

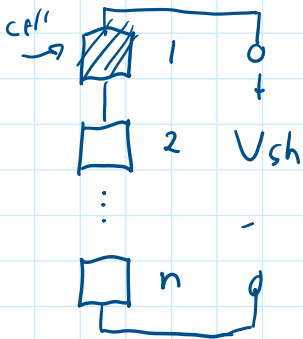
Home work is assigned today - Last HW!

Bypass + Blocking diodes (9.9.2)

Maximum Power Point Trackers (MPPT) (5.9.2)

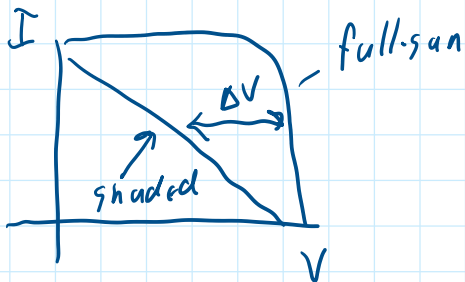
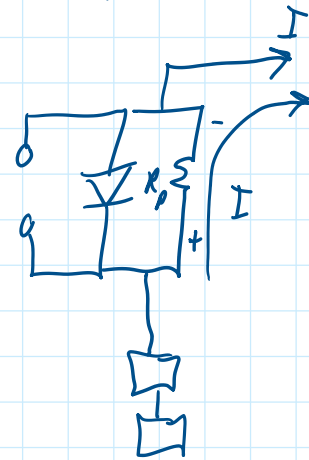
Review:

1 shaded cell



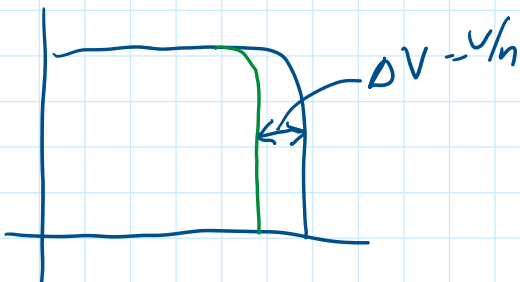
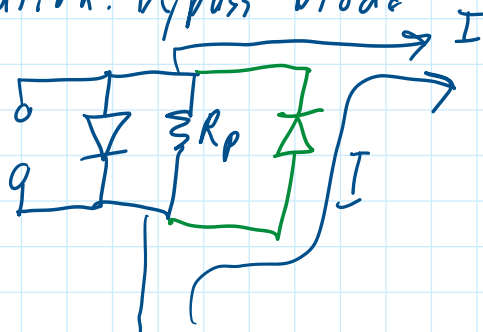
$$\Delta V = \frac{V}{n} + I R_p$$

\uparrow normal cell voltage \uparrow drop due to current in R_p

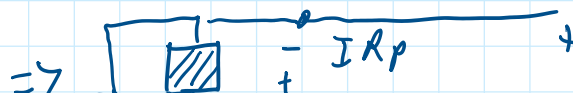
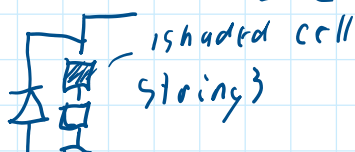


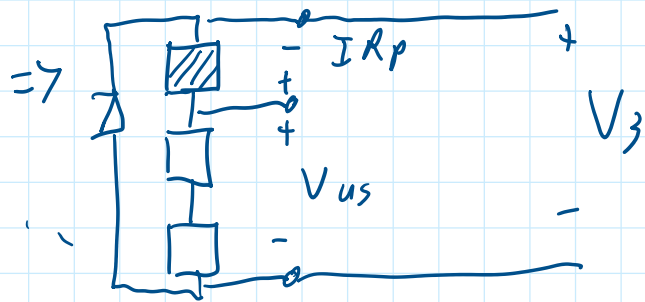
Solution: Bypass Diode

$$\Delta V = \frac{V}{n} \Rightarrow \text{no drop from } I R_p$$



However, it would be expensive to include a bypass diode for every cell \Rightarrow use one diode for multiple cells





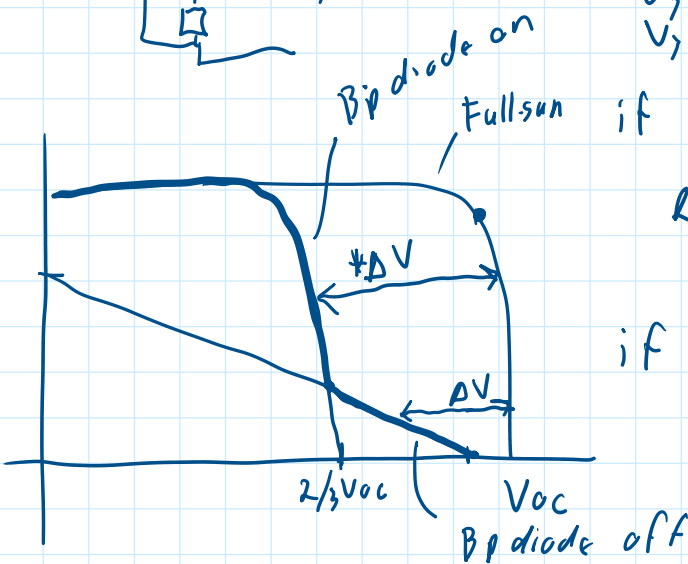
$$V_3 = V_{us} - I R_p \quad (\text{diode off}) \geq 0$$

$$V_3 = 0 \quad (\text{diode on}) \leq 0$$

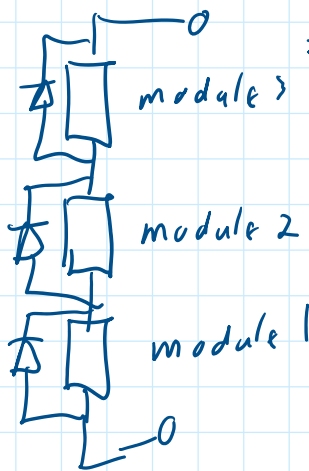
Full sun if $V_{us} > I R_p$ (diode off)

$$\Delta V_3 = \frac{V}{n} + I R_p$$

if $V_{us} < I R_p$ (diode on)
 $\Delta V = \frac{3V}{n}$ (all 3 cells bypassed)



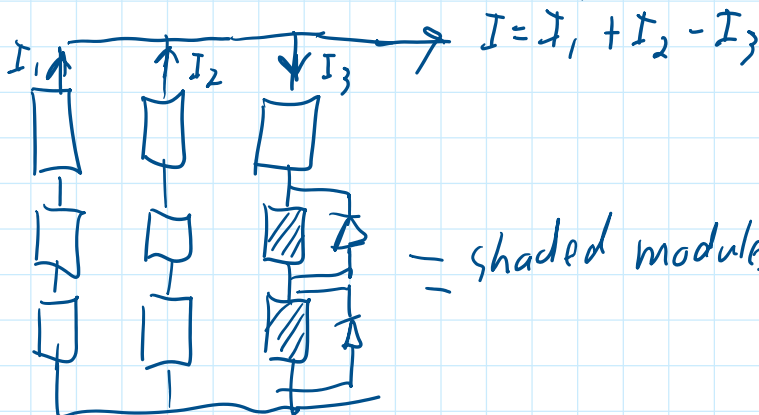
what about multiple modules in series?



=> Same idea

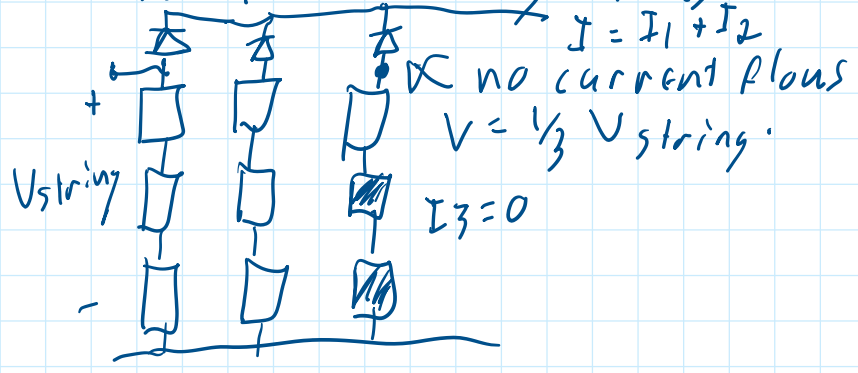
one bypass diode per module
 If a cell is shaded in a module, lose the contribution of the module, but rest are still contributing fully

what about Parallel Modules?



- Voltage of shaded as a string is $\frac{1}{3}$ of full sun strings
 => Current Flows into shaded string

Solution: blocking diodes

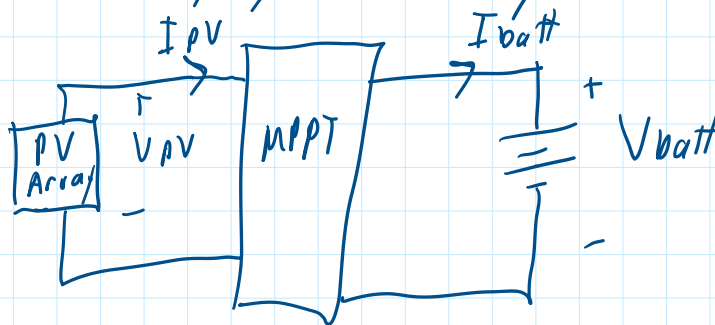


Maximum Power Point Tracking

Wednesday, April 22, 2020 10:54 AM

- ↳ want to operate PV Array at maximum power point, otherwise were wasting available power
- ↳ Not easy \Rightarrow Maximum Power Point moves around as I-V curves shift with insolation, temperature...
- ↳ We need a circuit and controller that allows us to track and operate at the MPP.
- ↳ Call this unit a Maximum Power Point Tracker (MPPT)

Ex / charging a battery



- V_{batt} is fixed
- want $V_{pv} = V_{mpp}$
- $I_{pv} = I_{mpp}$
- $P_{in} = P_{mpp} = P_{out} = V_{batt} \cdot I_{batt}$

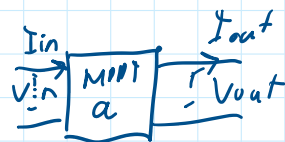
If $V_{batt} \neq V_{mpp}$, we need to convert the voltage level

\Rightarrow Assume that the MPPT acts like an ideal DC transformer with a conversion ratio "a" $\Rightarrow a = \frac{V_{out}}{V_{in}}$

note in different classes $a = M$

how does this work? \Rightarrow ^{gain} Power Electronics !!! ECE 464/469
 \rightarrow FA 2020
 \rightarrow Familiar Prof.!!!

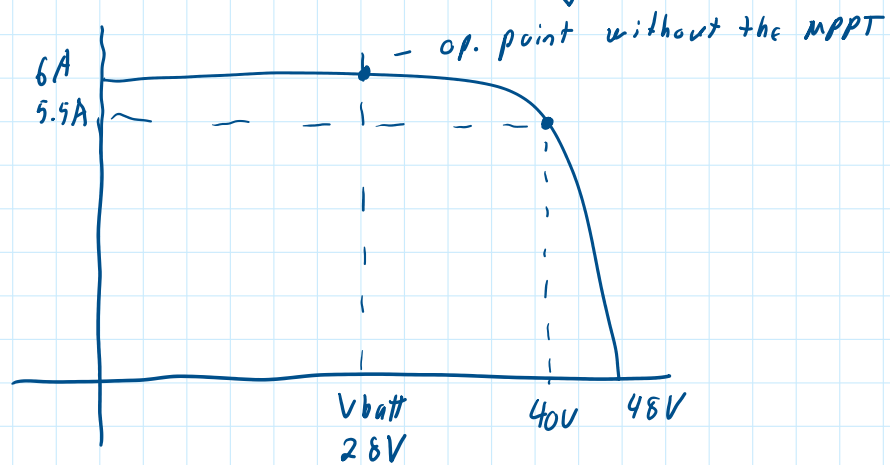
For MPPT:



$$\left. \begin{aligned} V_{out} &= aV_{in} \\ I_{in} &= aI_{out} \end{aligned} \right\} \begin{aligned} P_{in} &= P_{out} \\ V_{in} \cdot I_{in} &= V_{out} \cdot I_{out} \end{aligned}$$

Suppose:

- $V_{batt} = 28V$
- $V_{mpp} = 40V$
- $I_{mpp} = 5.5A$
- $P_{mpp} = 220W$

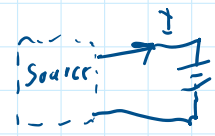
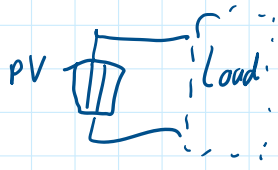
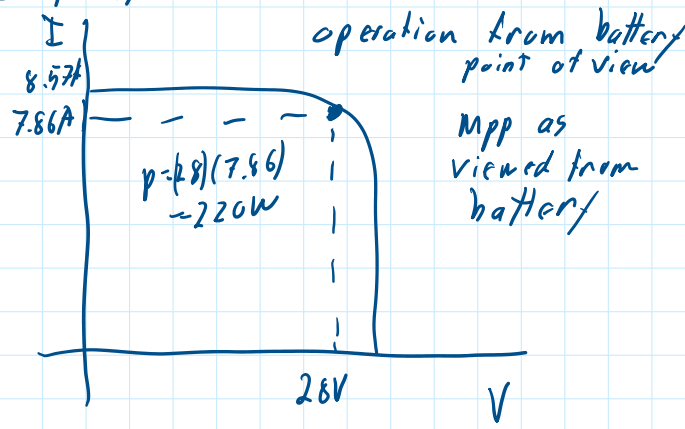
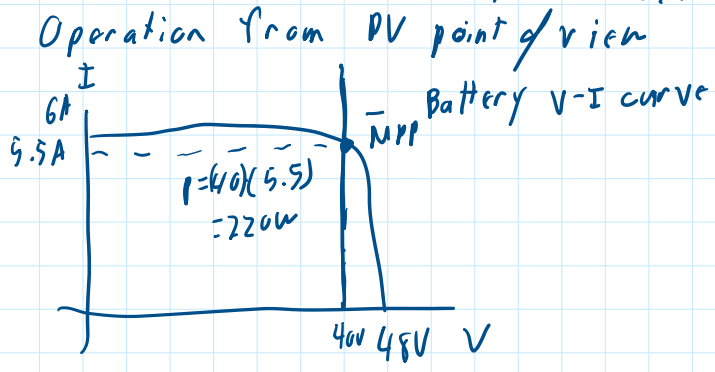


V_{batt} 40V 48V
28V

we use the MPPT to alter the battery V-I curve as the PV panel sees it so that it intersects the P-V I-V curve at the MPP

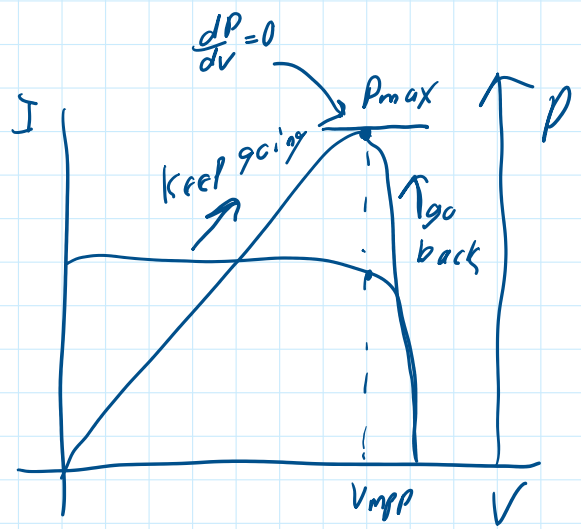
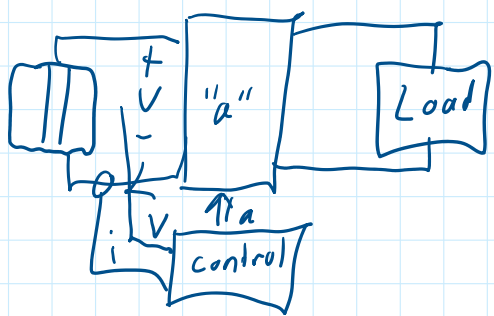
$$a = \frac{V_{out}}{V_{in}} = \frac{V_{batt}}{V_{mpp}} = \frac{28V}{40V} = 0.7$$

$$\Rightarrow I_{out} = \frac{I_{in}}{a} = \frac{I_{mpp}}{0.7} = \frac{5.5}{0.7} = 7.86A$$



MPPT Controllers

- MPPT circuit needs a way to control "a" to find the MPPT
 - ↳ there are tons of ways to do this
 - ↳ we'll look at one

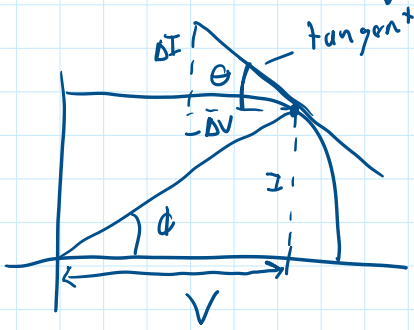


"Hill climbing" or "Perturb and Observe"
↳ converging methods

at the MPP $\frac{dP}{dV} = 0 \Rightarrow$ slope of the tangent to P-V curve

$$P = V \cdot I \Rightarrow \frac{dP}{dV} = \frac{d(VI)}{dV} = V \cdot \frac{dI}{dV} + \frac{dV}{dV} I = V \frac{dI}{dV} + I = 0$$

\Rightarrow at MPP : $\frac{I}{V} = -\frac{dI}{dV} \approx \frac{\Delta I}{\Delta V} \approx \frac{I}{V}$ MPP condition

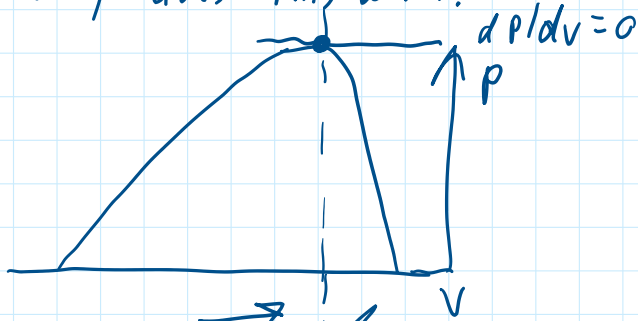


Book Fig 3.56

$\frac{I}{V} = -\frac{\Delta I}{\Delta V}$
 $\phi = \theta$

if $\phi < \theta$ decrease V
 if $\phi > \theta$ increase V

Why does this work?



$dP/dV > 0 \Rightarrow$ increase V
 $dP/dV < 0$ decrease V

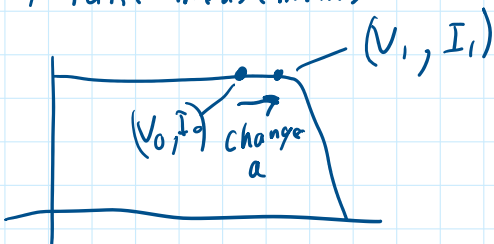
$\frac{dP}{dV} > 0 \Rightarrow$ Increase V
 $V \frac{dI}{dV} + I > 0$

$\frac{I}{V} > -\frac{dI}{dV} \approx -\frac{\Delta I}{\Delta V}$
 $\frac{I}{V} > \frac{-\Delta I}{\Delta V}$

How do we find ΔI and ΔV ?

$\phi > \theta \checkmark \Rightarrow$ increase V

\Rightarrow take measurements



$dI = I_1 - I_0$
 $dV = V_1 - V_0$ "perturb and observe"

Once we find MPP, we want to stay there
 \rightarrow check conditions often to see if state has changed