

Bayes' Rule :

$$\begin{aligned} P(A|B) &= \frac{P(A, B)}{P(B)} = \frac{\overset{\text{Likelihood}}{P(B|A)} \cdot \overset{\text{Prior}}{P(A)}}{P(B)} \\ &= \frac{P(B|A) \cdot P(A)}{\sum_A P(B, A)} \\ &= \frac{P(B|A) \cdot P(A)}{\sum_A P(B|A) P(A)} \end{aligned}$$

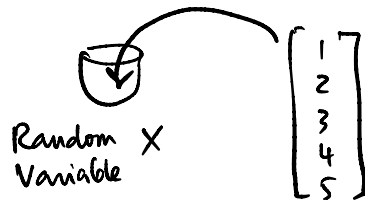
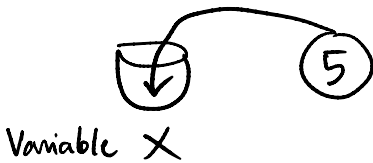
Posterior

marginalization

Chain Rule

$$\begin{aligned} P(A, B, C) &= P(A|B, C) P(B, C) \\ &= P(A|B, C) P(B|C) P(C) \end{aligned}$$

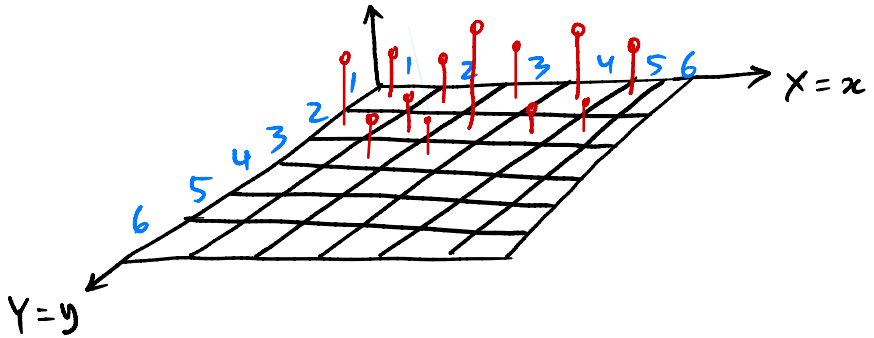
Random Variables :



$$E[X] = \mu_x = \sum_i x_i f_x(x_i)$$

$$\text{Var}(X) = E[(X - \mu_x)^2]$$

Joint Distribution



Conditional Distribution

$$P(X|Y) = \frac{P(X, Y)}{P(Y)}$$

$$P(X|Y=2) = \frac{P(X = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \end{bmatrix}, Y=2)}{P(Y=2)}$$

$$= \frac{P(X = [], Y=2)}{\sum_x P(X = [] | Y=2)}$$

■ Independence :

X and Y are independent when

$$P(X, Y) = P(X)P(Y) \quad \text{for all values of } X, Y$$

■ Variance and Covariance

$$\begin{aligned} \text{Var}(X) &= E[(X - \mu_X)^2] \\ &= E[X^2 + \mu_X^2 - 2X\mu_X] \\ &= E[X^2] + \mu_X^2 - 2\mu_X^2 \\ &= E[X^2] - 2E[X]^2 \end{aligned}$$

$$\begin{aligned} \text{Cov}(X, Y) &= E[(X - \mu_X)(Y - \mu_Y)] \\ &= E[XY - X\mu_Y - \mu_X Y + \mu_X \mu_Y] \\ &= E[XY] - E[X]\mu_Y - \mu_X E[Y] + \mu_X \mu_Y \\ &= E[XY] - E[X]E[Y] \end{aligned}$$

■ When $\text{Cov}(X, Y) = 0$

i.e., $E[XY] = E[X]E[Y]$

called

■ Correlation Coefficient = $\frac{\text{cov}(X, Y)}{\sqrt{\text{Var}(X) \text{Var}(Y)}} \in [-1, 1]$

■ Meaning of independence and correlation (or uncorrelation) in plain English?

■ Two RVs X and Y are uncorrelated.
Are they also independent?

■ Will 2 independent RVs be always uncorrelated?

■ Vector version of variance \rightarrow Covariance matrix

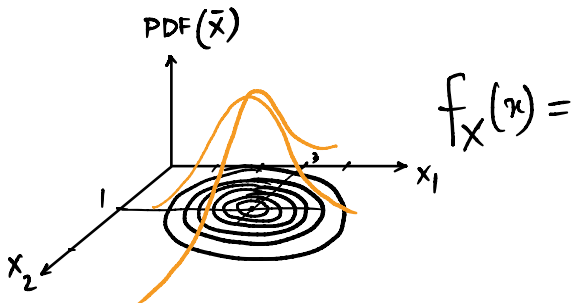
$$\text{Cov}(\bar{x}) = \text{Cov} \left(\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \right) = \text{Pairwise covariances}$$

Covariance matrix $\text{Cov}(x) =$

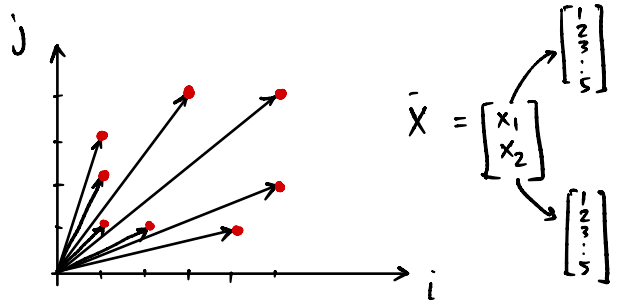
$$E[xx^T] =$$

$$\text{Cov}(\bar{x}) = \Sigma =$$

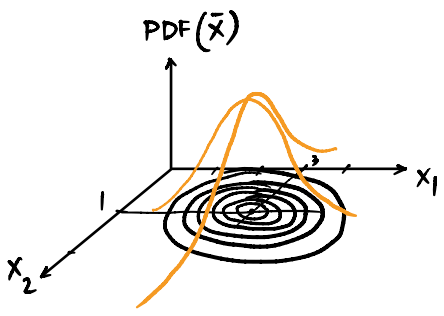
■ Visualize a 2D jointly Gaussian random variable.
where x_1 and x_2 are uncorrelated and $N(3,1)$ and $N(1,1)$



■ Interpret 2D data points as a realization of rand. vectors.



So data points have a model now → helps for analysis



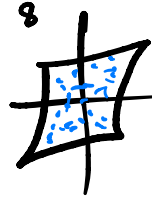
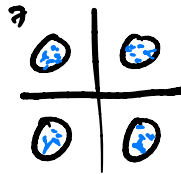
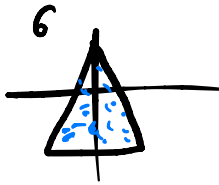
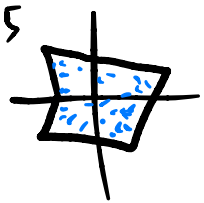
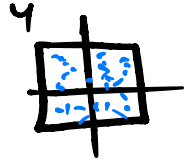
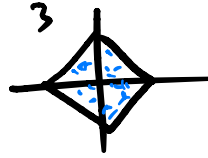
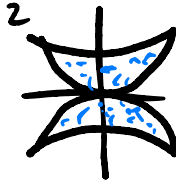
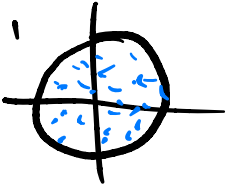
generate data
→

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Is the data uncorrelated ←

How about these data. Label them as

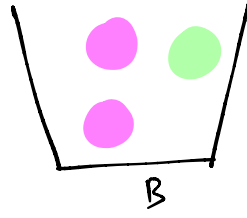
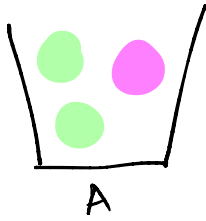
- Correlated : C
- Uncorrelated : U
- Independent : I
- Dependent : D



Application : covariance of received mic. data.

i.e., say $x = A\bar{s} + \bar{n}$

$$\text{Cov}(x) = E[xx^T]$$



$$\begin{aligned}
 P(A | \text{Red}) &= \frac{P(A, \text{Red})}{P(\text{Red})} = \frac{P(\text{Red} | A) P(A)}{P(\text{Red})} \\
 &= \frac{\frac{1}{3} \cdot \frac{1}{2}}{P(\text{Red})} = \frac{\frac{1}{6}}{P(\text{Red}, A) + P(\text{Red}, B)} \\
 &= \frac{1}{6} \cdot \frac{1}{P(\text{Red} | A) P(A) + P(\text{Red} | B) P(B)} \\
 &= \frac{1}{6} \cdot \frac{1}{\frac{1}{3} \cdot \frac{1}{2} + \frac{2}{3} \cdot \frac{1}{2}} \\
 &= \frac{1}{6} \cdot \frac{1}{\frac{1}{6} + \frac{1}{3}} = \frac{1}{6} \cdot \frac{1}{\frac{3}{6}} \\
 &= \frac{1}{6} \cdot 2 = \frac{1}{3} \quad //
 \end{aligned}$$

likelihood is self evident (given hypothesis, you know the chance of the evidence)
 $\hookrightarrow P(\text{article} | \text{CNN})$

Posterior requires you to know more about other hypothesis (given evidence, you need to understand how the evidence relates to other hypothesis)
 $\hookrightarrow P(\text{CNN} | \text{article})$

