Optimal Prediction of the Number of Unseen Species

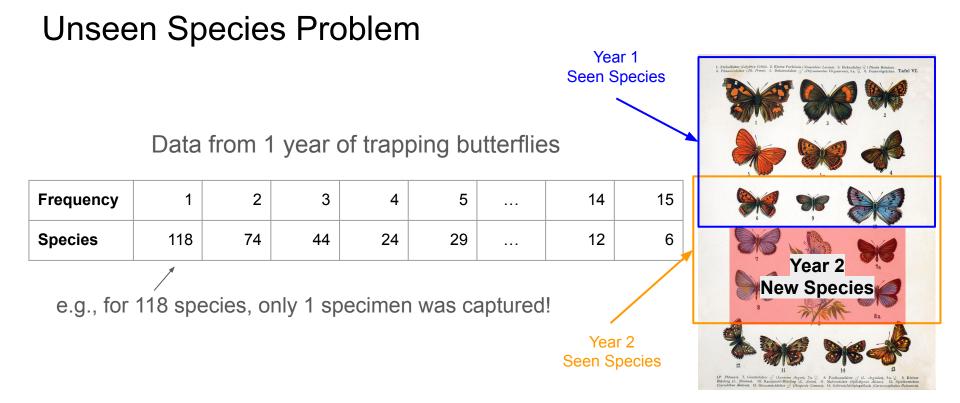
Orlitsky, Alon, Ananda Theertha Suresh, and Yihong Wu. "Optimal prediction of the number of unseen species." *Proceedings of the National Academy of Sciences* 113.47 (2016): 13283-13288.

Presenter: Jason Vega Wednesday, December 11, 2024

Overview

- 1. Background
- 2. Proposed Estimator
- 3. Theory

Background



Problem: How many **new species** from **another year** of trapping?

Unseen Species Problem

Year 1: *n* i.i.d. samples $X^n = (X_1, X_2, ..., X_n)$ Year 2: *m* i.i.d. samples $X_{n+1}^{n+m} = (X_{n+1}, X_{n+2}, ..., X_{n+m})$

> Year 1 unique species: $\{X^n\}$ Year 2 unique species: $\{X_{n+1}^{n+m}\}$

Year 2 new species: $U = |\{X_{n+1}^{n+m}\} \setminus \{X^n\}|$

Prior Work: Good-Toulmin Estimator

Φ_i: # of species w/ freq. *i* (**"prevalence of i"**)

Frequency	1	2	3	4	5	 14	15
Species	118	74	44	24	29	 12	6
	Φ	Φ	Φ	Φ	Φ	Φ ₁	4 Φ ₁

Let **t** = **m/n** (yr. 2 to yr 1. sample size ratio)

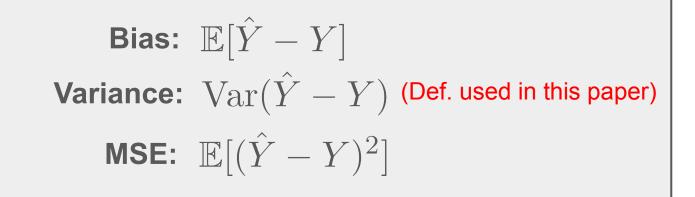
Good-Toulmin Estimator:
$$U^{\mathrm{GT}} = -\sum_{i=1}^{\infty} (-t)^i \Phi_i$$

e.g., for table data w/ t=1, U^{GT} = 118 - 74 + 44 - 24 + ... - 12 + 6 = 75

Background: Bias, Variance and MSE

Given sample X, want to estimate some quantity Y.

Estimator: $\hat{Y} = f(X)$

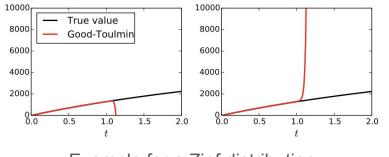


Note that Variance ≤ MSE

Ideally: low bias and variance!

Good-Toulmin Performance

- For $t \le 1$:
 - Bias: nearly unbiased!
 - **MSE:** O(nt²)
- For t > 1: high variance!



Example for a Zipf distribution

$$\begin{split} U^{\text{GT}} &= -\sum_{i=1}^{\infty} (-t)^{i} \Phi_{i} \\ \text{For t > 1, |(-t)^{i}| explodes as i grows!} \\ \text{As t} &\to \infty, U^{\text{GT}} \text{ dominated by } (-t)^{i} \Phi_{i} \text{ for } \\ \text{largest i s.t. } \Phi_{i} > 0 \end{split}$$

Problem: How to reduce variance for t > 1?

Prior Work: Efron-Thisted Estimator

Intuition: Counteract exploding (-t)ⁱ with something that *decays* with i!

Efron-Thisted Estimator:
$$U^{\text{ET}} = -\sum_{i=1}^{n} (-t)^{i} \mathbb{P}(\text{Bin}(k, \frac{1}{1+t}) \ge i) \Phi_{i}$$

Tail probability of Binomial distribution

- Derived by truncating Euler transform of U^{GT} after k terms... complicated!
 Later: U^{ET} derived easily through a probabilistic interpretation!
- **Performance:** Good empirical performance!
- **Problem:** No theoretical guarantees... (until Orlitsky et al., 2016!)

Proposed Estimator

Initial Attempt: Truncated Good-Toulmin Estimator

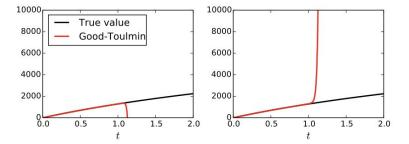
- What if we did something even simpler than U^{ET}?
- Idea: Since high variance due to $(-t)^i \Phi_i$ for large i, truncate U^{GT} after ℓ terms

Truncated Good-Toulmin Estimator: $U^{\ell} = -\sum_{i=1}^{\infty} (-t)^i \Phi_i$

• **Problem:** for t > 1, in the <u>worst case</u>, bias is still large! (will show later)

Smoothed Good-Toulmin Estimator

• U^{ℓ} may have positive or negative bias, depending on sign of dominant $(-t)^{i}\Phi_{i}$:



• Idea: Average over many U^{*l*} so that biases "cancel" out!

Smoothed Good-Toulmin Estimator:
$$U^L = \mathbb{E}_L \left[-\sum_{i=1}^L (-t)^i \Phi_i \right]$$

The smoothing distribution of L can control the MSE behavior!

Probabilistic Interpretation of Efron-Thisted

Smoothed Good-Toulmin:

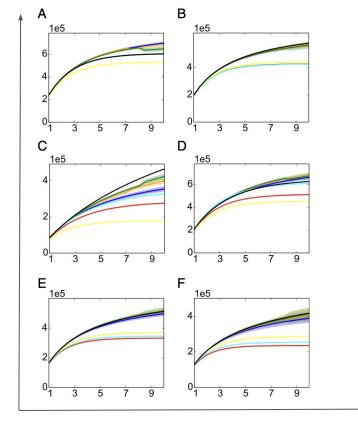
$$U^{L} = \mathbb{E}_{L} \left[-\sum_{i=1}^{L} (-t)^{i} \Phi_{i} \right]$$
$$= \mathbb{E}_{L} \left[-\sum_{i=1}^{\infty} (-t)^{i} \Phi_{i} \mathbb{I}\{i \leq L\} \right]$$
$$= -\sum_{i=1}^{\infty} (-t)^{i} \Phi_{i} \mathbb{E}_{L}[\mathbb{I}\{i \leq L\}]$$
$$= -\sum_{i=1}^{\infty} (-t)^{i} \Phi_{i} \mathbb{P}(L \geq i)$$

Efron-Thisted: $U^{\text{ET}} = -\sum_{i=1}^{n} (-t)^{i} \mathbb{P}(\text{Bin}(k, \frac{1}{1+t}) \ge i) \Phi_{i}$ Efron-Thisted is U^L with

$$L \sim Bin(k, \frac{1}{1+t})$$

Experimental Results (Synthetic Data)

Estimate of U

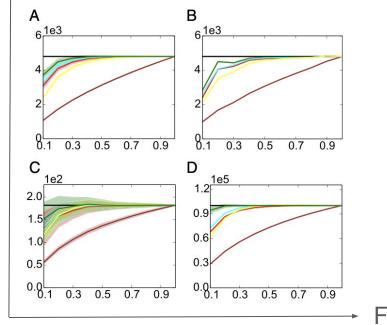


Black = True value Green = SGT Others = Other baselines

A-F denote various synthetic distributions (e.g. uniform, Zipf)

Experimental Results: Support Size Estimation (Real Data)

Estimated Support Size



Black = True value Green = SGT Others = Other baselines

A-D denote various real data distributions (e.g. Shakespearean vocabulary, last names from Census data)

Fraction of seen data

Est. Support Size = (# already seen species) + (U^E for m = # remaining data)



Evaluation Metric

Note: given n and t, U is at most m = nt

Worst-Case Normalized MSE of Estimator U^E:
$$\mathcal{E}_{n,t}(U^E) = \sup_p \mathbb{E}_p \left[\left(\frac{U^E - U}{nt} \right)^2 \right]$$

Recall that Variance ≤ MSE

Theorem 1: Performance of SGT

for $t \ge 1$ Table 1. NMSE of SGT estimators for three smoothing distributions $\mathcal{E}_{n,t}(U^{L})$ Parameters Smoothing distribution $r = \frac{1}{2t} \log_e \frac{n(t+1)^2}{t-1}$ $O(n^{-1/t})$ Poisson (r) $\mathsf{O}(n^{-\log_2(1+1/t)})$ $k = \left| \frac{1}{2} \log_2 \frac{nt^2}{t-1} \right|, \ q = \frac{1}{t+1}$ $\bigcup^{\text{ET}} \longrightarrow$ Binomial (k, q) $k = \left| \frac{1}{2} \log_3 \frac{nt^2}{t-1} \right|, q = \frac{2}{t+2}$ $O(n^{-\log_3(1+2/t)})$ Best! Binomial (k, q)

for t > 1: $-\log_3(1+2/t) \le -\log_2(1+1/t) \le -1/t$

- Principled method of selecting k for Efron-Thisted with performance guarantees
- Slight modification to q beats original U^{ET}

Theorem 2: Best-Case Performance

 $\exists c' s.t.$ for any n and any estimator U^{E} ,

$$\mathcal{E}_{n,t}(U^E) = \Omega\left(n^{-c'/t}\right)$$

Table 1. NMSE of SGT estimators for three smoothing distributions

Smoothing distribution	Parameters	$\mathcal{E}_{n,t}(U^L)$
Poisson (r)	$r = \frac{1}{2t} \log_e \frac{n(t+1)^2}{t-1}$	$O(n^{-1/t})$
Binomial (k, q)	$k = \left\lfloor \frac{1}{2} \log_2 \frac{nt^2}{t-1} \right\rfloor, \ q = \frac{1}{t+1}$	$O(n^{-\log_2(1+1/t)})$
Binomial (<i>k</i> , <i>q</i>)	$k = \left\lfloor \frac{1}{2} \log_3 \frac{nt^2}{t-1} \right\rfloor, \ q = \frac{2}{t+2}$	$O(n^{-\log_3(1+2/t)})$

SGT estimators are near-optimal!

Corollary 1: Limits of Prediction Accuracy

$$\forall \delta > 0,$$
$$\max\{t : \exists U^E \ \mathcal{E}_{n,t}(U^E) < \delta\} = \Theta\left(\frac{\log n}{\log \frac{1}{\delta}}\right)$$

At best, an estimator will be accurate for new sample sizes up to m∝n*log(n)

Corollary 1: Limits of Prediction Accuracy

Paper claims SGT achieves corollary 1 limit

Rough idea to support claim (note: some abuse of notation)

(from Theorem 1) $\mathcal{E}_{n,t}(U^L) = O(n^{-1/t}) < \delta$ $\Rightarrow \frac{1}{\delta} < n^{1/t}$ $\Rightarrow \log_n \frac{1}{\delta} < \frac{1}{t}$ $\Rightarrow \frac{\log \frac{1}{\delta}}{\log n} < \frac{1}{t}$ $\Rightarrow t < \frac{\log n}{\log \frac{1}{\delta}}$

Analysis of Linear Estimators

- All estimators shown so far are linear
- Consider an arbitrary linear estimator:

$$U^h = \sum_{i=1}^{\infty} h_i \Phi_i$$

 Note that the series h_i can form the derivatives at 0 for some function h through the Taylor expansion:

$$h(y) = \sum_{i=1}^{\infty} \frac{h_i y^i}{i!}$$
 (assuming h(0) = 0)

Analysis of Linear Estimators (Lemma 1)

• Let p_x be probability of observing species x, and let $\lambda_x = np_x$. The bias is then:

$$\mathbb{E}[U^{h} - U] = \sum_{x} e^{-\lambda_{x}} \left(h(\lambda_{x}) - (1 - e^{-t\lambda_{x}}) \right)$$

• And the variance satisfies:

$$\operatorname{Var}(U^h - U) \leq \mathbb{E}[\sum_{i=1}^{\infty} \Phi_i] \cdot \sup_{i \geq 1} h_i^2 + \mathbb{E}[U]$$
Want small derivatives at 0

 We can thus reinterpret constructing a linear estimator as function approximation of g(y) = 1-e^{-ty}

Analysis of Good-Toulmin

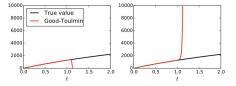
Lemma 1:

$$\mathbb{E}[U^h - U] = \sum_x e^{-\lambda_x} (h(\lambda_x) - (1 - e^{-t\lambda_x}))$$
$$\operatorname{Var}(U^h - U) \le \mathbb{E}[\sum_{i=1}^\infty \Phi_i] \cdot \sup_{i \ge 1} h_i^2 + \mathbb{E}[U]$$

• Recall Good-Toulmin estimator:

$$U^{\rm GT} = -\sum_{i=1}^{\infty} (-t)^i \Phi_i$$

- Note that its $\{h_i\}$ are the derivatives at 0 for $h(y) = 1 e^{-ty} = g(y)!$
 - For $h(y) = 1 e^{-ty}$, the ith derivative is $-(-t)^i e^{-ty}$, so the derivatives at 0 are $-(-t)^i$
- According to Lemma 1, this means that Good-Toulmin is unbiased
- However, for t > 1, $|-(-t)^i| \to \infty$ as $i \to \infty$, so the variance can **explode**!



Analysis of Truncated Good-Toulmin

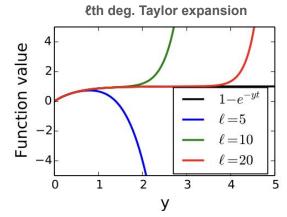
Lemma 1:

$$\mathbb{E}[U^h - U] = \sum_x e^{-\lambda_x} (h(\lambda_x) - (1 - e^{-t\lambda_x}))$$
$$\operatorname{Var}(U^h - U) \leq \mathbb{E}[\sum_{i=1}^\infty \Phi_i] \cdot \sup_{i \geq 1} h_i^2 + \mathbb{E}[U]$$

• Recall Truncated Good-Toulmin estimator:

$$U^{\ell} = -\sum_{i=1}^{\ell} (-t)^i \Phi_i$$

- Note that its {h_i} are the derivatives at 0 for the lth degree Taylor expansion of g(y)
- Now we are guaranteed **finite variance**!
- Approximation quality degrades for y far from 0 => large bias



Analysis of Smoothed Good-Toulmin

Lemma 1:

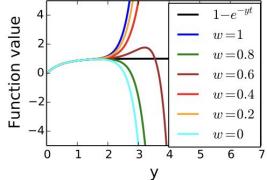
$$\mathbb{E}[U^h - U] = \sum_x e^{-\lambda_x} (h(\lambda_x) - (1 - e^{-t\lambda_x}))$$
$$\operatorname{Var}(U^h - U) \leq \mathbb{E}[\sum_{i=1}^\infty \Phi_i] \cdot \sup_{i \geq 1} h_i^2 + \mathbb{E}[U]$$

• Recall Smoothed Good-Toulmin estimator:

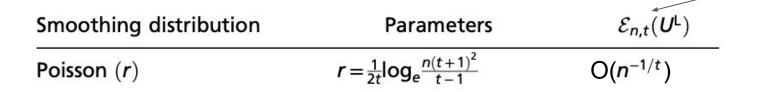
$$U^{L} = \mathbb{E}_{L}\left[-\sum_{i=1}^{L}(-t)^{i}\Phi_{i}\right]$$

- Clearly, its {h_i} are weighted averages of the derivatives at 0 for Taylor expansions of g(y) over all possible degrees
- Averaging over Taylor expansions gives overall better approximation of g(y) => bias can be reduced
- **Finite variance** possible for specific smoothing distributions

Avg. of 10th and 11th deg. Taylor expansion



Proof Sketch of Theorem 1 (Poisson)



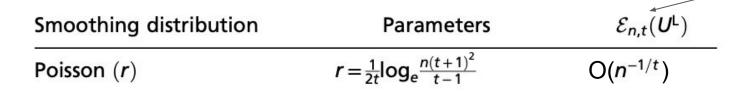
First, the following is proved (Theorem 3):

$$\mathbb{E}[(U^L - U)^2] \le \mathbb{E}\left[\sum_{i=1}^{\infty} \Phi_i\right] \mathbb{E}^2\left[t^L\right] + \left(\mathbb{E}\left[\sum_{i=1}^{\infty} \Phi_i\right] + \mathbb{E}[U]\right)^2 \xi_L(t)^2$$

where

$$\xi_L(t) = \max_{0 \le s < \infty} \left| \mathbb{E} \left[\frac{(-s)^L}{L!} \right] \right| e^{-s/t}$$

Proof Sketch of Theorem 1 (Poisson)



For Poisson distribution with parameter r,

$$\mathbb{E}[t^L] = e^{-r} \sum_{\ell=0}^{\infty} \frac{(rt)^{\ell}}{\ell!} = e^{r(t-1)}$$
$$\mathbb{E}\left[\frac{(-s)^L}{L!}\right] = e^{-r} \sum_{\ell=0}^{\infty} \frac{(-sr)^{\ell}}{(\ell!)^2} \leq e^{-r} \Longrightarrow \xi_L(t) \leq e^{-r}$$

Bessel function, which has values in [-1, 1]

Substituting into Theorem 3 and optimizing over r yields the Theorem 1 bound.

Conclusion

- **Unseen species problem:** Estimates # unseen species in future sample given past data
- Prior work:
 - Good-Toulmin estimator works well for $t \le 1$, but has large variance for t > 1
 - Efron-Thisted estimator empirically worked well for t > 1, but had no theoretical support
- Smoothed Good-Toulmin estimator proposed
 - Generalizes Efron-Thisted
 - Principled selection of parameters
 - Worst-case MSE performance guarantees
- Bias and variance of linear estimators can be analyzed via their Taylor expansions; used to show why truncated Good-Toulmin has high bias