Algorithms \& Models of Computation CS/ECE 374, Fall 2020
24.4

Proof of Cook-Levin Theorem

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Statement and sketch of idea for the proof

## Cook-Levin Theorem

## Theorem 24.1 (Cook-Levin). <br> SAT is NP-Complete.

We have already seen that SAT is in NP.
Need to prove that every language $L \in N P, L \leq_{p}$ SAT
Difficulty: Infinite number of languages in NP. Must simultaneously show a generic reduction strategy.

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## The plot against SAT

High-level plan to proving the Cook-Levin theorem
What does it mean that $L \in N P$ ?
$\boldsymbol{L} \in \boldsymbol{N P}$ implies that there is a non-deterministic TM $\boldsymbol{M}$ and polynomial $\boldsymbol{p}()$ such that

$$
\boldsymbol{L}=\left\{\boldsymbol{x} \in \Sigma^{*} \mid \boldsymbol{M} \text { accepts } \boldsymbol{x} \text { in at most } \boldsymbol{p}(|\boldsymbol{x}|) \text { steps }\right\}
$$

```
Input: M,x,p.
Question: Does M stops on input x after p(|x|) steps?
```

Describe a reduction $R$ that computes from $\mathbf{M , x , p}$ a SAT formula $\varphi$.
$\rightarrow \boldsymbol{R}$ takes as input a string $\boldsymbol{x}$ and outputs a SAT formula $\varphi$

- $R$ runs in time polynomial in $|x|,|M|$
> $x \in L$ if and only if $\varphi$ is satisfiable


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Input: $M, x, p$.
Question: Does $\boldsymbol{M}$ stops on input $\boldsymbol{x}$ after $\boldsymbol{p}(|\boldsymbol{x}|)$ steps?
Describe a reduction $R$ that computes from $M, x, p$ a SAT formula $\varphi$ - $\boldsymbol{R}$ takes as input a string $x$ and outputs a SAT formula $\varphi$ - $\boldsymbol{R}$ runs in time polynomial in $|\boldsymbol{x}|,|\boldsymbol{M}|$ $\Rightarrow x \in L$ if and only if $\varphi$ is satisfiable

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## The plot against SAT continued


$\varphi$ is satisfiable if and only if $\boldsymbol{x} \in \boldsymbol{L}$
$\varphi$ is satisfiable if and only if nondeterministic $M$ accepts $x$ in $p(|x|)$ steps

## BIG IDEA

$>\varphi$ will express " $M$ on input $x$ accepts in $p(|x|)$ steps'
$\rightarrow \varphi$ will encode a computation history of $M$ on $x$
$\varphi$ : CNF formula s.t if we have a satisfying assignment to it $\Rightarrow$ accepting
computation of $\boldsymbol{M}$ on $\boldsymbol{x}$ down to the last details (where the head is, what transition is chosen, what the tape contents are, at each step, etc).

## The plot against SAT continued


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## The Matrix Executions

## Tableau of Computation

$\boldsymbol{M}$ runs in time $\boldsymbol{p}(|\boldsymbol{x}|)$ on $\boldsymbol{x}$. Entire computation of $\boldsymbol{M}$ on $\boldsymbol{x}$ can be represented by a "tableau"


Row $\boldsymbol{i}$ gives contents of all cells at time $\boldsymbol{i}$
At time $\mathbf{0}$ tape has input $\boldsymbol{x}$ followed by blanks
Each row long enough to hold all cells $\boldsymbol{M}$ might ever have scanned.

## Variables of $\varphi$

Four types of variables to describe computation of $\boldsymbol{M}$ on $\boldsymbol{x}$

- $\boldsymbol{T}(\boldsymbol{b}, \boldsymbol{h}, \boldsymbol{i})$ : tape cell at position $\boldsymbol{h}$ holds symbol $\boldsymbol{b}$ at time $\boldsymbol{i}$.

For $h=1, \ldots, p(|x|), b \in \Gamma, i=0, \ldots, p(|x|)$.

- $\boldsymbol{H}(\boldsymbol{h}, \boldsymbol{i}):$ read/write head is at position $\boldsymbol{h}$ at time $\boldsymbol{i}$.

Fir $\boldsymbol{h}=\mathbf{1}, \ldots, \boldsymbol{p}(|\boldsymbol{x}|)$, and $\boldsymbol{i}=\mathbf{0}, \ldots, \boldsymbol{p}(|\boldsymbol{x}|)$

- $\boldsymbol{S}(\boldsymbol{q}, \boldsymbol{i})$ state of $\boldsymbol{M}$ is $\boldsymbol{q}$ at time $\boldsymbol{i}$.

For all $\boldsymbol{q} \in \boldsymbol{Q}$ and $\boldsymbol{i}=\mathbf{0}, \ldots, \boldsymbol{p}(|\boldsymbol{x}|)$.

- I(j,i) instruction number $\boldsymbol{j}$ is executed at time $\boldsymbol{i}$
$M$ is non-deterministic, need to specify transitions in some way. Number transitions as $\mathbf{1}, \mathbf{2}, \ldots, \boldsymbol{\ell}$ where $\boldsymbol{j}$ th transition is $<\boldsymbol{q}_{\boldsymbol{j}}, \boldsymbol{b}_{\boldsymbol{j}}, \boldsymbol{q}_{\boldsymbol{j}}^{\prime}, \boldsymbol{b}_{\boldsymbol{j}}^{\prime}, \boldsymbol{d}_{\boldsymbol{j}}>$ indication $\left(\boldsymbol{q}_{\boldsymbol{j}}^{\prime}, \boldsymbol{b}_{\boldsymbol{j}}^{\prime}, \boldsymbol{d}_{\boldsymbol{j}}\right) \in \boldsymbol{\delta}\left(\boldsymbol{q}_{\boldsymbol{j}}, \boldsymbol{b}_{\boldsymbol{j}}\right)$, direction $\boldsymbol{d}_{\boldsymbol{j}} \in\{-\mathbf{1}, \mathbf{0}, \mathbf{1}\}$.
Number of variables is $\boldsymbol{O}\left(\boldsymbol{p}(|x|)^{2}|M|^{2}\right)$


## Notation

Some abbreviations for ease of notation $\bigwedge_{k=1}^{m} x_{k}$ means $x_{1} \wedge x_{2} \wedge \ldots \wedge x_{m}$
$\bigvee_{k=1}^{m} x_{k}$ means $x_{1} \vee x_{2} \vee \ldots \vee x_{m}$
$\oplus\left(x_{1}, x_{2}, \ldots, x_{k}\right)$ is a formula that means exactly one of $x_{1}, x_{2}, \ldots, x_{m}$ is true. Can be converted to CNF form

CNF formula showing making sure that at most one variable is assigned value $\mathbf{1}$


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$$

## Clauses of $\varphi$

$\varphi$ is the conjunction of $\mathbf{8}$ clause groups:

$$
\varphi=\bigwedge_{i=1}^{12} \varphi_{i}
$$

where each $\varphi_{i}$ is a CNF formula. Described in subsequent slides.
Property: $\varphi$ is satisfied $\Longleftrightarrow$ there is an execution of $M$ on $\boldsymbol{x}$ that accepts the language in $\boldsymbol{p}(|\boldsymbol{x}|)$ time.

## THE END

(for now)

