOR

$(\boldsymbol{a} \vee \boldsymbol{b} \vee \boldsymbol{c}) \wedge(\boldsymbol{b} \vee \overline{\boldsymbol{c}} \vee \overline{\boldsymbol{d}}) \wedge(\overline{\boldsymbol{a}} \vee \boldsymbol{c} \vee \boldsymbol{d}) \wedge(\boldsymbol{a} \vee \overline{\boldsymbol{b}} \vee \overline{\mathbf{d}})$


## THE END

(for now)

Algorithms \& Models of Computation CS/ECE 374, Fall 2020
24.4

Proof of Cook-Levin Theorem

Algorithms \& Models of Computation
CS/ECE 374, Fall 2020
24.4.1

Statement and sketch of idea for the proof

## Cook-Levin Theorem

## Theorem 24.1 (Cook-Levin). <br> SAT is NP-Complete.

We have already seen that SAT is in NP.
Need to prove that every language $L \in N P, L \leq_{p}$ SAT
Difficulty: Infinite number of languages in NP. Must simultaneously show a generic reduction strategy.

## Cook-Levin Theorem

## Theorem 24.1 (Cook-Levin). <br> SAT is NP-Complete.

We have already seen that SAT is in NP.

Need to prove that every language $L \in N P, L \leq_{P}$ SAT
Difficulty: Infinite number of languages in NP. Must simultaneously show a generic reduction strategy.

## The plot against SAT

High-level plan to proving the Cook-Levin theorem
What does it mean that $L \in N P$ ?
$\boldsymbol{L} \in \boldsymbol{N P}$ implies that there is a non-deterministic TM $\boldsymbol{M}$ and polynomial $\boldsymbol{p}()$ such that

$$
\boldsymbol{L}=\left\{\boldsymbol{x} \in \Sigma^{*} \mid \boldsymbol{M} \text { accepts } \boldsymbol{x} \text { in at most } \boldsymbol{p}(|\boldsymbol{x}|) \text { steps }\right\}
$$

```
Input: M,x,p.
Question: Does M stops on input x after p(|x|) steps?
```

Describe a reduction $R$ that computes from $\mathbf{M , x , p}$ a SAT formula $\varphi$.
$\rightarrow \boldsymbol{R}$ takes as input a string $\boldsymbol{x}$ and outputs a SAT formula $\varphi$

- $R$ runs in time polynomial in $|x|,|M|$
> $x \in L$ if and only if $\varphi$ is satisfiable


## The plot against SAT

## High-level plan to proving the Cook-Levin theorem

What does it mean that $L \in N P$ ?
$\boldsymbol{L} \in \boldsymbol{N} \boldsymbol{P}$ implies that there is a non-deterministic TM $\boldsymbol{M}$ and polynomial $\boldsymbol{p}()$ such that

$$
\boldsymbol{L}=\left\{\boldsymbol{x} \in \Sigma^{*} \mid \boldsymbol{M} \text { accepts } \boldsymbol{x} \text { in at most } \boldsymbol{p}(|\boldsymbol{x}|) \text { steps }\right\}
$$

Input: $M, x, p$.
Question: Does $\boldsymbol{M}$ stops on input $\boldsymbol{x}$ after $\boldsymbol{p}(|\boldsymbol{x}|)$ steps?
Describe a reduction $R$ that computes from $M, x, p$ a SAT formula $\varphi$ - $\boldsymbol{R}$ takes as input a string $x$ and outputs a SAT formula $\varphi$ - $\boldsymbol{R}$ runs in time polynomial in $|\boldsymbol{x}|,|\boldsymbol{M}|$ $\Rightarrow x \in L$ if and only if $\varphi$ is satisfiable

## The plot against SAT

## High-level plan to proving the Cook-Levin theorem

What does it mean that $L \in N P$ ?
$\boldsymbol{L} \in \boldsymbol{N P}$ implies that there is a non-deterministic TM $\boldsymbol{M}$ and polynomial $\boldsymbol{p}()$ such that

$$
\boldsymbol{L}=\left\{\boldsymbol{x} \in \Sigma^{*} \mid \boldsymbol{M} \text { accepts } \boldsymbol{x} \text { in at most } \boldsymbol{p}(|\boldsymbol{x}|) \text { steps }\right\}
$$

Input: $M, x, p$.
Question: Does $M$ stops on input $\boldsymbol{x}$ after $\boldsymbol{p}(|\boldsymbol{x}|)$ steps?
Describe a reduction $\boldsymbol{R}$ that computes from $\boldsymbol{M}, \boldsymbol{x}, \boldsymbol{p}$ a SAT formula $\varphi$.

- $\boldsymbol{R}$ takes as input a string $\boldsymbol{x}$ and outputs a SAT formula $\varphi$
- $\boldsymbol{R}$ runs in time polynomial in $|\boldsymbol{x}|,|\boldsymbol{M}|$
- $x \in L$ if and only if $\varphi$ is satisfiable


## The plot against SAT continued


$\varphi$ is satisfiable if and only if $\boldsymbol{x} \in \boldsymbol{L}$
$\varphi$ is satisfiable if and only if nondeterministic $M$ accepts $x$ in $p(|x|)$ steps

## BIG IDEA

$>\varphi$ will express " $M$ on input $x$ accepts in $p(|x|)$ steps'
$\rightarrow \varphi$ will encode a computation history of $M$ on $x$
$\varphi$ : CNF formula s.t if we have a satisfying assignment to it $\Rightarrow$ accepting
computation of $\boldsymbol{M}$ on $\boldsymbol{x}$ down to the last details (where the head is, what transition is chosen, what the tape contents are, at each step, etc).

## The plot against SAT continued


$\varphi$ is satisfiable if and only if $x \in L$
$\boldsymbol{\varphi}$ is satisfiable if and only if nondeterministic $\boldsymbol{M}$ accepts $\boldsymbol{x}$ in $\boldsymbol{p}(|\boldsymbol{x}|)$ steps

- $\varphi$ will express " $\boldsymbol{M}$ on input $\boldsymbol{x}$ accepts in $\boldsymbol{p}(|\boldsymbol{x}|)$ steps"
- $\varphi$ will encode a computation history of $M$ on $\boldsymbol{x}$
$\varphi$ : CNF formula s.t if we have a satisfying assignment to it $\Rightarrow$ accepting
computation of $\boldsymbol{M}$ on $\boldsymbol{x}$ down to the last details (where the head is, what transition is chosen, what the tape contents are, at each step, etc).


## The plot against SAT continued


$\varphi$ is satisfiable if and only if $x \in L$
$\boldsymbol{\varphi}$ is satisfiable if and only if nondeterministic $\boldsymbol{M}$ accepts $\boldsymbol{x}$ in $\boldsymbol{p}(|\boldsymbol{x}|)$ steps

## BIG IDEA

- $\varphi$ will express " $\boldsymbol{M}$ on input $\boldsymbol{x}$ accepts in $\boldsymbol{p}(|\boldsymbol{x}|)$ steps"
- $\varphi$ will encode a computation history of $\boldsymbol{M}$ on $\boldsymbol{x}$


## The plot against SAT continued


$\varphi$ is satisfiable if and only if $\boldsymbol{x} \in \boldsymbol{L}$
$\boldsymbol{\varphi}$ is satisfiable if and only if nondeterministic $\boldsymbol{M}$ accepts $\boldsymbol{x}$ in $\boldsymbol{p}(|\boldsymbol{x}|)$ steps

## BIG IDEA

- $\varphi$ will express " $\boldsymbol{M}$ on input $\boldsymbol{x}$ accepts in $\boldsymbol{p}(|\boldsymbol{x}|)$ steps"
- $\varphi$ will encode a computation history of $\boldsymbol{M}$ on $\boldsymbol{x}$
$\varphi$ : CNF formula s.t if we have a satisfying assignment to it $\Longrightarrow$ accepting computation of $\boldsymbol{M}$ on $\boldsymbol{x}$ down to the last details (where the head is, what transition is chosen, what the tape contents are, at each step, etc).


## The Matrix Executions

## Tableau of Computation

$\boldsymbol{M}$ runs in time $\boldsymbol{p}(|\boldsymbol{x}|)$ on $\boldsymbol{x}$. Entire computation of $\boldsymbol{M}$ on $\boldsymbol{x}$ can be represented by a "tableau"


Row $\boldsymbol{i}$ gives contents of all cells at time $\boldsymbol{i}$
At time $\mathbf{0}$ tape has input $\boldsymbol{x}$ followed by blanks
Each row long enough to hold all cells $\boldsymbol{M}$ might ever have scanned.

## Variables of $\varphi$

Four types of variables to describe computation of $\boldsymbol{M}$ on $\boldsymbol{x}$

- $\boldsymbol{T}(\boldsymbol{b}, \boldsymbol{h}, \boldsymbol{i})$ : tape cell at position $\boldsymbol{h}$ holds symbol $\boldsymbol{b}$ at time $\boldsymbol{i}$.

For $h=1, \ldots, p(|x|), b \in \Gamma, i=0, \ldots, p(|x|)$.

- $\boldsymbol{H}(\boldsymbol{h}, \boldsymbol{i}):$ read/write head is at position $\boldsymbol{h}$ at time $\boldsymbol{i}$.

Fir $\boldsymbol{h}=\mathbf{1}, \ldots, \boldsymbol{p}(|\boldsymbol{x}|)$, and $\boldsymbol{i}=\mathbf{0}, \ldots, \boldsymbol{p}(|\boldsymbol{x}|)$

- $\boldsymbol{S}(\boldsymbol{q}, \boldsymbol{i})$ state of $\boldsymbol{M}$ is $\boldsymbol{q}$ at time $\boldsymbol{i}$.

For all $\boldsymbol{q} \in \boldsymbol{Q}$ and $\boldsymbol{i}=\mathbf{0}, \ldots, \boldsymbol{p}(|\boldsymbol{x}|)$.

- I(j,i) instruction number $\boldsymbol{j}$ is executed at time $\boldsymbol{i}$
$M$ is non-deterministic, need to specify transitions in some way. Number transitions as $\mathbf{1}, \mathbf{2}, \ldots, \boldsymbol{\ell}$ where $\boldsymbol{j}$ th transition is $<\boldsymbol{q}_{\boldsymbol{j}}, \boldsymbol{b}_{\boldsymbol{j}}, \boldsymbol{q}_{\boldsymbol{j}}^{\prime}, \boldsymbol{b}_{\boldsymbol{j}}^{\prime}, \boldsymbol{d}_{\boldsymbol{j}}>$ indication $\left(\boldsymbol{q}_{\boldsymbol{j}}^{\prime}, \boldsymbol{b}_{\boldsymbol{j}}^{\prime}, \boldsymbol{d}_{\boldsymbol{j}}\right) \in \boldsymbol{\delta}\left(\boldsymbol{q}_{\boldsymbol{j}}, \boldsymbol{b}_{\boldsymbol{j}}\right)$, direction $\boldsymbol{d}_{\boldsymbol{j}} \in\{-\mathbf{1}, \mathbf{0}, \mathbf{1}\}$.
Number of variables is $\boldsymbol{O}\left(\boldsymbol{p}(|x|)^{2}|M|^{2}\right)$


## Notation

Some abbreviations for ease of notation $\bigwedge_{k=1}^{m} x_{k}$ means $x_{1} \wedge x_{2} \wedge \ldots \wedge x_{m}$
$\bigvee_{k=1}^{m} x_{k}$ means $x_{1} \vee x_{2} \vee \ldots \vee x_{m}$
$\oplus\left(x_{1}, x_{2}, \ldots, x_{k}\right)$ is a formula that means exactly one of $x_{1}, x_{2}, \ldots, x_{m}$ is true. Can be converted to CNF form

CNF formula showing making sure that at most one variable is assigned value $\mathbf{1}$


Making sure that one of the variables is true: $\bigvee_{i=1}^{k} x_{i}$


## Notation

Some abbreviations for ease of notation
$\bigwedge_{k=1}^{m} x_{k}$ means $x_{1} \wedge x_{2} \wedge \ldots \wedge x_{m}$
$\bigvee_{k=1}^{m} x_{k}$ means $x_{1} \vee x_{2} \vee \ldots \vee x_{m}$
$\bigoplus\left(x_{1}, x_{2}, \ldots, x_{k}\right)$ is a formula that means exactly one of $x_{1}, x_{2}, \ldots, x_{m}$ is true. Can be converted to CNF form

CNF formula showing making sure that at most one variable is assigned value $\mathbf{1}$ :

$$
\bigwedge_{1 \leq i<j \leq k}\left(\overline{x_{i}} \vee \overline{x_{j}}\right)
$$

Making sure that one of the variables is true: $\bigvee_{i=1}^{k} x_{i}$


## Notation

Some abbreviations for ease of notation
$\bigwedge_{k=1}^{m} x_{k}$ means $x_{1} \wedge x_{2} \wedge \ldots \wedge x_{m}$
$\bigvee_{k=1}^{m} x_{k}$ means $\boldsymbol{x}_{1} \vee \boldsymbol{x}_{2} \vee \ldots \vee \boldsymbol{x}_{m}$
$\bigoplus\left(x_{1}, x_{2}, \ldots, x_{k}\right)$ is a formula that means exactly one of $x_{1}, x_{2}, \ldots, x_{m}$ is true. Can be converted to CNF form

CNF formula showing making sure that at most one variable is assigned value $\mathbf{1}$ :

$$
\bigwedge_{1 \leq i<j \leq k}\left(\overline{x_{i}} \vee \overline{x_{j}}\right)
$$

Making sure that one of the variables is true: $\bigvee_{i=1}^{k} \boldsymbol{x}_{\boldsymbol{i}}$.


## Notation

Some abbreviations for ease of notation
$\bigwedge_{k=1}^{m} x_{k}$ means $x_{1} \wedge x_{2} \wedge \ldots \wedge x_{m}$
$\bigvee_{k=1}^{m} x_{k}$ means $x_{1} \vee x_{2} \vee \ldots \vee x_{m}$
$\bigoplus\left(x_{1}, x_{2}, \ldots, x_{k}\right)$ is a formula that means exactly one of $x_{1}, x_{2}, \ldots, x_{m}$ is true. Can be converted to CNF form

CNF formula showing making sure that at most one variable is assigned value $\mathbf{1}$ :

$$
\bigwedge_{1 \leq i<j \leq k}\left(\overline{x_{i}} \vee \overline{x_{j}}\right)
$$

Making sure that one of the variables is true: $\bigvee_{i=1}^{k} \boldsymbol{x}_{\boldsymbol{i}}$.

$$
\bigoplus\left(x_{1}, x_{2}, \ldots, x_{k}\right)=\bigwedge_{1 \leq i<j \leq k}\left(\overline{x_{i}} \vee \overline{x_{j}}\right) \bigwedge\left(x_{1} \vee x_{2} \vee \cdots \vee x_{k}\right)
$$

## Clauses of $\varphi$

$\varphi$ is the conjunction of $\mathbf{8}$ clause groups:

$$
\varphi=\bigwedge_{i=1}^{12} \varphi_{i}
$$

where each $\varphi_{i}$ is a CNF formula. Described in subsequent slides.
Property: $\varphi$ is satisfied $\Longleftrightarrow$ there is an execution of $M$ on $\boldsymbol{x}$ that accepts the language in $\boldsymbol{p}(|\boldsymbol{x}|)$ time.

## THE END

(for now)

Algorithms \& Models of Computation

## CS/ECE 374, Fall 2020

### 24.4.2

The consistency of execution

## The variables of $\varphi$

## Variables:

$\left\langle\boldsymbol{q}_{\boldsymbol{j}}, \boldsymbol{b}_{j}, \boldsymbol{q}_{\boldsymbol{j}}^{\prime}, \boldsymbol{b}_{\boldsymbol{j}}^{\prime}, \boldsymbol{d}_{\boldsymbol{j}}\right\rangle: \boldsymbol{j}$ th instruction of $\boldsymbol{M}$ $\boldsymbol{I}(\boldsymbol{j}, \boldsymbol{i})$ : Instruction $\boldsymbol{j}$ was issued at time $\boldsymbol{i}$. $\boldsymbol{H}(\boldsymbol{h}, \boldsymbol{i})$ : The head is at location $\boldsymbol{h}$ at time $\boldsymbol{i}$. $\boldsymbol{T}(\boldsymbol{c}, \boldsymbol{h}, \boldsymbol{i})$ : The tape at location $\boldsymbol{h}$ at time $\boldsymbol{i}$ stored the character $\boldsymbol{c}$.

## $\varphi_{1}$ : The input is encoded correctly

$\varphi_{1}$ asserts (is true eff) the variables are set $\mathrm{T} / \mathrm{F}$ indicating that $\boldsymbol{M}$ starts in state $\boldsymbol{q}_{0}$ at time $\mathbf{0}$ with tape contents containing $\boldsymbol{x}$ followed by blanks. Let $\boldsymbol{x}=x_{1} x_{2} \ldots x_{n}$

$$
\begin{aligned}
& \varphi_{1}=\boldsymbol{S}\left(\boldsymbol{q}_{\mathbf{0}}, \mathbf{0}\right) \quad / / \text { state at time } \mathbf{0} \text { is } \boldsymbol{q}_{\mathbf{0}} \\
& \bigwedge_{h=1} \boldsymbol{T}\left(x_{h}, \boldsymbol{h}, \mathbf{0}\right) \quad / / \text { at time } \mathbf{0} \text { cells } \mathbf{1} \text { to } \boldsymbol{n} \text { have value } x_{1} \text { to } x_{n} \\
& \wedge \bigwedge_{h=n+1}^{p(n)} T(\sqcup, h, 0) \\
& \text { // all remaining cells are blank } \\
& \wedge \boldsymbol{H}(\mathbf{1}, \mathbf{0}) \quad / / \text { The head is at time } \mathbf{0} \text { at start of tape }
\end{aligned}
$$

## $\varphi_{2}: M$ is in exactly one state at any point in time

$\varphi_{2}$ asserts $M$ in exactly one state at any time $\boldsymbol{i}$ :

$$
\varphi_{2}=\bigwedge_{i=0}^{p(|x|)}\left(\oplus\left(S\left(q_{0}, i\right), S\left(q_{1}, i\right), \ldots, S\left(q_{|Q|}, i\right)\right)\right)
$$

## Variables:

$\left\langle\boldsymbol{a}_{j}, \boldsymbol{b}_{\boldsymbol{j}}, \boldsymbol{q}_{\boldsymbol{j}}^{\prime}, \boldsymbol{b}_{j}^{\prime}, \boldsymbol{d}_{\boldsymbol{j}}\right\rangle: j$ th instruction of $\boldsymbol{M}$
$\boldsymbol{I}(\boldsymbol{j}, \boldsymbol{i})$ : Instruction $\boldsymbol{j}$ was issued at time $\boldsymbol{i}$.
$\boldsymbol{H}(\boldsymbol{h}, \boldsymbol{i})$ : The head is at location $\boldsymbol{h}$ at time $\boldsymbol{i}$.
$\boldsymbol{T}(\boldsymbol{c}, \boldsymbol{h}, \boldsymbol{i})$ : The tape at location $\boldsymbol{h}$ at time $\boldsymbol{i}$ stored the character $\boldsymbol{c}$.

## $\varphi_{3}:$ Each tape cell holds a unique symbol at any time

$\varphi_{3}$ asserts that each tape cell holds a unique symbol at any given time.

$$
\varphi_{3}=\bigwedge_{i=0}^{p(|x| \mid)} \bigwedge_{h=1}^{p(|x|)} \oplus\left(T\left(b_{1}, \boldsymbol{h}, \boldsymbol{i}\right), T\left(\boldsymbol{b}_{2}, \boldsymbol{h}, \boldsymbol{i}\right), \ldots, T\left(\boldsymbol{b}_{|\Gamma|}, \boldsymbol{h}, \boldsymbol{i}\right)\right)
$$

For each time $\boldsymbol{i}$ and for each cell position $\boldsymbol{h}$ exactly one symbol $\boldsymbol{b} \in \Gamma$ at cell position $\boldsymbol{h}$ at time $\boldsymbol{i}$

## Variables:

$\left\langle\boldsymbol{q}_{\boldsymbol{j}}, \boldsymbol{b}_{\boldsymbol{j}}, \boldsymbol{q}_{\boldsymbol{j}}^{\prime}, \boldsymbol{b}_{\boldsymbol{j}}^{\prime}, \boldsymbol{d}_{\boldsymbol{j}}\right\rangle: \boldsymbol{j}$ th instruction of $\boldsymbol{M}$
$\boldsymbol{I}(\boldsymbol{j}, \boldsymbol{i})$ : Instruction $\boldsymbol{j}$ was issued at time $\boldsymbol{i}$.
$\boldsymbol{H}(\boldsymbol{h}, \boldsymbol{i})$ : The head is at location $\boldsymbol{h}$ at time $\boldsymbol{i}$.
$\boldsymbol{T}(\boldsymbol{c}, \boldsymbol{h}, \boldsymbol{i})$ : The tape at location $\boldsymbol{h}$ at time $\boldsymbol{i}$ stored the character $\boldsymbol{c}$.

## $\varphi_{4}$ : tape head of $\boldsymbol{M}$ is in exactly one position at any time $\boldsymbol{i}$

 $\varphi_{4}$ asserts that the read/write head of $\boldsymbol{M}$ is in exactly one position at any time $\boldsymbol{i}$$$
\varphi_{4}=\bigwedge_{i=0}^{p(|x|)}(\oplus(\boldsymbol{H}(\mathbf{1}, \boldsymbol{i}), \boldsymbol{H}(2, \boldsymbol{i}), \ldots, \boldsymbol{H}(\boldsymbol{p}(|x|), \boldsymbol{i})))
$$

## Variables:

$\left\langle\boldsymbol{q}_{j}, \boldsymbol{b}_{\boldsymbol{j}}, \boldsymbol{q}_{\boldsymbol{j}}^{\prime}, \boldsymbol{b}_{\boldsymbol{j}}^{\prime}, \boldsymbol{d}_{\boldsymbol{j}}\right\rangle: \boldsymbol{j}$ th instruction of $\boldsymbol{M}$
$\boldsymbol{I}(\boldsymbol{j}, \boldsymbol{i})$ : Instruction $\boldsymbol{j}$ was issued at time $\boldsymbol{i}$.
$\boldsymbol{H}(\boldsymbol{h}, \boldsymbol{i})$ : The head is at location $\boldsymbol{h}$ at time $\boldsymbol{i}$.
$\boldsymbol{T}(\boldsymbol{c}, \boldsymbol{h}, \boldsymbol{i})$ : The tape at location $\boldsymbol{h}$ at time $\boldsymbol{i}$ stored the character $\boldsymbol{c}$.

## $\varphi_{5}: M$ accepts the input

$\varphi_{5}$ asserts that $M$ accepts

- Let $\boldsymbol{q}_{a}$ be unique accept state of $\boldsymbol{M}$
- without loss of generality assume $\boldsymbol{M}$ runs all $\boldsymbol{p}(|\boldsymbol{x}|)$ steps

$$
\varphi_{5}=\boldsymbol{S}\left(\boldsymbol{q}_{a}, \boldsymbol{p}(|\boldsymbol{x}|)\right)
$$

State at time $\boldsymbol{p}(|\boldsymbol{x}|)$ is $\boldsymbol{q}_{\boldsymbol{a}}$ the accept state.
If we don't want to make assumption of running for all steps

$$
\varphi_{5}=\bigvee_{i=1}^{p(|x|)} S\left(q_{a}, i\right)
$$

which means $M$ enters accepts state at some time.

## $\varphi_{6}: M$ executes a unique instruction at each time

$\varphi_{6}$ asserts that $M$ executes a unique instruction at each time

$$
\varphi_{6}=\bigwedge_{i=0}^{p(|x|)} \oplus(I(1, i), I(2, i), \ldots, I(m, i))
$$

where $\boldsymbol{m}$ is max instruction number.

## Variables:

$\left\langle\boldsymbol{q}_{\boldsymbol{j}}, \boldsymbol{b}_{j}, \boldsymbol{q}_{\boldsymbol{j}}^{\prime}, \boldsymbol{b}_{\boldsymbol{j}}^{\prime}, \boldsymbol{d}_{\boldsymbol{j}}\right\rangle: \boldsymbol{j}$ th instruction of $\boldsymbol{M}$
$\boldsymbol{I}(\boldsymbol{j}, \boldsymbol{i})$ : Instruction $\boldsymbol{j}$ was issued at time $\boldsymbol{i}$.
$\boldsymbol{H}(\boldsymbol{h}, \boldsymbol{i})$ : The head is at location $\boldsymbol{h}$ at time $\boldsymbol{i}$.
$\boldsymbol{T}(\boldsymbol{c}, \boldsymbol{h}, \boldsymbol{i})$ : The tape at location $\boldsymbol{h}$ at time $\boldsymbol{i}$ stored the character $\boldsymbol{c}$.

## $\varphi_{7}$ : Tape changes only because of the head writing something

$\varphi_{7}$ ensures that variables don't allow tape to change from one moment to next if the read/write head was not there.
"If head is not at position $\boldsymbol{h}$ at time $\boldsymbol{i}$ then at time $\boldsymbol{i}+\mathbf{1}$ the symbol at cell $\boldsymbol{h}$ must be unchanged"

$$
\varphi_{7}=\bigwedge_{i} \bigwedge_{h} \bigwedge_{b \neq c}(\overline{H(h, i)} \Rightarrow \overline{T(b, h, i) \bigwedge T(c, h, i+1)})
$$

since $\boldsymbol{A} \Rightarrow \boldsymbol{B}$ is same as $\neg \boldsymbol{A} \vee \boldsymbol{B}$, rewrite above in CNF form

$$
\varphi_{7}=\bigwedge_{i} \bigwedge_{h} \bigwedge_{b \neq c}(H(h, i) \vee \neg T(b, h, i) \vee \neg T(c, h, i+1))
$$

## $\varphi_{8}:$ Transitions are done from correct states

$\boldsymbol{j}$ th instruction of $\boldsymbol{M}:<\boldsymbol{q}_{j}, \boldsymbol{b}_{\boldsymbol{j}}, \boldsymbol{q}_{\boldsymbol{j}}^{\prime}, \boldsymbol{b}_{\boldsymbol{j}}^{\prime}, \boldsymbol{d}_{\boldsymbol{j}}>$

$$
\varphi_{8}=\bigwedge_{i} \bigwedge_{j}\left(I(j, i) \Rightarrow S\left(q_{j}, i\right)\right)
$$

If instruction $\boldsymbol{j}$ is executed at time $\boldsymbol{i}$ then state at time $\boldsymbol{i}$ must be $\boldsymbol{q}_{\boldsymbol{j}}$.

## Variables:

$\left\langle\boldsymbol{q}_{j}, \boldsymbol{b}_{j}, \boldsymbol{q}_{\boldsymbol{j}}^{\prime}, \boldsymbol{b}_{\boldsymbol{j}}^{\prime}, \boldsymbol{d}_{j}\right\rangle: \boldsymbol{j}$ th instruction of $\boldsymbol{M}$
$\boldsymbol{I}(\boldsymbol{j}, \boldsymbol{i})$ : Instruction $\boldsymbol{j}$ was issued at time $\boldsymbol{i}$.
$\boldsymbol{H}(\boldsymbol{h}, \boldsymbol{i})$ : The head is at location $\boldsymbol{h}$ at time $\boldsymbol{i}$.
$\boldsymbol{T}(\boldsymbol{c}, \boldsymbol{h}, \boldsymbol{i})$ : The tape at location $\boldsymbol{h}$ at time $\boldsymbol{i}$ stored the character $\boldsymbol{c}$.

## $\varphi_{9}:$ Transitions are done into correct state

$j$ th instruction of $\boldsymbol{M}:<\boldsymbol{q}_{j}, \boldsymbol{b}_{j}, \boldsymbol{q}_{\boldsymbol{j}}^{\prime}, \boldsymbol{b}_{j}^{\prime}, \boldsymbol{d}_{j}>$

$$
\varphi_{9}=\bigwedge_{i} \bigwedge_{j}\left(I(j, i) \Rightarrow S\left(q_{j}^{\prime}, i+1\right)\right)
$$

If instruction $\boldsymbol{j}$ was performed at time $\boldsymbol{i}$, then state at time $\boldsymbol{i}+\mathbf{1}$ must be $\boldsymbol{q}_{\boldsymbol{j}}^{\prime}$.

## Variables:

$\left\langle\boldsymbol{q}_{j}, \boldsymbol{b}_{\boldsymbol{j}}, \boldsymbol{a}_{\boldsymbol{j}}^{\prime}, \boldsymbol{b}_{j}^{\prime}, \boldsymbol{d}_{\boldsymbol{j}}\right\rangle: \boldsymbol{j}$ th instruction of $\boldsymbol{M}$
$\boldsymbol{I}(\boldsymbol{j}, \boldsymbol{i})$ : Instruction $\boldsymbol{j}$ was issued at time $\boldsymbol{i}$.
$\boldsymbol{H}(\boldsymbol{h}, \boldsymbol{i})$ : The head is at location $\boldsymbol{h}$ at time $\boldsymbol{i}$.
$\boldsymbol{T}(\boldsymbol{c}, \boldsymbol{h}, \boldsymbol{i})$ : The tape at location $\boldsymbol{h}$ at time $\boldsymbol{i}$ stored the character $\boldsymbol{c}$.

## $\varphi_{10}:$ The character written on tape that triggered an

 instruction, is the correct one$$
\varphi_{10}=\bigwedge_{i} \bigwedge_{h} \bigwedge_{j}\left[(I(j, i) \bigwedge H(h, i)) \Rightarrow T\left(\boldsymbol{b}_{j}, \boldsymbol{h}, \boldsymbol{i}\right)\right]
$$

If instruction $\boldsymbol{j}$ was executed at time $\boldsymbol{i}$ and head was at position $\boldsymbol{h}$, then cell $\boldsymbol{h}$ has the symbol needed to issue instruction $\boldsymbol{j}$ is written under the head location on the tape.

## Variables:

$\left\langle\boldsymbol{q}_{j}, \boldsymbol{b}_{j}, \boldsymbol{q}_{\boldsymbol{j}}^{\prime}, \boldsymbol{b}_{j}^{\prime}, \boldsymbol{d}_{\boldsymbol{j}}\right\rangle: \boldsymbol{j}$ th instruction of $\boldsymbol{M}$
$\boldsymbol{I}(\boldsymbol{j}, \boldsymbol{i})$ : Instruction $\boldsymbol{j}$ was issued at time $\boldsymbol{i}$.
$\boldsymbol{H}(\boldsymbol{h}, \boldsymbol{i})$ : The head is at location $\boldsymbol{h}$ at time $\boldsymbol{i}$.
$\boldsymbol{T}(\boldsymbol{c}, \boldsymbol{h}, \boldsymbol{i})$ : The tape at location $\boldsymbol{h}$ at time $\boldsymbol{i}$ stored the character $\boldsymbol{c}$.

## $\varphi_{11}$ : The correct symbol was written to the tape at time $\boldsymbol{i}$

$$
\varphi_{11}=\bigwedge_{i} \bigwedge_{j} \bigwedge_{h}\left[(I(j, i) \wedge H(h, i)) \Rightarrow T\left(b_{j}^{\prime}, h, i+1\right)\right]
$$

If instruction $\boldsymbol{j}$ was executed time $\boldsymbol{i}$ with head at $\boldsymbol{h}$, then at next time step symbol $\boldsymbol{b}_{\boldsymbol{j}}^{\prime}$ was written in position $\boldsymbol{h}$

## Variables:

$\left\langle\boldsymbol{q}_{j}, \boldsymbol{b}_{\boldsymbol{j}}, \boldsymbol{q}_{\boldsymbol{j}}^{\prime}, \boldsymbol{b}_{\boldsymbol{j}}^{\prime}, \boldsymbol{d}_{\boldsymbol{j}}\right\rangle: \boldsymbol{j}$ th instruction of $\boldsymbol{M}$
$\boldsymbol{I}(\boldsymbol{j}, \boldsymbol{i})$ : Instruction $\boldsymbol{j}$ was issued at time $\boldsymbol{i}$.
$\boldsymbol{H}(\boldsymbol{h}, \boldsymbol{i})$ : The head is at location $\boldsymbol{h}$ at time $\boldsymbol{i}$.
$\boldsymbol{T}(\boldsymbol{c}, \boldsymbol{h}, \boldsymbol{i})$ : The tape at location $\boldsymbol{h}$ at time $\boldsymbol{i}$ stored the character $\boldsymbol{c}$.

## $\varphi_{12}:$ Head was moved in the right direction at time $\boldsymbol{i}$

$$
\varphi_{12}=\bigwedge_{i} \bigwedge_{j} \bigwedge_{h}\left[(I(\boldsymbol{j}, \boldsymbol{i}) \wedge \boldsymbol{H}(\boldsymbol{h}, \boldsymbol{i})) \Rightarrow \boldsymbol{H}\left(\boldsymbol{h}+\boldsymbol{d}_{j}, \boldsymbol{i}+\mathbf{1}\right)\right]
$$

The head is moved properly according to instr $\boldsymbol{j}$.

## Variables:

$\left\langle\boldsymbol{q}_{\boldsymbol{j}}, \boldsymbol{b}_{\boldsymbol{j}}, \boldsymbol{q}_{\boldsymbol{j}}^{\prime}, \boldsymbol{b}_{j}^{\prime}, \boldsymbol{d}_{\boldsymbol{j}}\right\rangle: \boldsymbol{j}$ th instruction of $\boldsymbol{M}$
$\boldsymbol{I}(\boldsymbol{j}, \boldsymbol{i})$ : Instruction $\boldsymbol{j}$ was issued at time $\boldsymbol{i}$.
$\boldsymbol{H}(\boldsymbol{h}, \boldsymbol{i})$ : The head is at location $\boldsymbol{h}$ at time $\boldsymbol{i}$.
$\boldsymbol{T}(\boldsymbol{c}, \boldsymbol{h}, \boldsymbol{i})$ : The tape at location $\boldsymbol{h}$ at time $\boldsymbol{i}$ stored the character $\boldsymbol{c}$.

## THE END

(for now)

Algorithms \& Models of Computation CS/ECE 374, Fall 2020

### 24.4.3

Proof of correctness

## Proof of Correctness

(Sketch)

- Given $\boldsymbol{M}, \boldsymbol{x}$, poly-time algorithm to construct $\varphi$
- if $\varphi$ is satisfiable then the truth assignment completely specifies an accepting computation of $\boldsymbol{M}$ on $\boldsymbol{x}$
- if $\boldsymbol{M}$ accepts $\boldsymbol{x}$ then the accepting computation leads to an "obvious" truth assignment to $\varphi$. Simply assign the variables according to the state of $M$ and cells at each time $\boldsymbol{i}$.
Thus $M$ accepts $\boldsymbol{x}$ if and only if $\varphi$ is satisfiable


## THE END

(for now)

Algorithms \& Models of Computation

## CS/ECE 374, Fall 2020

24.5

NP-Complete problems to know and remember

## List of NP-Complete Problems to Remember

## Problems

1. SAT
2. 3SAT
3. CircuitSAT
4. Independent Set
5. Clique
6. Vertex Cover
7. Hamilton Cycle and Hamilton Path in both directed and undirected graphs
8. 3Color and Color

[^0]:    Can safely assume every node has at most two incoming edges

