

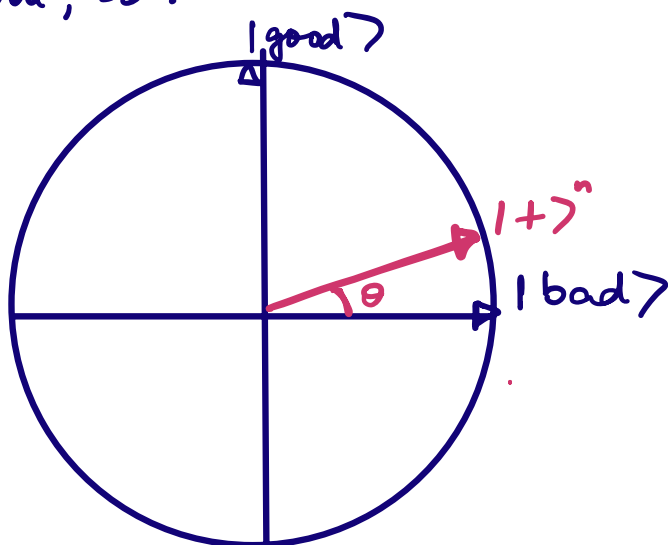
PICTORIAL REPRESENTATION OF GROVER

(Goal: Find x^* s.t. $f(x^*)=1$)

There is a "good" state: $|x^*\rangle$

and a "bad" state: $\frac{1}{\sqrt{N-1}} \sum_{x \neq x^*} |x\rangle$

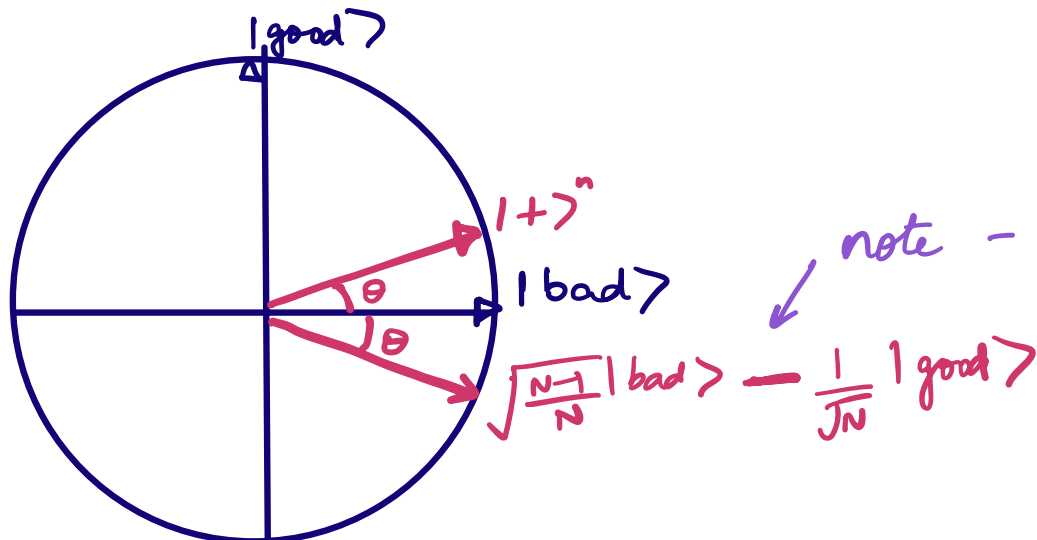
These are orthogonal, so:



1. Start with $|+\rangle = \frac{\sqrt{N-1}}{\sqrt{N}} |bad\rangle + \frac{1}{\sqrt{N}} |good\rangle$ note +

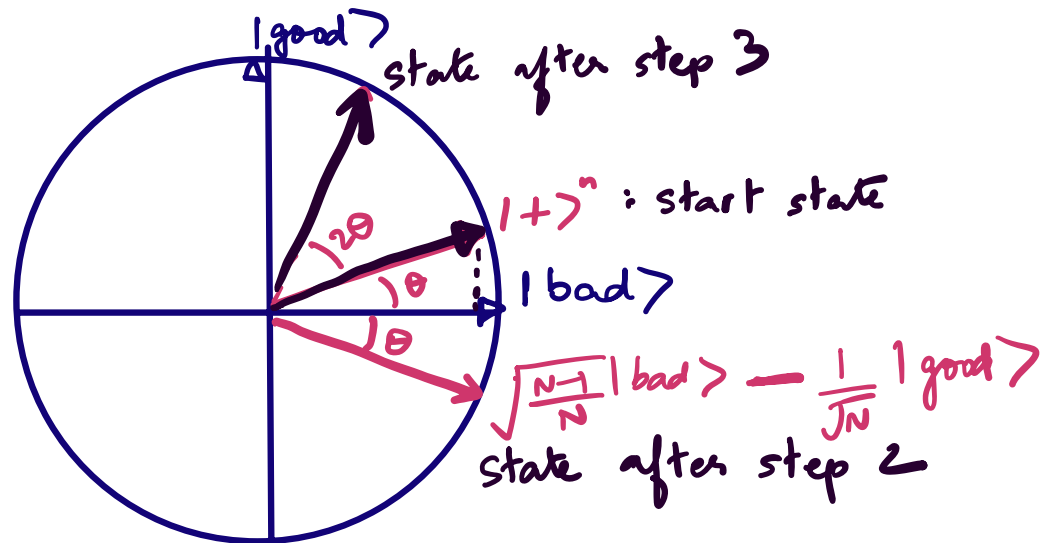
2. $D_{f\pm}(|bad\rangle) = |bad\rangle$ and $D_{f\pm}(|good\rangle) = -|good\rangle$

$D_{f\pm}$ "reflects about $|bad\rangle$ "



3. $D(|+\rangle) = |+\rangle$ and $D(|y\rangle) = -|y\rangle$
 for $|y\rangle$ orthogonal to $|+\rangle$

\mathcal{D} "reflects about $|+\rangle$ " "



4. Result:

$$\sin \theta = \frac{1}{\sqrt{N}} \sim \theta$$

Steps 2,3 rotate by $2\theta \sim \frac{2}{\sqrt{N}}$ towards $|good\rangle$

5. Repeat.

(Roughly) $O(\sqrt{N})$ iterations: $|good\rangle$

LOWER BOUNDS ON SEARCH

One of the most important problems in Computer Science: Is $P = NP$?

Equivalently, can NP-complete problems (e.g., SAT) be solved in ^{quantum} polynomial time?

BOOLEAN 3-SAT:

Is there an assignment to x_1, x_2, \dots, x_n such that:

$$(x_1 \vee x_2 \vee x_3) \wedge (\bar{x}_1 \vee x_3 \vee x_5) \dots (x_1 \vee \bar{x}_2 \vee x_n) = 1?$$

Let $x = x_1, x_2, \dots, x_n$

and define

$$f(x) := (x_1 \vee x_2 \vee x_3) \wedge (\bar{x}_1 \vee x_3 \vee x_5) \dots (x_1 \vee \bar{x}_2 \vee x_n)$$

The question above is equivalent to asking,

Is there an x^* such that $f(x^*) = 1$?

Suppose (Grover) search on arbitrary data
(i.e. not necessary that $f(x^*)=1$ for unique x^*)
took $\text{poly}(n)$ calls to $D_{f\pm}$, instead of $O(2^{n/2})$.

Then you could use it to solve 3-SAT!

More generally solve any problem in NP
polynomial time with a quantum algorithm

This would be very surprising!!!

So, can we rule out super-efficient
black-box search?
Yes! How?

Any search algorithm can be written as

$$U_T D_f U_{T-1} D_f \dots D_f U_1 |0^n\rangle$$

where $T \leq N$ is # calls to D_f ... why? (H.W.)
" 2^n

Denote by $|\Phi_t\rangle$ the state

$$U_{t-1} \circ_f U_{t-2} \dots \circ_f U_1 |0^n\rangle$$

when f is the zero function.

$$\text{Let } |\Phi_t\rangle = \sum_{x \in \{0,1\}^n} \alpha_{xt} |x\rangle$$

$$\text{Note that: } \sum_{x \in \{0,1\}^n} (\alpha_{xt})^2 = 1$$

$$\Rightarrow \sum_{t \in [T]} \sum_{x \in \{0,1\}^n} (\alpha_{xt})^2 = T$$

$$\Rightarrow \exists x^* \text{ such that } \sum_{t \in [T]} (\alpha_{x^*t})^2 \leq \frac{T}{N}$$

(Pigeonhole Principle)

Now consider two possibilities for f .

- ① f is the zero function (i.e. $f(x) = 0 \forall x$)
- ② f is zero everywhere except on x^* .

Any search algorithm should distinguish
 ① from ②.

Let $|\tilde{\Phi}_t\rangle$ denote

$$U_{t-1} \tilde{O}_f U_{t-2} \dots \tilde{O}_f U_1 |0^n\rangle$$

Distinguishing ① from ② is same as

distinguishing $|\tilde{\Phi}_T\rangle$ from $|\Phi_T\rangle$.

$$\| |\Phi_T\rangle - |\tilde{\Phi}_T\rangle \|$$

$$= \| U_T O_f U_{T-1} O_f \dots U_1 |0^n\rangle - U_T \tilde{O}_f U_{T-1} \tilde{O}_f \dots U_1 |0^n\rangle \|$$

$$\text{let } |\Psi_T\rangle_i = U_T O_f U_{T-1} O_f \dots O_f U_i \tilde{O}_f \dots \tilde{O}_f U_1 |0^n\rangle$$

$$|\Phi_T\rangle = |\Psi_T\rangle_i \quad \text{and} \quad |\tilde{\Phi}_T\rangle = |\Psi_T\rangle_T$$

$$\text{Then, } 1 = \|\ |\phi_T\rangle - |\tilde{\phi}_T\rangle \|$$

$$= \|\ |\psi_T\rangle_1 - |\psi_T\rangle_T \|$$

$$= \|\ |\psi_T\rangle_1 - |\psi_T\rangle_2 + |\psi_T\rangle_2 - |\psi_T\rangle_3 \dots - |\psi_T\rangle_T \|$$

$$\leq \underbrace{\|\ |\psi_T\rangle_1 - |\psi_T\rangle_2 \|}_{E_1} + \underbrace{\|\ |\psi_T\rangle_2 - |\psi_T\rangle_3 \|}_{E_2} \dots$$

$$\|E_1\| + \|E_2\| \dots + \|E_T\| \text{ and } \|E_i\|^2 = 4 \alpha_{xi}^2$$

↳ (why?)

$$\leq \sqrt{\sum_{i \in [T]} \|E_i\|^2} \cdot \sqrt{\sum_{i \in [T]} 1^2} \quad (\text{Cauchy-Schwarz})$$

$$\leq \sqrt{4 \sum_{i \in [T]} \alpha_{xi}^2} \sqrt{T} = \sqrt{4 \frac{T^2}{N}} = \frac{2T}{\sqrt{N}}$$

$$\Rightarrow T = O(\sqrt{N}).$$