



$$A\bar{x} = \bar{b} \in col. \text{ Space is the union of}$$

$$B \text{ Row Space : All possible vectors that can be formed by a neighted combinations of A's
$$\begin{bmatrix} r_1 & r_2 & r_3 \end{bmatrix} \begin{bmatrix} -r_1 & -r_2 \\ -r_2 & -r_3 \end{bmatrix} =$$

$$E \text{ Kample : } A = \begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} \Rightarrow r_1 =$$

$$\bar{r}_3 = \bar{r}_3 = \bar{r}_2 =$$

$$\bar{r}_3 = \bar{b}^T \in row \text{ space of } A = union \text{ of}$$

$$4 + \frac{1}{2} = \bar{b}^T \in row \text{ space of } A = union \text{ of}$$

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() How do you solve this ? - Somehow make A - Get to a form like - Ganss - Jordan : X = A b - How do you get A-1 ? A 0107 Ax = b : when is this solvable?
 b has to need to hold. A has to be ₹¥-There shouldn't be of getting to b from columns of A. ₽ • No way to · Any Ax Matrix is Mostrix is Determinant (A) 3 Rank(A) = No. of eq cr cr meanly ١f ⇒ If dependent, then $w_1 c_1 + w_2 c_2 =$ means C3 can be expressed as

Nwu space : {x̄ : } ≡ space of an N(A) Shape of mult space : $\begin{bmatrix} c_{11} & c_{12} \\ c_{21} & c_{22} \\ c_{31} & c_{32} \end{bmatrix} \begin{bmatrix} x_{4} \\ n_{2} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \qquad \begin{bmatrix} c_{11} & c_{21} & c_{31} \\ c_{12} & c_{22} & c_{32} \end{bmatrix} \begin{bmatrix} y_{1} \\ y_{2} \\ y_{3} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ $\begin{bmatrix} c_{11} & c_{22} & c_{32} \\ y_{3} \end{bmatrix} \begin{bmatrix} y_{1} \\ y_{2} \\ y_{3} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ M Observe That : $\frac{c_{11}}{G_{21}} \quad \frac{c_{21}}{G_{22}} \quad \frac{c_{31}}{G_{32}} \quad \frac{y_1}{y_1} \quad \frac{y_2}{y_2} \quad \frac{y_3}{y_1} \quad \frac{y_2}{y_2} \quad \frac{y_3}{y_3} \quad \frac{y_1}{y_2} \quad \frac{y_2}{y_3} \quad \frac{y_3}{y_1} \quad \frac{y_2}{y_2} \quad \frac{y_3}{y_3} \quad \frac{y_3}{y_1} \quad \frac{y_3}{y_2} \quad \frac{y_3}{y_1} \quad \frac{y_3}{y_2} \quad \frac{y_3}{y_1} \quad \frac{y_3}{y_2} \quad \frac{y_3}{y_3} \quad \frac{y_3}{y_1} \quad \frac{y_3}{y_2} \quad \frac{y_3}{y_2} \quad \frac{y_3}{y_1} \quad \frac{y_3}{y_2} \quad \frac{y_3}{y_1} \quad \frac{y_3}{y_2} \quad \frac{y_3}{y_2} \quad \frac{y_3}{y_1} \quad \frac{y_3}{y_2} \quad \frac{y_3}{y_1} \quad \frac{y_3}{y_2} \quad \frac{y_3}{y_1} \quad \frac{y_3}{y_2} \quad \frac{y_3}{y_2} \quad \frac{y_3}{y_1} \quad \frac{y_3}{y_2$ * N(A^T) _ and N(A) _